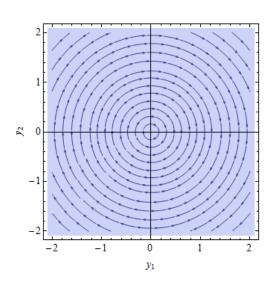
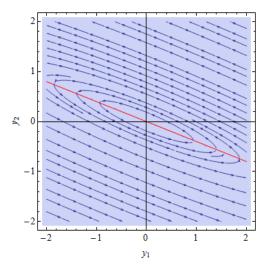
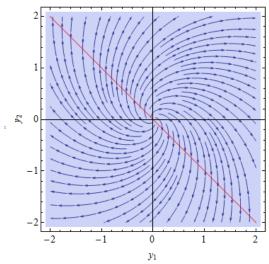
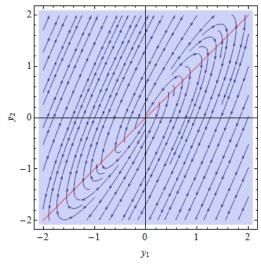
1. Centre: $\alpha=0$. Example: A= $\begin{pmatrix} -2 & -5 \\ 1 & 2 \end{pmatrix}$; $\lambda_1=i=-\lambda_2$; The red line is $x_2=-2$ $x_1/5$, where trajectories become vertical.





2. Unstable focus: $\alpha>0$. Example: $A=\begin{pmatrix} -2 & 2 \\ -5 & 4 \end{pmatrix}$; $\lambda_1=1+i$, $\lambda_2=1-i$; The red lines are $y_2=-y_1$ and $x_2=x_1$ where the trajectories become vertical.





3. Stable focus: α <0. Example: $A=\begin{pmatrix} 2 & 2 \\ -5 & 4 \end{pmatrix}$; $\lambda_1=-1+i$, $\lambda_2=-1-i$; The red lines are $y_2=y_1$ and $x_2=-x_1$ where the trajectories become vertical.

