

Solutions I

$$(1) \quad x_1(2 - \beta x_2) = 0 \Rightarrow x_1 = 0 \quad \text{or} \quad x_2 = 2/\beta$$

$$(2) \quad x_2(-\gamma + \delta x_1) = 0 \Rightarrow x_2 = 0 \quad \text{or} \quad x_1 = \gamma/\delta$$

$$x_1 = 0 \quad \text{in (2)} \Rightarrow x_2 = 0$$

$$x_2 = 2/\beta \quad \text{in (2)} \Rightarrow x_1 = \gamma/\delta$$

\Rightarrow 2 fixed points: $\vec{x}_F^{(1)} = (0, 0)$, $\vec{x}_F^{(2)} = (\frac{\gamma}{\delta}, \frac{2}{\beta})$

ii)

$$(1) \quad x_2 = -5$$

$$(2) \cos x_1 = 0 \Rightarrow x_1^{(n)} = (2n - 1)\frac{\pi}{2} \quad n \in \mathbb{Z} \Rightarrow \text{infinitely many f.p.} \quad \vec{x}_F^{(n)} = (2n - 1)\frac{\pi}{2}, -5$$

iii)

$$(1) \quad e^{x_1} + \lambda x_2 + \gamma x_1 - \beta = 0$$

$$(2) \quad x_1^3 = 0 \Rightarrow x_1 = 0 \quad \text{into (1)} \Rightarrow 1 - \beta + \lambda x_2 = 0$$

a) $\lambda \neq 0 \Rightarrow x_2 = \frac{\beta-1}{\lambda} \Rightarrow$ one fixed point: $\vec{x}_F = (0, \frac{\beta-1}{\lambda})$

b) $\lambda = 0, \beta = 1 \Rightarrow$ infinitely many f.p.: $\vec{x}_F = (0, x_2)$

c) $\lambda = 0, \beta \neq 1 \Rightarrow$ no fixed points

iv)

$$(1) \quad x_2(2 - x_2 - 2x_1) = 0 \Rightarrow x_2 = 0 \quad \text{into (2)} \Rightarrow x_1 = 0 \quad \text{or} \quad x_1 = 2$$

$$(2) \quad x_1(2 - x_1 - 2x_2) = 0 \Rightarrow x_1 = 0 \quad \text{into (2)} \Rightarrow x_2 = 0 \quad \text{or} \quad x_2 = 2$$

$$\text{or} \quad 2 - x_2 - 2x_1 = 0 \quad \wedge \quad 2 - x_1 - 2x_2 = 0 \Rightarrow -2 + 3x_2 = 0 \Rightarrow x_2 = \frac{2}{3}$$

$$\Rightarrow \frac{4}{3} - 2x_1 = 0 \Rightarrow x_1 = \frac{2}{3}$$

$$\Rightarrow \text{four fixed points: } \vec{x}_F^{(1)} = (0, 0), \vec{x}_F^{(2)} = (0, 2), \vec{x}_F^{(3)} = (2, 0), \vec{x}_F^{(4)} = (\frac{2}{3}, \frac{2}{3})$$

2) i)

$$A = \begin{pmatrix} 0 & 1 \\ -2 & 3 \end{pmatrix} \quad \det A_1 = 0 = \lambda^2 - 3\lambda + 2 \Rightarrow \lambda_1 = 2 \quad \text{with} \quad \vec{v}_1 = (1, 2)$$

$$\lambda_2 = 1 \quad \text{with} \quad \vec{v}_2 = (1, 1)$$

$$\Rightarrow U = (v_1, v_2) = \begin{pmatrix} 1 & 1 \\ 2 & 1 \end{pmatrix} \Rightarrow U^{-1} = -\begin{pmatrix} 1 & -1 \\ -2 & 1 \end{pmatrix}$$

$$\Rightarrow J = U^{-1}AU = \begin{pmatrix} 2 & 0 \\ 0 & 1 \end{pmatrix} = \text{unstable node}$$

recall $A = \begin{pmatrix} a & b \\ c & d \end{pmatrix}$

$$\Rightarrow A^{-1} = \frac{1}{\det A} \begin{pmatrix} d & -b \\ -c & a \end{pmatrix}$$

$$A = \begin{pmatrix} -2 & 2 \\ -2 & 3 \end{pmatrix} \quad e_1 = 2 \quad \text{with} \quad \vec{v}_1 = (1, 2) \\ e_2 = -1 \quad \text{with} \quad \vec{v}_2 = (2, 1)$$

$$\Rightarrow U = \begin{pmatrix} 1 & 2 \\ 2 & 1 \end{pmatrix} \quad U^{-1} = -\frac{1}{3} \begin{pmatrix} 1 & -2 \\ -2 & 1 \end{pmatrix} \quad \Rightarrow J = U^{-1}AU = \begin{pmatrix} 2 & 0 \\ 0 & -1 \end{pmatrix} \equiv \text{saddle point}$$

$$A = \begin{pmatrix} 1 & -1 \\ 1 & 3 \end{pmatrix} \quad e_1 = e_2 = 2 \quad \vec{v}_1 = \vec{v}_2 = (-1, 1)$$

$$\Rightarrow U = \begin{pmatrix} -1 & 1 \\ 1 & 0 \end{pmatrix} \quad U^{-1} = \begin{pmatrix} 0 & 1 \\ 1 & 1 \end{pmatrix} \quad \Rightarrow J = U^{-1}AU = \begin{pmatrix} 2 & 1 \\ 0 & 2 \end{pmatrix} \equiv \text{unstable improper node}$$

Fixed points:

$$(1) \quad x_1(12 - 3x_1, -4x_2) = 0 \quad \Rightarrow \quad x_1 = 0 \quad \text{into (2)} \Rightarrow \quad x_2 = 0 \quad \text{or} \quad x_2 = 4$$

$$(2) \quad x_2(4 - 2x_1, -x_2) = 0 \quad \Rightarrow \quad x_2 = 0 \quad \text{into (1)} \Rightarrow \quad x_1 = 0 \quad \text{or} \quad x_1 = 4$$

$$\text{or} \quad 12 - 3x_1 - 4x_2 = 0 \quad \wedge \quad 4 - 2x_1 - x_2 = 0 \quad \Rightarrow \quad -4 + 5x_1 = 0 \quad \Rightarrow \quad x_1 = \frac{4}{5} \\ \Rightarrow x_2 = \frac{12}{5}$$

\Rightarrow four fixed points:

$$\vec{x}_f^{(1)} = (0, 0) \quad \vec{x}_f^{(2)} = (0, 4) \quad \vec{x}_f^{(3)} = (4, 0) \quad \vec{x}_f^{(4)} = \left(\frac{4}{5}, \frac{12}{5}\right)$$

Linearisation:

$$A(x_1, x_2) = \begin{pmatrix} (12 - 6x_1, -4x_2) & -4x_1 \\ -2x_2 & (4 - 2x_1, -2x_2) \end{pmatrix}$$

$$A(\vec{x}_f^{(1)}) = \begin{pmatrix} 12 & 0 \\ 0 & 4 \end{pmatrix} \quad \equiv \text{unstable node} \quad \because e_1 = 12 \quad e_2 = 4 \\ \vec{v}_1 = (1, 0) \quad \vec{v}_2 = (0, 1)$$

$$A(\vec{x}_f^{(2)}) = \begin{pmatrix} -4 & 0 \\ -8 & -4 \end{pmatrix} \quad \equiv \text{stable improper node} \quad \because e_1 = e_2 = -4 \\ \vec{v}_1 = \vec{v}_2 = (0, 1)$$

$$J = U^{-1}AU = \begin{pmatrix} -4 & 1 \\ 0 & -4 \end{pmatrix} \quad \text{with} \quad U = \begin{pmatrix} 0 & -1/8 \\ 1 & 0 \end{pmatrix}$$

$$A(x_1^{(3)}) = \begin{pmatrix} -12 & -16 \\ 0 & -4 \end{pmatrix} \equiv \text{stable node} \quad \because e_1 = -12 \quad e_2 = -4$$

$$\vec{v}_1 = (1, 0) \quad \vec{v}_2 = (-2, 1)$$

$$J = U^{-1}AU = \begin{pmatrix} -12 & 0 \\ 0 & -4 \end{pmatrix} \quad \text{with } U = \begin{pmatrix} 1 & -2 \\ 0 & 1 \end{pmatrix}$$

$$A(x_1^{(4)}) = \begin{pmatrix} -\frac{12}{5} & -\frac{16}{5} \\ -\frac{24}{5} & -\frac{12}{5} \end{pmatrix} \equiv \text{saddle point} \quad \therefore e_{\pm} = -\frac{4}{5}(3 \pm 2\sqrt{6})$$

$$V_{\pm} = \left(\pm \sqrt{\frac{2}{3}}, 1 \right)$$

$$J = U^{-1}AU = \begin{pmatrix} -\frac{4}{5}(3-2\sqrt{6}) & 0 \\ 0 & -\frac{4}{5}(3+2\sqrt{6}) \end{pmatrix}$$

$$= \begin{pmatrix} 1.519\dots & 0 \\ 0 & -6.319\dots \end{pmatrix}$$

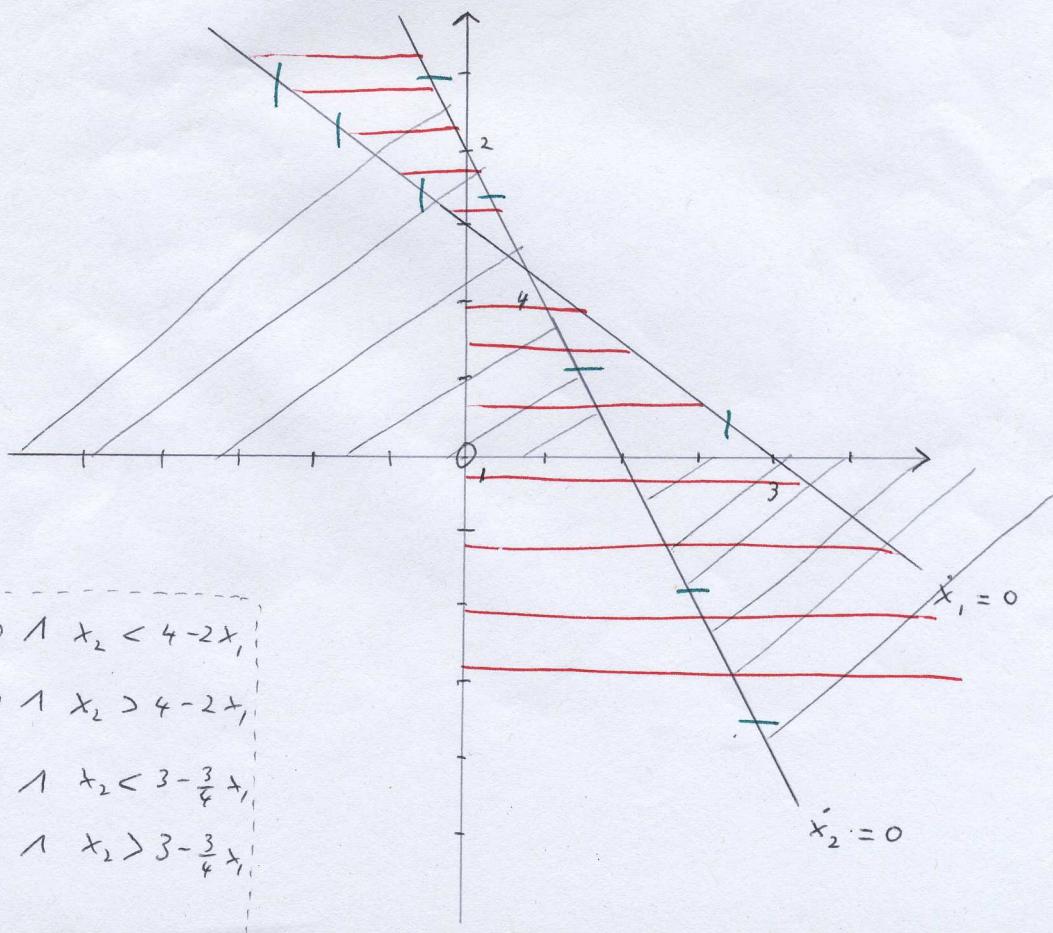
The linearisation theorem applies in all fixed points

isoclines:

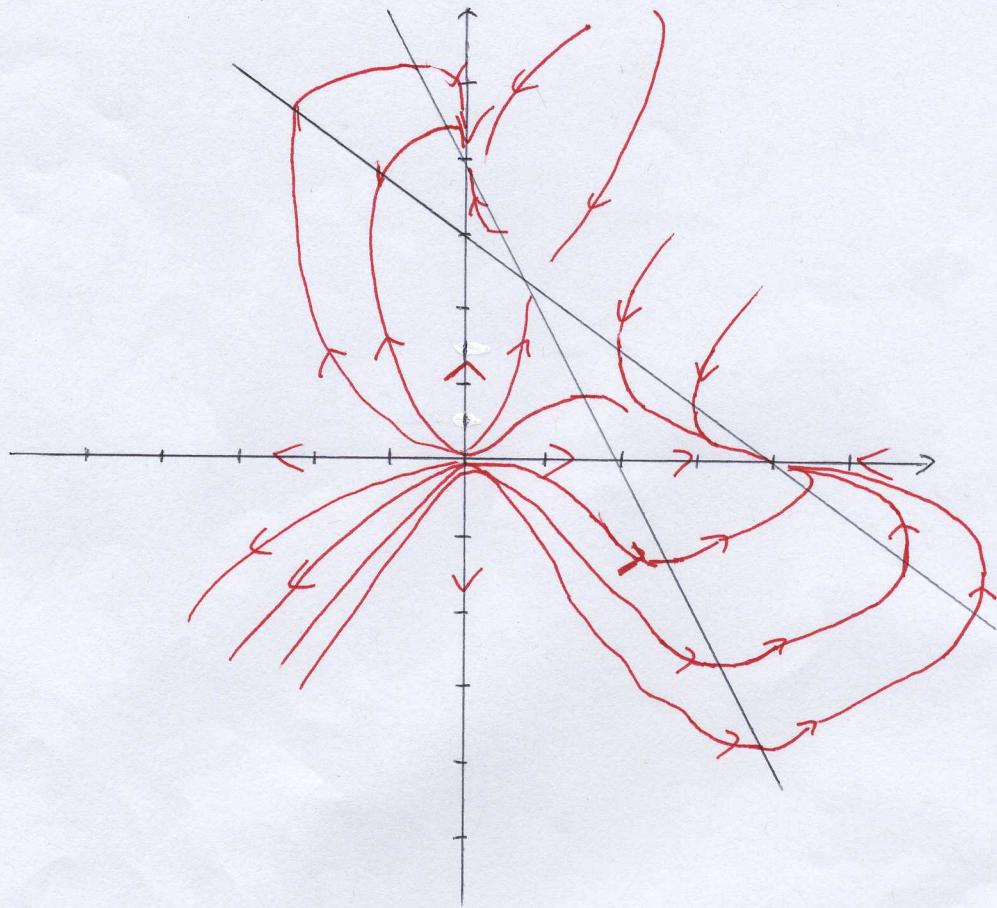
$$\frac{x_2(4-2x_1-x_2)}{x_1(12-3x_1-4x_2)} = k$$

$$k \rightarrow 0 \quad x_2 = 0 \quad \text{or} \quad 4 - 2x_1 - x_2 = 0 \quad \Rightarrow \quad x_2 = 4 - 2x_1$$

$$k \rightarrow \infty \quad x_1 = 0 \quad \text{or} \quad 12 - 3x_1 - 4x_2 = 0 \quad \Rightarrow \quad x_2 = 3 - \frac{3}{4}x_1$$



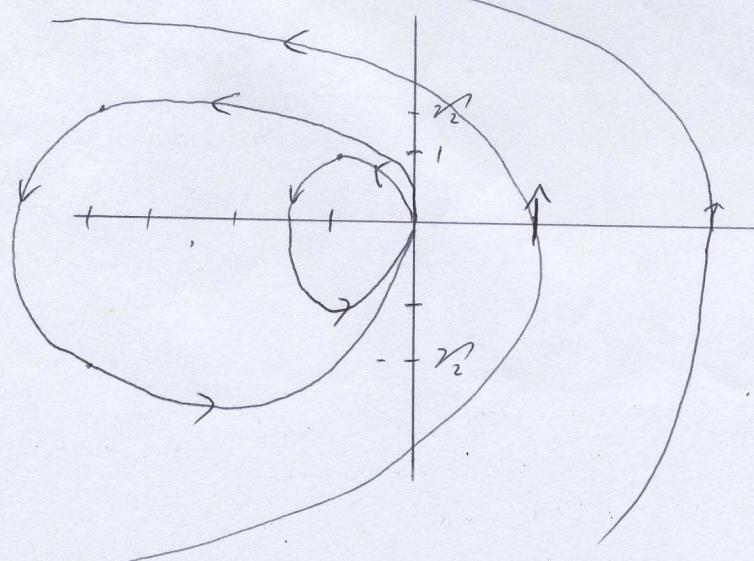
$$\begin{aligned} \dot{x}_2 > 0 \quad &x_2 > 0 \quad \text{or} \quad x_2 < 4 - 2x_1 \\ \text{or} \quad &x_2 < 0 \quad \text{or} \quad x_2 > 3 - \frac{3}{4}x_1 \\ \dot{x}_1 > 0 \quad &x_1 > 0 \quad \text{or} \quad x_1 < 3 - \frac{3}{4}x_1 \\ \text{or} \quad &x_1 < 0 \quad \text{or} \quad x_1 > 4 - 2x_1 \end{aligned}$$



(ii) fixed point: $x_f = (0, 0)$

linearisation: $A \begin{pmatrix} 0 & -7x_2^6 \\ 1 & 4x_2^3 \end{pmatrix} \Big|_{x_f} = \begin{pmatrix} 0 & 0 \\ 1 & 0 \end{pmatrix}$

$$\frac{\dot{x}_2}{\dot{x}_1} = \frac{x_1 + x_2^4}{-x_2^2} \quad \begin{cases} \rightarrow \infty & \text{for } x_2 = 0 \\ \rightarrow 0 & \text{for } x_2 = \sqrt[4]{-x_1} \end{cases}$$



$$\det A = 0$$

\Rightarrow non-singular system

\Rightarrow The linearisation

Theorem does not apply.