Section A: Calculus

1. (a) Sketch the region of integration in the double integral

$$I = \int_{y=0}^{y=3} dy \int_{x=y/3}^{x=1} x e^{x^3} dx.$$

By changing the order of integration, evaluate I.

(b) The cylindrical coordinates (r, θ, z) are related to the Cartesian coordinates (x, y, z) by

$$x = r\cos\theta, \qquad y = r\sin\theta, \qquad z = z.$$

Obtain the Jacobian determinant of the transformation from Cartesian to cylindrical coordinates. Hence use cylindrical coordinates to obtain the volume of the region enclosed by the cylinder $x^2 + y^2 = 4$, the cylinder $x^2 + y^2 = 9$ and the planes z = 0 and z = 3 for y > 0.

2. (a) Find and classify the stationary points (maxima, minima and saddle points) of the function

$$f(x,y) = ax^2 + bxy + cy^2,$$

if a, b, c are all positive, real constants with $b^2 < 4ac$. How would the nature of the stationary points change if a was instead negative with b, c positive as before?

(b) Compute the Taylor's expansion of the function

$$f(x,y) = xye^{x+y}.$$

around the point (0,0) including up to second order terms. What can you conclude from the form of the expansion about the nature of the point (0,0)?

Turn over...

3. (a) Let z = f(x, y) be a real function of the two independent variables x and y which is defined implicitly by means of a constraint of the form G(x, y, z) = 0. Obtain formulae for the partial derivatives $\partial z/\partial x$ and $\partial z/\partial y$ in terms of the partial derivatives G_x, G_y, G_z . Give all the details of the derivation. Use these formulae to compute $\partial z/\partial x$ and $\partial z/\partial y$ if

$$G(x, y, z) = \sin(xyz).$$

(b) Use the method of Lagrange multipliers to find the maximum and minimum values of the function f(x, y) = 6x + y subject to the constraint $x^2 - y^2 = 1$. Compute also the corresponding values of the Lagrange multiplier.

4. Determine the functions $u_1(x)$, $u_2(x)$ such that $y(x) = c_1u_1(x) + c_2u_2(x)$ is the general solution of the following homogeneous second-order differential equation

$$y'' + 8y' + 25y = 0,$$

where c_1, c_2 are arbitrary constants. Show that the Wronskian of u_1, u_2 is nowhere zero.

Use the method of variation of parameters to find a particular solution of the inhomogeneous second-order differential equation

$$y'' + 8y' + 25y = e^{-2x}.$$

Hence determine the general solution of this inhomogeneous equation.

Turn over...

Section B: Linear Algebra

In the following questions, M(2, 2) and P_n denote the vector spaces over \mathbb{R} of all realvalued 2×2 matrices and all polynomials of degree at most n with real coefficients respectively.

- 5. (a) Determine whether the following subsets are subspaces (giving reasons for your answers).
 - i. $U = \{ \begin{pmatrix} a & b \\ c & d \end{pmatrix} \in M(2,2) \mid a+d = b+c \}$ in M(2,2)ii. $V = \{ p(x) \in P_3 \mid p(-2) = 0 \}$ in P_3 iii. $W = \{ (x_1, x_2, \dots, x_n) \in \mathbb{R}^n \mid x_1 \ge x_2 \ge \dots \ge x_n \}$ in \mathbb{R}^n
 - (b) Find a basis for the real vector space M(2,2). What is the dimension of M(2,2)?
 - (c) Do the following sets form a basis for \mathbb{R}^3 ? If not, determine whether they are linearly independent, a spanning set for \mathbb{R}^3 , or neither.
 - i. $\{(1,0,2), (1,2,0), (0,1,2), (2,2,2)\}.$
 - ii. $\{(5,0,0), (2,1,-3), (-1,4,0)\}.$
- 6. (a) Let V, W be real vector spaces. Define what it means for a map $f: V \to W$ to be linear.
 - (b) Is there a linear map $f : \mathbb{R}^2 \to M(2,2)$ satisfying $f(1,0) = \begin{pmatrix} 1 & 1 \\ 0 & 0 \end{pmatrix}$, $f(1,1) = \begin{pmatrix} 0 & 0 \\ 1 & 1 \end{pmatrix}$ and $f(2,1) = \begin{pmatrix} 1 & 2 \\ 3 & 4 \end{pmatrix}$? Justify your answer.
 - (c) Suppose $f : \mathbb{R}^2 \to M(2,2)$ is a linear map satisfying $f(1,0) = \begin{pmatrix} 1 & 1 \\ 0 & 0 \end{pmatrix}$ and $f(1,1) = \begin{pmatrix} 0 & 0 \\ 1 & 1 \end{pmatrix}$. Find f(x,y) for all $(x,y) \in \mathbb{R}^2$.
 - (d) Define what is meant by the image, the kernel, the rank and the nullity of a linear map and state carefully the Rank-Nullity theorem.
 - (e) Consider the linear map $f : \mathbb{R}^3 \to \mathbb{R}^4$ given by

$$f(x, y, z) = (x + y, y + z, x + y, y + z)$$

for all $(x, y, z) \in \mathbb{R}^3$. Determine whether f is injective, surjective, both or neither and find a basis for the kernel of f and a basis for the image of f.

- 7. (a) Define what is meant by an eigenvector and an eigenvalue for a real $n \times n$ matrix.
 - (b) State carefully the diagonalization theorem for matrices.
 - (c) Show that the matrix $A = \begin{pmatrix} -4 & 0 & -2 \\ -4 & -2 & -4 \\ 4 & 0 & 2 \end{pmatrix}$ is diagonalizable and hence find an invertible 3×3 matrix P (and P^{-1}) such that $P^{-1}AP$ is diagonal.
- 8. (a) Show that

$$\langle p(x), q(x) \rangle = \int_{-1}^{1} p(x)q(x)dx$$

for all $p(x), q(x) \in P_2$ defines a real inner product on the vector space P_2 .

- (b) Define the norm of a polynomial $p(x) \in P_2$ with respect to the above inner product. What is the norm of p(x) = x?
- (c) When do we say that two polynomials $p(x), q(x) \in P_2$ are orthogonal (with respect to the above inner product)? Are x + 1 and x^2 orthogonal?
- (d) What is an orthonormal set of polynomials in P_2 (with respect to the above inner product)? Check that

$$\{p_1(x) = \frac{1}{\sqrt{2}}, p_2(x) = \frac{\sqrt{3}}{\sqrt{2}}x\}$$

is an orthonormal set.

(e) Using the fact that $\{p_1(x), p_2(x), x^2\}$ is a basis for P_2 , find a polynomial $p_3(x)$ such that $\{p_1(x), p_2(x), p_3(x)\}$ is an orthonormal basis for P_2 .

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