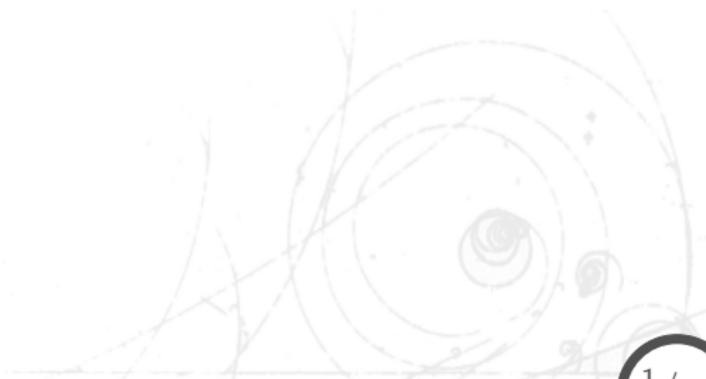


Nonlocal gauge equivalent integrable systems

Andreas Fring

Cardiff University, 14/11/2019



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- J. Cen, A. Fring, J. Phys A49 (2016) 365202; Physica D: Nonlin Phen. 397 (2019) 17; J. of Nonlin Math. Phys. 27 (2020) 17
F. Correa, A. Fring, J. High Energ. Phys. (2016) 2016: 8
J. Cen, F. Correa, A. Fring, J. Math. Phys. 58 (2017) 032901; J. Phys. A50 (2017) 435201; J. Math. Phys. 60 (2019) 081508;
[arXiv:1910.07272](https://arxiv.org/abs/1910.07272)

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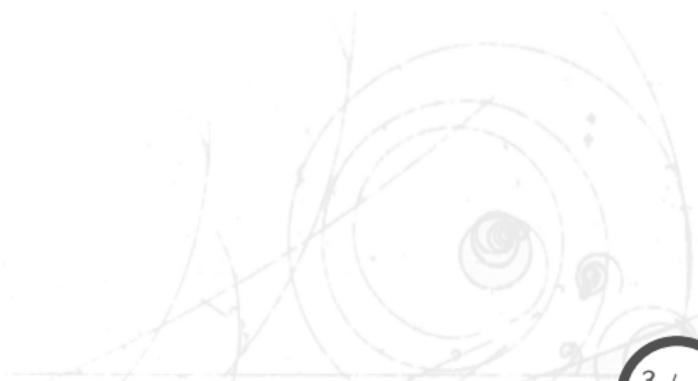
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- Conclusions and Outlook

The complex Korteweg-de Vries equation

The complex KdV equation equals two coupled real equations

$$u_t + 6uu_x + u_{xxx} = 0 \quad \Leftrightarrow \quad \begin{cases} p_t + 6pp_x + p_{xxx} - 6qq_x = 0 \\ q_t + 6(pq)_x + q_{xxx} = 0 \end{cases}$$

with $u(x, t) = p(x, t) + iq(x, t)$, $p(x, t), q(x, t) \in \mathbb{R}$



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 - for $(pq)_x \rightarrow pq_x$: complex KdV \Rightarrow Hirota-Satsuma equations
 - for $q_{xxx} \rightarrow 0$ complex KdV \Rightarrow Ito equations

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$$x \rightarrow -x, t \rightarrow -t, i \rightarrow -i, u \rightarrow u, p \rightarrow p, q \rightarrow -q$$

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Lax pair:

$$L_t = [M, L]$$

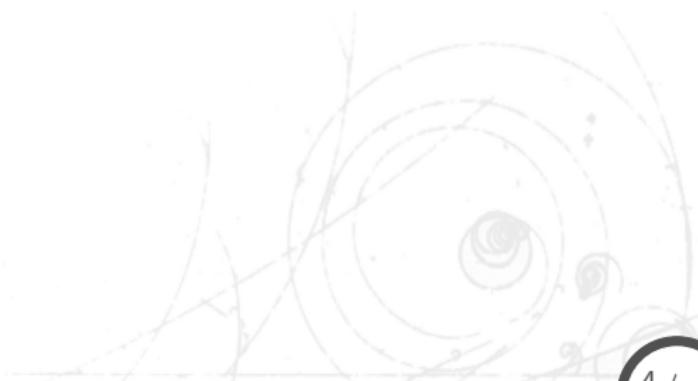
$$L = \partial_x^2 + \frac{1}{6}u \quad \text{and} \quad M = 4\partial_x^3 + u\partial_x + \frac{1}{2}u_x$$

Solutions from Hirota's direct method

Convert KdV equation into Hirota's bilinear form

$$(D_x^4 + D_x D_t) \tau \cdot \tau = 0$$

with $u = 2(\ln \tau)_{xx}$. (D_x, D_t are Hirota derivatives)



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Expanding $\tau = \sum_{k=0}^{\infty} \lambda^k \tau^k$ gives multi-soliton solutions

$$\tau_{\mu;\alpha}(x, t) = 1 + e^{\eta_{\mu;\alpha}}$$

$$\tau_{\mu,\nu;\alpha,\beta}(x, t) = 1 + e^{\eta_{\mu;\alpha}} + e^{\eta_{\nu;\beta}} + \varkappa(\alpha, \beta) e^{\eta_{\mu;\alpha} + \eta_{\nu;\beta}}$$

$$\begin{aligned} \tau_{\mu,\nu,\rho;\alpha,\beta,\gamma}(x, t) = & 1 + e^{\eta_{\mu;\alpha}} + e^{\eta_{\nu;\beta}} + e^{\eta_{\rho;\gamma}} + \varkappa(\alpha, \beta) e^{\eta_{\mu;\alpha} + \eta_{\nu;\beta}} \\ & + \varkappa(\alpha, \gamma) e^{\eta_{\mu;\alpha} + \eta_{\rho;\gamma}} + \varkappa(\beta, \gamma) e^{\eta_{\nu;\beta} + \eta_{\rho;\gamma}} \\ & + \varkappa(\alpha, \beta) \varkappa(\alpha, \gamma) \varkappa(\beta, \gamma) e^{\eta_{\mu;\alpha} + \eta_{\nu;\beta} + \eta_{\rho;\gamma}} \end{aligned}$$

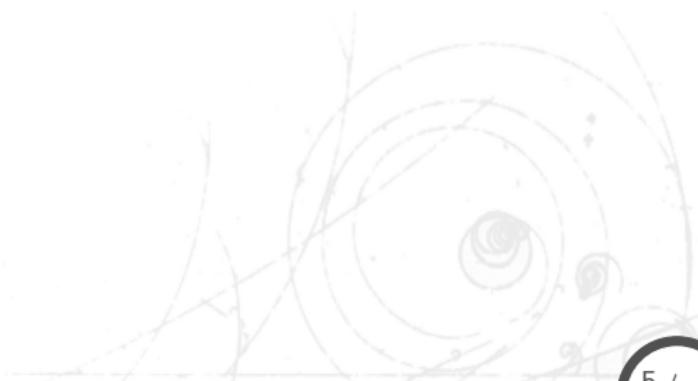
with $\eta_{\mu;\alpha} := \alpha x - \alpha^3 t + \mu$, $\varkappa(\alpha, \beta) := (\alpha - \beta)^2 / (\alpha + \beta)^2$

$\mu, \nu, \rho \in \mathbb{C}$, $\alpha, \beta, \gamma \in \mathbb{R}$

One-soliton solution

We find

$$u_{i\theta;\alpha}(x, t) = \frac{\alpha^2 + \alpha^2 \cos \theta \cosh(\alpha x - \alpha^3 t)}{[\cos \theta + \cosh(\alpha x - \alpha^3 t)]^2} - i \frac{\alpha^2 \sin \theta \sinh(\alpha x - \alpha^3 t)}{[\cos \theta + \cosh(\alpha x - \alpha^3 t)]^2}$$



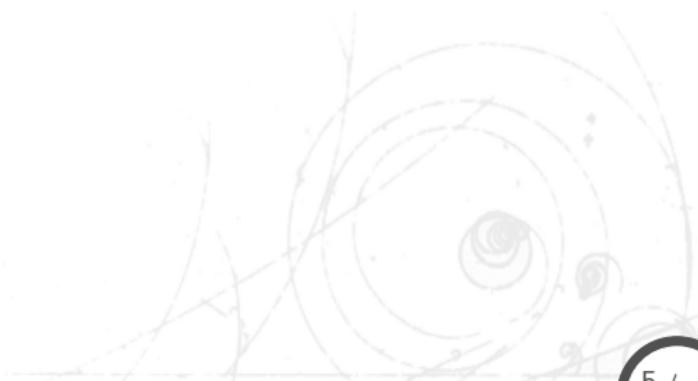
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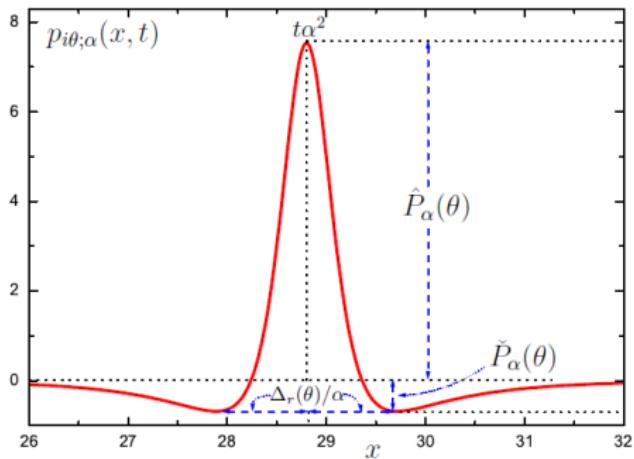
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$$\begin{aligned}\hat{P}_\alpha(\theta) &= \frac{\alpha^2}{2} \sec^2\left(\frac{\theta}{2}\right) \\ \check{P}_\alpha(\theta) &= \frac{\alpha^2}{4} \cot^2(\theta) \\ \Delta_r(\theta) &= \operatorname{arccosh}(\cos \theta - 2 \sec \theta)\end{aligned}$$

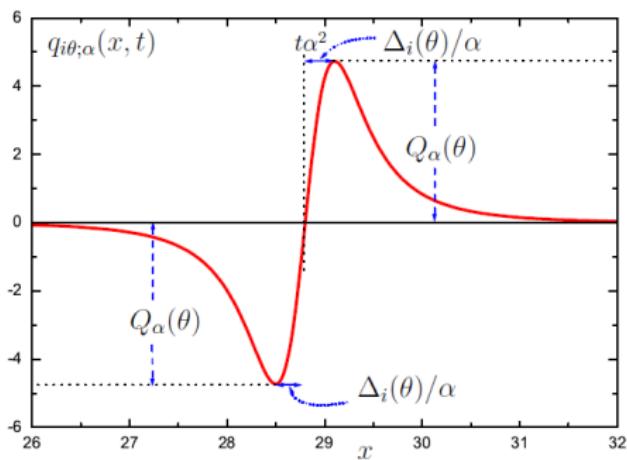
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$$Q_\alpha(\theta) = \frac{8\alpha^2 \sqrt{5 + \cos(2\theta) + \cos \theta A}}{[6 \cos \theta + A]^2 / \sin \theta}$$

$$\Delta_i(\theta) = \operatorname{arccosh} \left[\frac{1}{2} \cos \theta + \frac{1}{4} A \right]$$

$$A = \sqrt{2} \sqrt{17 + \cos(2\theta)}$$

Real charges from one-soliton solution

$$\text{Mass : } m_\alpha = \int_{-\infty}^{\infty} u_{i\theta;\alpha}(x, t) dx = 2\alpha$$

$$\text{Momentum : } p_\alpha = \int_{-\infty}^{\infty} u_{i\theta;\alpha}^2 dx = \frac{2}{3}\alpha^3$$

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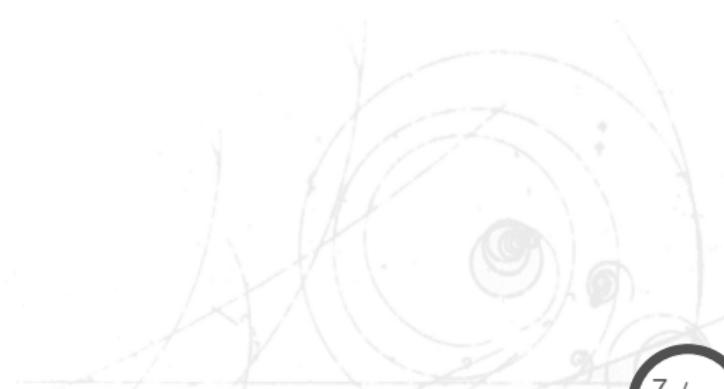
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This is not possible for N-soliton solutions with $N > 2$.



Nondegenerate two-soliton solutions

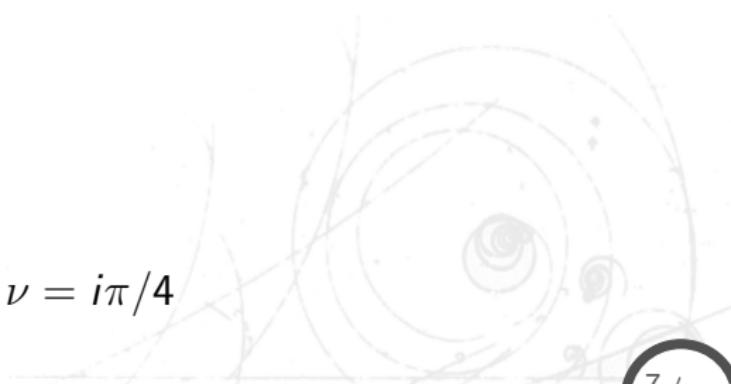
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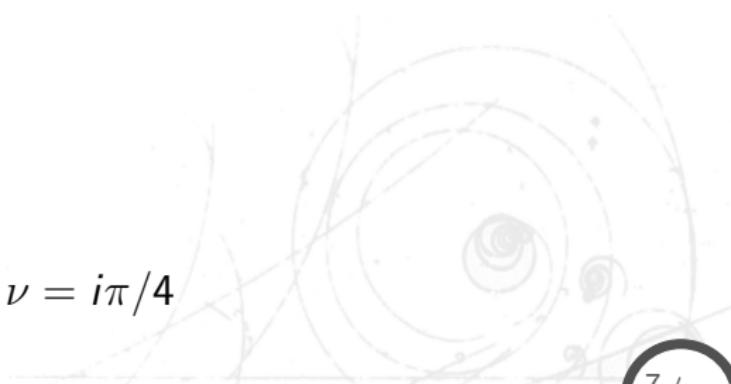
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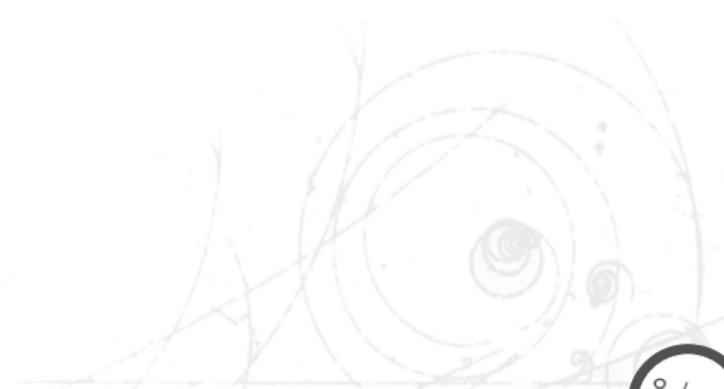
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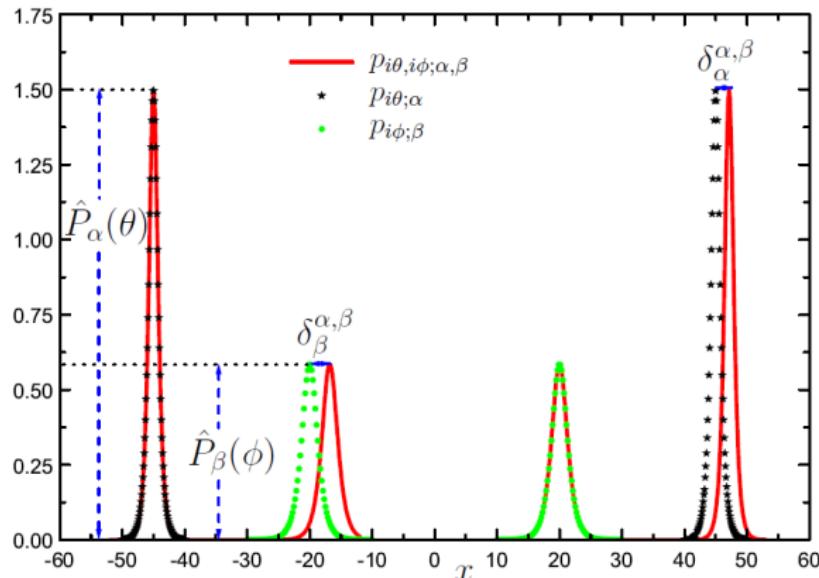
Time-delays and lateral displacements

Comparing trajectories in the asymptotic past and future



Time-delays and lateral displacements

Comparing trajectories in the asymptotic past and future



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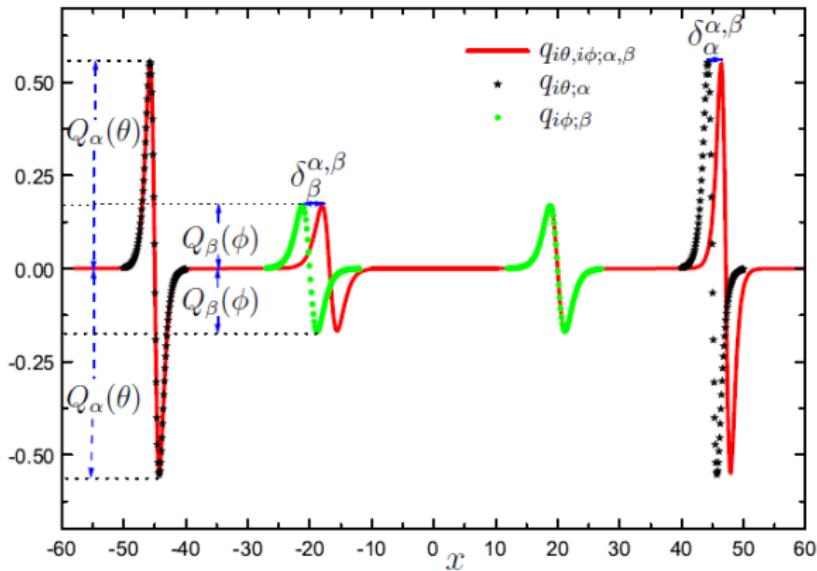
Displacements: $(\Delta_x)_\alpha = \delta_\alpha^{\alpha, \beta}$ and $(\Delta_x)_\beta = -\delta_\beta^{\alpha, \beta}$

Time-delays: $(\Delta_t)_\alpha = -\frac{1}{\alpha^2} \delta_\alpha^{\alpha, \beta}$ and $(\Delta_t)_\beta = \frac{1}{\beta^2} \delta_\beta^{\alpha, \beta}$

Consistency relations: $\sum_k m_k (\Delta_x)_k = 0$ and $\sum_k p_k (\Delta_t)_k = 0$

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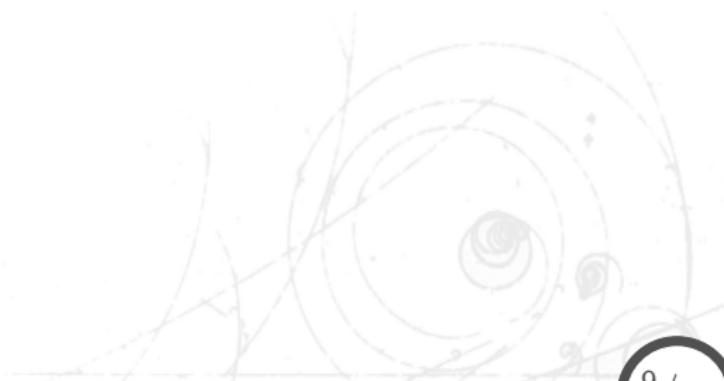
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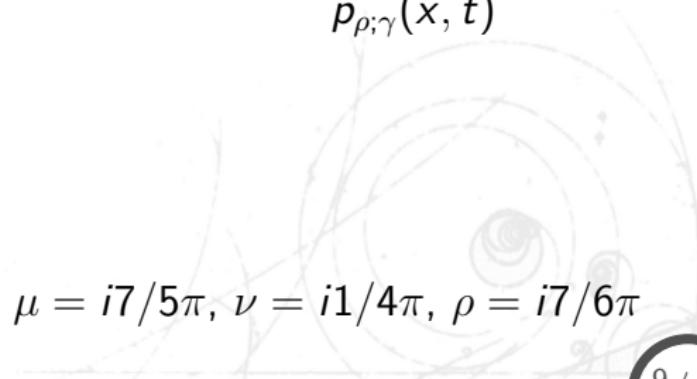
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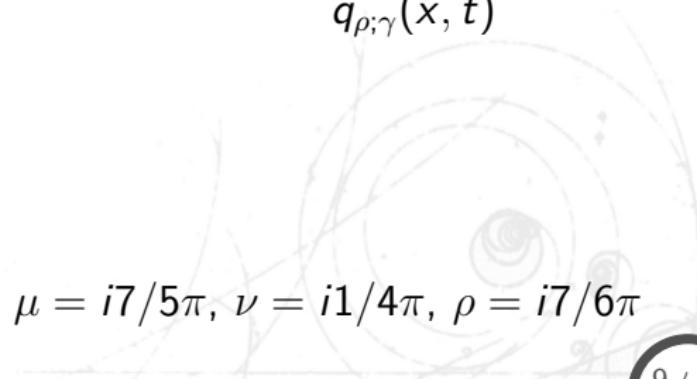
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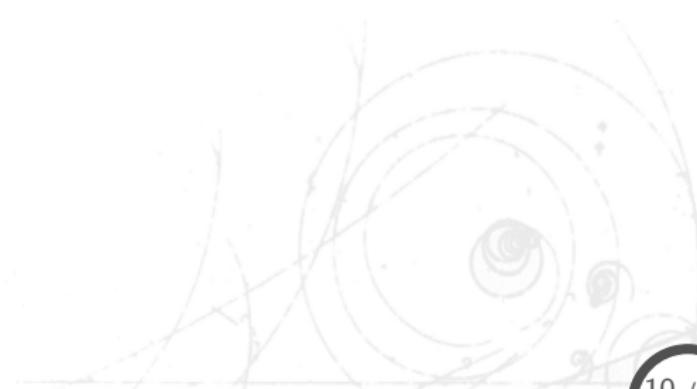

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Factorized Scattering

Displacements:

$$\begin{aligned}(\Delta_x)_\alpha &= \delta_\alpha^{\alpha,\beta} + \delta_\alpha^{\alpha,\gamma} \\(\Delta_x)_\beta &= \delta_\beta^{\beta,\gamma} - \delta_\beta^{\alpha,\beta} \\(\Delta_x)_\gamma &= -\delta_\gamma^{\alpha,\gamma} - \delta_\gamma^{\beta,\gamma}\end{aligned}$$



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Displacements:

$$\begin{aligned}(\Delta_x)_\alpha &= \delta_\alpha^{\alpha,\beta} + \delta_\alpha^{\alpha,\gamma} \\ (\Delta_x)_\beta &= \delta_\beta^{\beta,\gamma} - \delta_\beta^{\alpha,\beta} \\ (\Delta_x)_\gamma &= -\delta_\gamma^{\alpha,\gamma} - \delta_\gamma^{\beta,\gamma}\end{aligned}$$

Time-delays:

$$\begin{aligned}(\Delta_t)_\alpha &= -\frac{1}{\alpha^2} (\delta_\alpha^{\alpha,\beta} + \delta_\alpha^{\alpha,\gamma}) \\ (\Delta_t)_\beta &= \frac{1}{\beta^2} (\delta_\beta^{\alpha,\beta} - \delta_\beta^{\beta,\gamma}) \\ (\Delta_t)_\gamma &= \frac{1}{\gamma^2} (\delta_\gamma^{\alpha,\gamma} + \delta_\gamma^{\beta,\gamma})\end{aligned}$$

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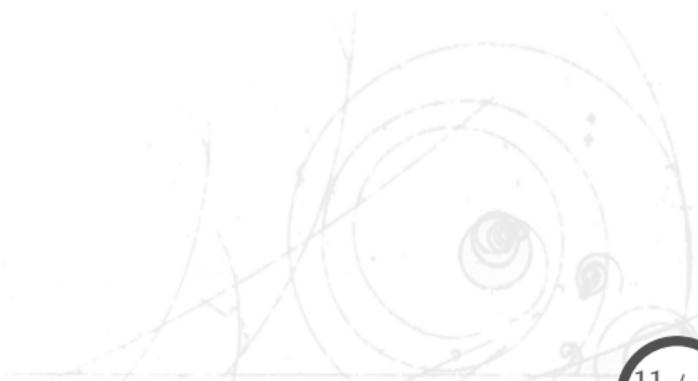
Classical factorization

This corresponds to the factorization of the quantum S-matrix described by the Yang-Baxter and bootstrap equation.

Reality of complex N-soliton charges

Asymptotically complex N-solitons factor into N one-solitons

Charges based on one-solitons solutions are real by \mathcal{PT} -symmetry



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Therefore

Reality condition

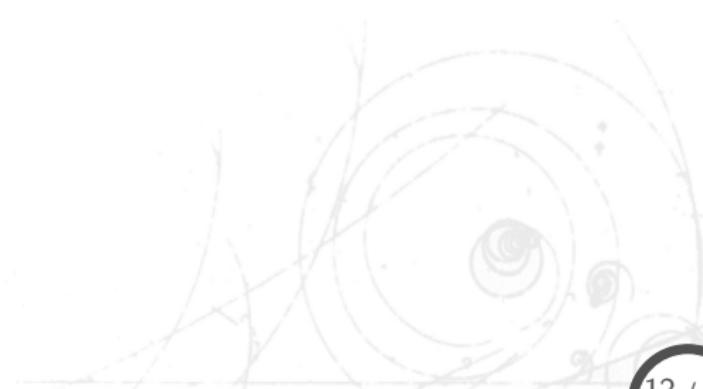
\mathcal{PT} -symmetry and integrability ensure the reality of all charges.

Regularized degenerate multi-solitons

- In general for **real** solutions:

The limit $E_\alpha \rightarrow E_\beta$ gives $\lim_{\alpha \rightarrow \beta} u_{\alpha,\beta,\gamma,\dots}(x, t) \rightarrow \infty$

The best scenario still has cusps.



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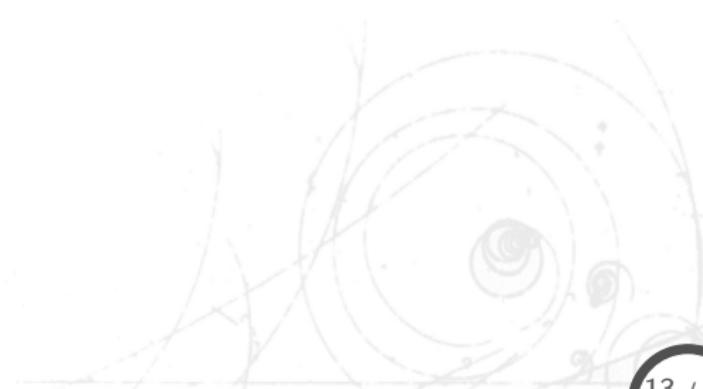
- In the **complex** case the limits become finite.

Technically we use Wronskians as τ -functions involving solutions of the Schrödinger equation and Jordan states obtained from Darboux-Crum transformations.

A link to Hirota's direct method and solutions obtained from a superpositon principle based on Bäcklund transformations is also established.

Degenerate two-soliton solutions

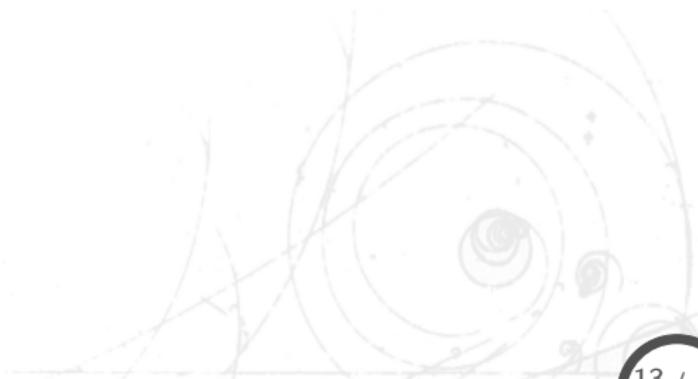
$$u_{i\theta,i\phi;\alpha,\alpha}(x,t) = \frac{2\alpha^2 \left[(\alpha x - 3\alpha^3 t + i\phi) \sinh(\eta_{i\theta;\alpha}) - 2 \cosh(\eta_{i\theta;\alpha}) - 2 \right]}{\left[\alpha x - 3\alpha^3 t + i\phi + \sinh(\eta_{i\theta;\alpha}) \right]^2}$$



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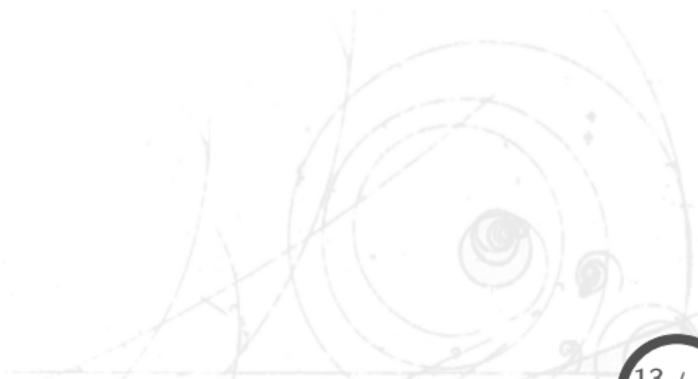
$$\alpha = 6/5, \theta = \pi/3, \phi = \pi/4$$



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$$\begin{aligned} p_{i\theta,i\phi;\alpha,\alpha}(x,t) \\ p_{i\theta;\alpha}(x,t) \end{aligned}$$

Relative displacement:

$$\Delta(t) = \frac{1}{\alpha} \ln(4\alpha^3|t|)$$

Total displacement:

$$\pm 2\Delta(t)$$

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Degenerate N-soliton solutions ($\alpha_1 = \alpha_2 = \dots \alpha_N$)

Notation:

$$\lim_{\alpha_2, \dots, \alpha_N \rightarrow \alpha_1 = \alpha} u_{i\theta_1=i\theta, \dots, i\theta_N; \alpha_1, \dots, \alpha_N} = p_{i\theta, \dots, i\theta_N; N\alpha} + iq_{i\theta, \dots, i\theta_N; N\alpha}$$

Asymptotic limits:

$$\lim_{t \rightarrow \sigma\infty} p_{i\theta, \dots, i\theta_{2n}; 2n\alpha} [t\alpha^2 + \sigma\Delta_{n,\ell,1}(t), t] = \hat{P}_\alpha \left(\theta + \frac{1 - (-1)^{n+\ell+1}}{2}\pi \right)$$

$$\lim_{t \rightarrow \sigma\infty} p_{i\theta, \dots, i\theta_{2n}; 2n\alpha} [t\alpha^2 - \sigma\Delta_{n,\ell,1}(t), t] = \hat{P}_\alpha \left(\theta + \frac{1 - (-1)^{n+\ell}}{2}\pi \right)$$

for $n = 1, 2, \dots, \ell = 1, 2, \dots, n, \sigma = \pm 1$

$$\lim_{t \rightarrow \sigma\infty} p_{i\theta, \dots, i\theta_{2n+1}; (2n+1)\alpha} [t\alpha^2 \pm \Delta_{n,\ell,0}(t), t] = \hat{P}_\alpha \left(\theta + \frac{1 - (-1)^{n+\ell}}{2}\pi \right)$$

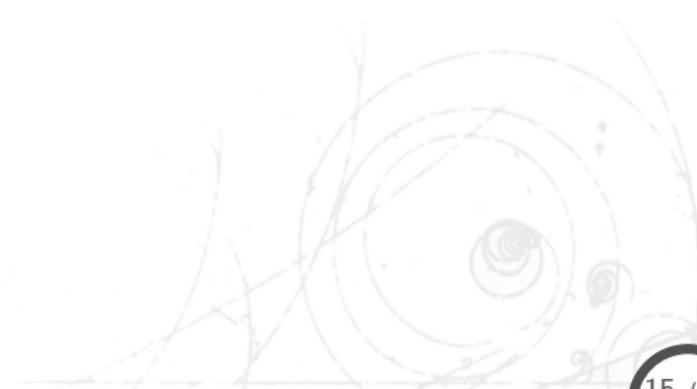
for $n = 0, 1, 2, \dots, \ell = 0, 1, 2, \dots, n$

Time-dependent displacements:

$$\Delta_{n,\ell,\kappa}(t) = \frac{1}{\alpha} \ln \left[\frac{(n-\ell)!}{(n+\ell-\kappa)!} (4|t|\alpha^3)^{2\ell-\kappa} \right]$$

Higher order nonlinear Schrödinger equation

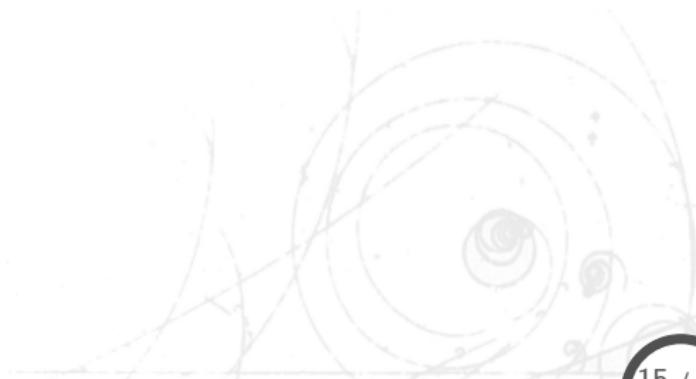
$$iq_t + \frac{1}{2}q_{xx} + |q|^2 q = 0$$



Higher order nonlinear Schrödinger equation

$$iq_t + \frac{1}{2}q_{xx} + |q|^2 q + i\varepsilon \left[\alpha q_{xxx} + \beta |q|^2 q_x + \gamma q |q|_x^2 \right] = 0$$

\mathcal{PT} -symmetry: $\mathcal{PT} : x \rightarrow -x, t \rightarrow -t, i \rightarrow -i, q \rightarrow q$



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Integrable cases:

$\varepsilon = 0 \equiv$ nonlinear Schrödinger equation (NLSE)

$\alpha : \beta : \gamma = 0 : 1 : 1 \equiv$ derivative NLSE of type I

$\alpha : \beta : \gamma = 0 : 1 : 0 \equiv$ derivative NLSE of type II

$\alpha : \beta : \gamma = 1 : 6 : 3 \equiv$ Sasa-Satsuma equation

Higher order nonlinear Schrödinger equation

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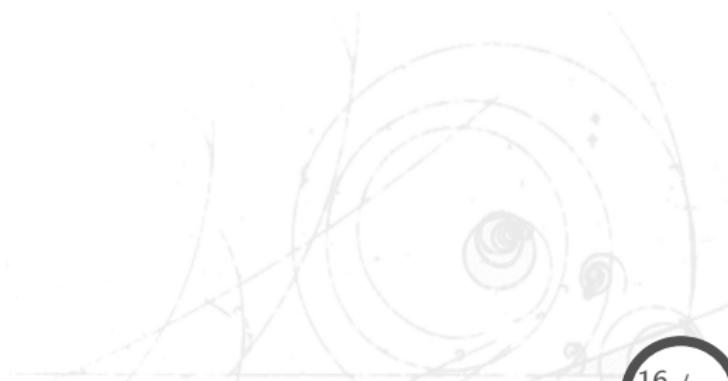
$\alpha : \beta : \gamma = 1 : 6 : 3 \equiv$ Sasa-Satsuma equation

$\alpha : \beta : \gamma = 1 : 6 : 0 \equiv$ Hirota equation

$$iq_t + \frac{1}{2}q_{xx} + |q|^2 q + i\varepsilon \left[q_{xxx} + 6 |q|^2 q_x \right] = 0$$

Zero curvature condition

$$\partial_t U - \partial_x V + [U, V] = 0$$



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$$U = \begin{pmatrix} -i\lambda & q(x, t) \\ r(x, t) & i\lambda \end{pmatrix}, \quad V = \begin{pmatrix} A(x, t) & B(x, t) \\ C(x, t) & -A(x, t) \end{pmatrix}$$

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$$C_x(x, t) = r_t(x, t) + 2r(x, t)A(x, t) + 2i\lambda C(x, t)$$

$$A(x, t) = -i\alpha qr - 2i\alpha\lambda^2 + \beta (rq_x - qr_x - 4i\lambda^3 - 2i\lambda qr)$$

$$B(x, t) = i\alpha q_x + 2\alpha\lambda q + \beta (2q^2r - q_{xx} + 2i\lambda q_x + 4\lambda^2 q)$$

$$C(x, t) = -i\alpha r_x + 2\alpha\lambda r + \beta (2qr^2 - r_{xx} - 2i\lambda r_x + 4\lambda^2 r)$$

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$$q_t - i\alpha q_{xx} + 2i\alpha q^2 r + \beta [q_{xxx} - 6qrq_x] = 0$$

$$r_t + i\alpha r_{xx} - 2i\alpha qr^2 + \beta (r_{xxx} - 6qrr_x) = 0$$

Nonlocality (Zero curvature condition)

Complex conjugate pair: $r(x, t) = \kappa q^*(x, t)$ (Hirota equation)

$$\begin{aligned} iq_t &= -\alpha \left(q_{xx} - 2\kappa |q|^2 q \right) - i\beta \left(q_{xxx} - 6\kappa |q|^2 q_x \right) \\ -iq_t^* &= -\alpha \left(q_{xx}^* - 2\kappa |q|^2 q^* \right) + i\beta \left(q_{xxx}^* - 6\kappa |q|^2 q_x^* \right) \end{aligned}$$

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\mathcal{P} conjugate pair: $r(x, t) = \kappa q^*(-x, t)$ (Nonlocal Hirota equⁿ)

$$\begin{aligned} iq_t &= -\alpha \left[q_{xx} - 2\kappa \tilde{q}^* q^2 \right] + \delta [q_{xxx} - 6\kappa q \tilde{q}^* q_x] \\ -i\tilde{q}_t^* &= -\alpha \left[\tilde{q}_{xx}^* - 2\kappa q (\tilde{q}^*)^2 \right] - \delta (\tilde{q}_{xxx}^* - 6\kappa \tilde{q}^* q \tilde{q}_x^*) \end{aligned}$$
$$\beta = i\delta, \alpha, \delta \in \mathbb{R}, q := q(x, t); \tilde{q} := q(-x, t)$$

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\mathcal{T} conjugate pair: $r(x, t) = \kappa q^*(x, -t)$

$$\begin{aligned} iq_t &= -i\hat{\delta} \left[q_{xx} - 2\kappa \hat{q}^* q^2 \right] + \delta [q_{xxx} - 6\kappa q \hat{q}^* q_x] \\ i\hat{q}_t^* &= i\hat{\delta} \left[\hat{q}_{xx}^* - 2\kappa q (\hat{q}^*)^2 \right] + \delta (\hat{q}_{xxx}^* - 6\kappa \hat{q}^* q \hat{q}_x^*) \end{aligned}$$

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\mathcal{P} transformed pair: $r(x, t) = \kappa q(-x, t)$:

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\mathcal{T} transformed pair: $r(x, t) = \kappa q(x, -t)$

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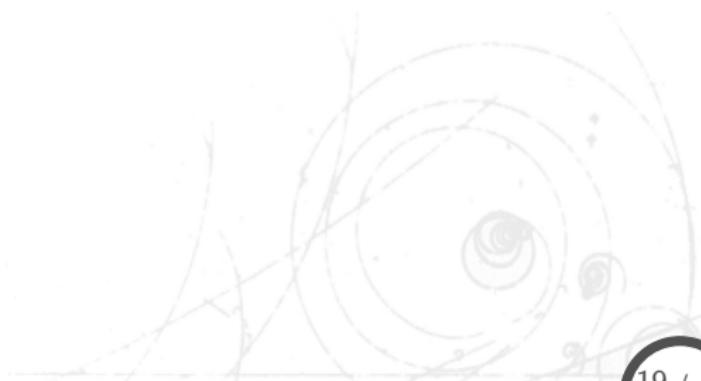
Nonlocality (Alice and Bob systems)

Korteweg-de Vries equation:

$$u_t + 6uu_x + u_{xxx} = 0$$

Take

$$u(x, t) = \frac{1}{2} [a(x, t) + b(x, t)], \mathcal{PT}a(x, t) = a(-x, -t) = b(x, t)$$



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$$b_t + 3/4(a + b)(a_x + 3b_x) + b_{xxx} = 0$$

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One -soliton solution

$$a_{\mu,\nu;\alpha}(x, t) = u_{\mu,\alpha}(x, t) + \nu \tanh \left[\frac{1}{2}(\alpha x - \alpha^3 t + \mu) \right]$$

$$b_{\mu,\nu;\alpha}(x, t) = u_{\mu,\alpha}(x, t) - \nu \tanh \left[\frac{1}{2}(\alpha x - \alpha^3 t + \mu) \right]$$

$$u_{\mu,\alpha}(x, t) = \frac{\alpha^2}{2} \operatorname{sech}^2 \left[\frac{1}{2}(\alpha x - \alpha^3 t + \mu) \right]$$

Nonlocality in Hirota's direct method

Bilinearisation of the local Hirota equation

$$\begin{aligned} f^3 \left[iq_t + \alpha q_{xx} - 2\kappa\alpha |q|^2 q + i\beta \left(q_{xxx} - 6\kappa |q|^2 q_x \right) \right] = \\ f \left[iD_t g \cdot f + \alpha D_x^2 g \cdot f + i\beta D_x^3 g \cdot f \right] + \left[3i\beta \left(\frac{g}{f} f_x - g_x \right) - \alpha g \right] \\ \times \left[D_x^2 f \cdot f + 2\kappa |g|^2 \right] \end{aligned}$$

$$D_x^n f \cdot g = \sum_{k=0}^n \binom{n}{k} (-1)^k \frac{\partial^{n-k}}{\partial x^{n-k}} f(x) \frac{\partial^k}{\partial x^k} g(x)$$

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$$\begin{aligned} f^3 \left[iq_t + \alpha q_{xx} - 2\kappa\alpha |q|^2 q + i\beta \left(q_{xxx} - 6\kappa |q|^2 q_x \right) \right] = \\ f \left[iD_t g \cdot f + \alpha D_x^2 g \cdot f + i\beta D_x^3 g \cdot f \right] + \left[3i\beta \left(\frac{g}{f} f_x - g_x \right) - \alpha g \right] \\ \times \left[D_x^2 f \cdot f + 2\kappa |g|^2 \right] \end{aligned}$$

$$D_x^n f \cdot g = \sum_{k=0}^n \binom{n}{k} (-1)^k \frac{\partial^{n-k}}{\partial x^{n-k}} f(x) \frac{\partial^k}{\partial x^k} g(x)$$

$$iD_t g \cdot f + \alpha D_x^2 g \cdot f + i\beta D_x^3 g \cdot f = 0, \quad D_x^2 f \cdot f = -2\kappa |g|^2$$

Nonlocality in Hirota's direct method

Bilinearisation of the local Hirota equation

$$\begin{aligned} f^3 \left[iq_t + \alpha q_{xx} - 2\kappa\alpha |q|^2 q + i\beta \left(q_{xxx} - 6\kappa |q|^2 q_x \right) \right] = \\ f \left[iD_t g \cdot f + \alpha D_x^2 g \cdot f + i\beta D_x^3 g \cdot f \right] + \left[3i\beta \left(\frac{g}{f} f_x - g_x \right) - \alpha g \right] \\ \times \left[D_x^2 f \cdot f + 2\kappa |g|^2 \right] \end{aligned}$$

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Solve by formal power series that becomes **exact**

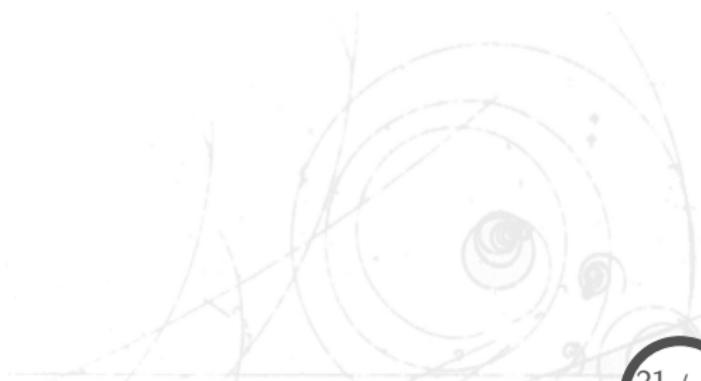
$$f(x, t) = \sum_{k=0}^{\infty} \varepsilon^{2k} f_{2k}(x, t), \quad \text{and} \quad g(x, t) = \sum_{k=1}^{\infty} \varepsilon^{2k-1} g_{2k-1}(x, t)$$

Bilinearisation of the nonlocal Hirota equation

$$\begin{aligned} f^3 \tilde{f}^* [iq_t + \alpha q_{xx} + 2\alpha \tilde{q}^* q^2 - \delta(q_{xxx} + 6q\tilde{q}^* q_x)] = \\ f\tilde{f}^* [iD_t g \cdot f + \alpha D_x^2 g \cdot f - \delta D_x^3 g \cdot f] + \left(\frac{3\delta}{f} D_x g \cdot f - \alpha g \right) \\ \times \left(\tilde{f}^* D_x^2 f \cdot f - 2fg\tilde{g}^* \right) \end{aligned}$$

not bilinear yet

$$iD_t g \cdot f + \alpha D_x^2 g \cdot f - \delta D_x^3 g \cdot f = 0, \quad \tilde{f}^* D_x^2 f \cdot f = 2fg\tilde{g}^*$$



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not bilinear yet

$$iD_t g \cdot f + \alpha D_x^2 g \cdot f - \delta D_x^3 g \cdot f = 0, \quad \tilde{f}^* D_x^2 f \cdot f = 2fg\tilde{g}^*$$

introduce auxiliary function

$$D_x^2 f \cdot f = hg, \quad \text{and} \quad 2f\tilde{g}^* = h\tilde{f}^*$$

Solve again formal power series that becomes **exact**

$$h(x, t) = \sum_k \varepsilon^k h_k(x, t).$$

Two-types of nonlocal solutions (one-soliton)

Truncated expansions: $f = 1 + \varepsilon^2 f_2$, $g = \varepsilon g_1$, $h = \varepsilon h_1$

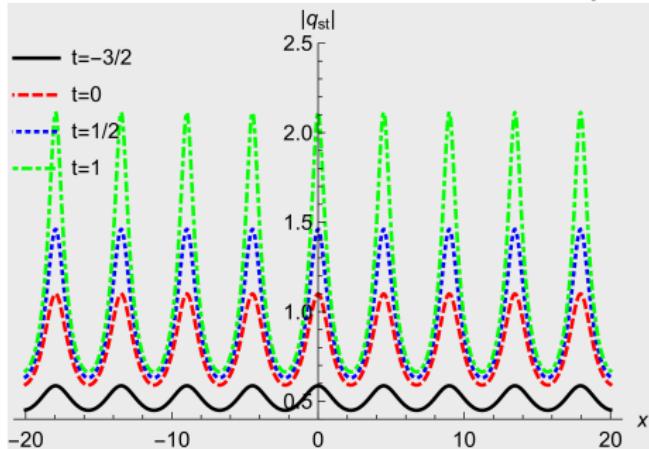
$$0 = \varepsilon [i(g_1)_t + \alpha(g_1)_{xx} - \delta(g_1)_{xxx}]$$

$$+ \varepsilon^3 [2(f_2)_x(g_1)_x - g_1 [(f_2)_{xx} + i(f_2)_t] + i f_2 [(g_1)_t + i(g_1)_{xx}]]$$

$$0 = \varepsilon^2 [2(f_2)_{xx} - g_1 h_1] + \varepsilon^4 [2f_2(f_2)_{xx} - 2(f_2)_x^2]$$

$$0 = \varepsilon [2\tilde{g}_1^* - h_1] + \varepsilon^3 [2f_2\tilde{g}_1^* - \tilde{f}_2^* h_1]$$

Standard solution, solve six equations independently, then $\varepsilon \rightarrow 1$



$$q_{st}^{(1)} = \frac{\lambda(\mu - \mu^*)^2 \tau_{\mu,\gamma}}{(\mu - \mu^*)^2 + |\lambda|^2 \tau_{\mu,\gamma} \tilde{\tau}_{\mu,\gamma}^*}$$

$$\tau_{\mu,\gamma}(x, t) := e^{\mu x + \mu^2(i\alpha - \beta\mu)t + \gamma}$$

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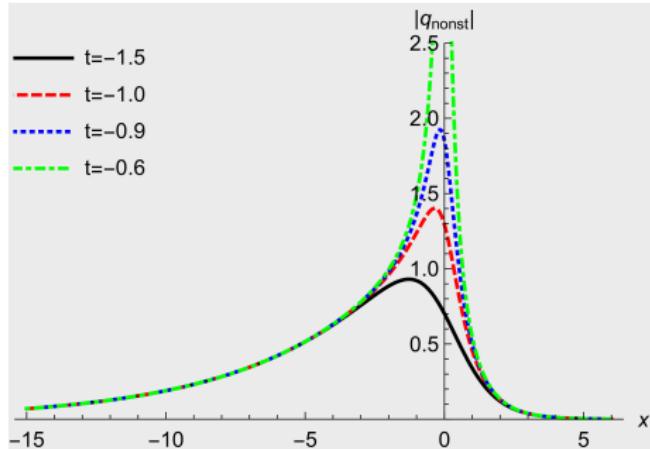
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$$0 = [2\tilde{g}_1^* - h_1] + \left[2f_2\tilde{g}_1^* - \tilde{f}_2^* h_1 \right]$$

Nonstandard solution, solve five equations, last one for $\varepsilon = 1$



$$q_{\text{nonst}}^{(1)} = \frac{(\mu + \nu)\tau_{\mu, i\gamma}}{1 + \tau_{\mu, i\gamma}\tilde{\tau}_{-\nu, -i\theta}^*}.$$

$$\tau_{\mu, \gamma}(x, t) := e^{\mu x + \mu^2(i\alpha - \beta\mu)t + \gamma}$$

Two-soliton solution

Truncated expansions:

$$f = 1 + \varepsilon^2 f_2 + \varepsilon^4 f_4, \quad g = \varepsilon g_1 + \varepsilon^3 g_3, \quad h = \varepsilon h_1 + \varepsilon^3 h_3$$

$$q_{\text{nl}}^{(2)}(x, t) = \frac{g_1(x, t) + g_3(x, t)}{1 + f_2(x, t) + f_4(x, t)}$$

$$g_1 = \tau_{\mu, \gamma} + \tau_{\nu, \delta}$$

$$g_3 = \frac{(\mu - \nu)^2}{(\mu - \mu^*)^2 (\nu - \mu^*)^2} \tau_{\mu, \gamma} \tau_{\nu, \delta} \tilde{\tau}_{\mu, \gamma}^* + \frac{(\mu - \nu)^2}{(\mu - \nu^*)^2 (\nu - \nu^*)^2} \tau_{\mu, \gamma} \tau_{\nu, \delta} \tilde{\tau}_{\nu, \delta}^*$$

$$f_2 = \frac{\tau_{\mu, \gamma} \tilde{\tau}_{\mu, \gamma}^*}{(\mu - \mu^*)^2} + \frac{\tau_{\nu, \delta} \tilde{\tau}_{\mu, \gamma}^*}{(\nu - \mu^*)^2} + \frac{\tau_{\mu, \gamma} \tilde{\tau}_{\nu, \delta}^*}{(\mu - \nu^*)^2} + \frac{\tau_{\nu, \delta} \tilde{\tau}_{\nu, \delta}^*}{(\nu - \nu^*)^2}$$

$$f_4 = \frac{(\mu - \nu)^2 (\mu^* - \nu^*)^2}{(\mu - \mu^*)^2 (\nu - \mu^*)^2 (\mu - \nu^*)^2 (\nu - \nu^*)^2} \tau_{\mu, \gamma} \tilde{\tau}_{\mu, \gamma}^* \tau_{\nu, \delta} \tilde{\tau}_{\nu, \delta}^*$$

$$h_1 = 2 \tilde{\tau}_{\mu, \gamma}^* + 2 \tilde{\tau}_{\nu, \delta}^*$$

$$h_3 = \frac{2 (\mu^* - \nu^*)^2}{(\mu - \mu^*)^2 (\nu^* - \mu)^2} \tilde{\tau}_{\mu, \gamma}^* \tilde{\tau}_{\nu, \delta}^* \tau_{\mu, \gamma} + \frac{2 (\mu^* - \nu^*)^2}{(\mu^* - \nu)^2 (\nu - \nu^*)^2} \tilde{\tau}_{\mu, \gamma}^* \tilde{\tau}_{\nu, \delta}^* \tau_{\nu, \delta}$$

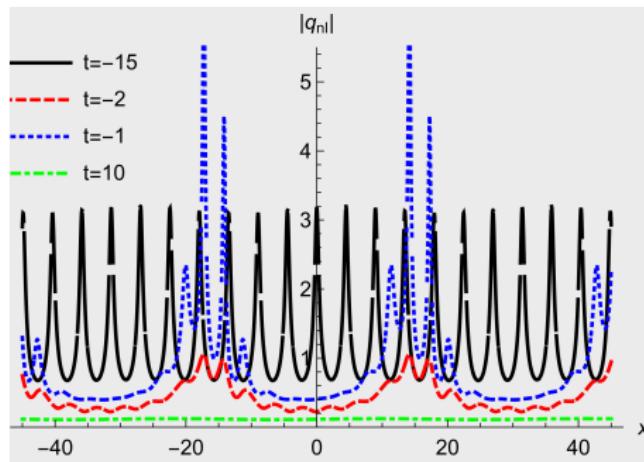
Two-soliton solution

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$$q_{\text{nl}}^{(2)}(x, t) = \frac{g_1(x, t) + g_3(x, t)}{1 + f_2(x, t) + f_4(x, t)}$$

Nonlocal regular two-soliton solution



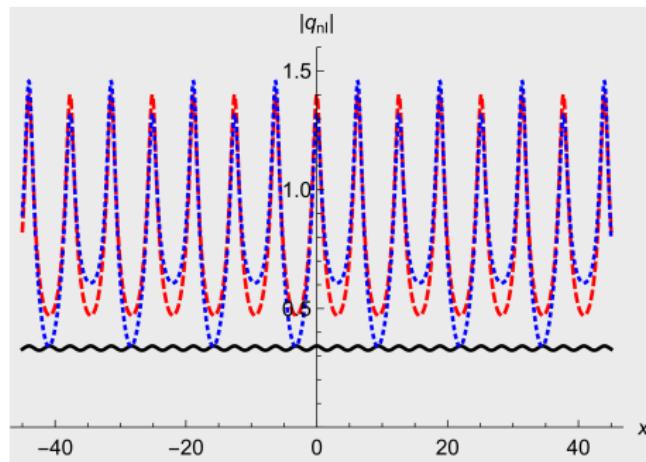
Two-soliton solution

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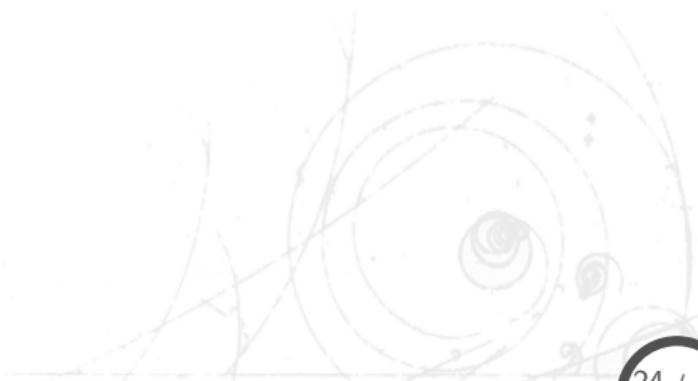
Nonlocal regular two one-soliton solution vs two-soliton solution



Nonlocality in Darboux-Crum transformations

Quantum mechanical analogue to supersymmetry, intertwining

$$L_n H_{n-1} = H_n L_n$$

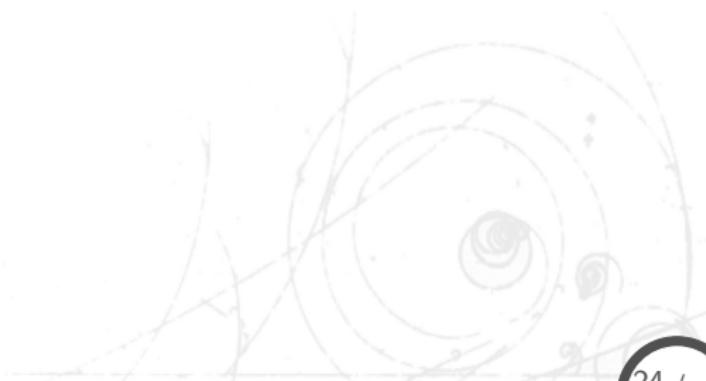


Nonlocality in Darboux-Crum transformations

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iteration $\mathcal{L}_n H_0 = H_n \mathcal{L}_n$, $\mathcal{L}_n := L_n L_{n-1} \dots L_1$, $\Psi_n(\lambda) = \mathcal{L}_n \Psi(\lambda)$



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In Hirota case, Hamiltonian of Dirac type :

$$\Psi = \begin{pmatrix} \varphi \\ \phi \end{pmatrix} \quad \Psi_x = U \Psi \iff \begin{aligned} -i\varphi_x + iq\phi &= -\lambda\varphi \\ i\phi_x - ir\varphi &= -\lambda\phi \end{aligned} \iff H\Psi(\lambda) = -\lambda\Psi(\lambda)$$

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$$H = \begin{pmatrix} -i\partial_x & iq \\ -ir & i\partial_x \end{pmatrix} = -i\sigma_3\partial_x + V,$$

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$$H_n = \begin{pmatrix} -i\partial_x & iq_n \\ -ir_n & i\partial_x \end{pmatrix} = -i\sigma_3\partial_x + V_n,$$

Solve the "seed" equations for $q = r = 0$:

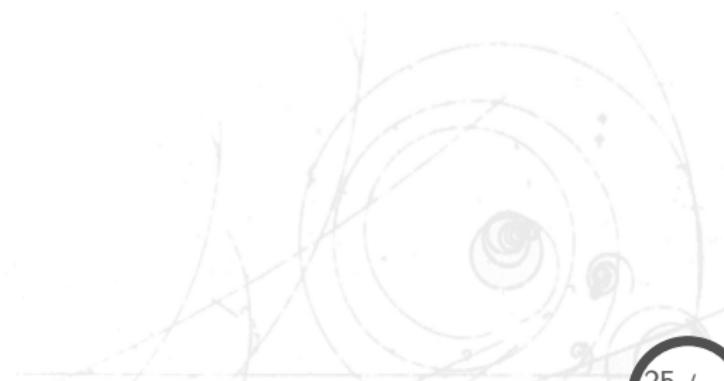
$$\tilde{\Psi}_1(x, t; \lambda) = \begin{pmatrix} \varphi_1(x, t; \lambda) \\ \phi_1(x, t; \lambda) \end{pmatrix} = \begin{pmatrix} e^{\lambda x + 2i\lambda^2(\alpha - 2\delta\lambda)t + \gamma_1} \\ e^{-\lambda x - 2i\lambda^2(\alpha - 2\delta\lambda)t + \gamma_2} \end{pmatrix}$$

Implement nonlocality in the construction Ψ_2 :

Two choices to achieve $r(x, t) = \pm q^*(-x, t)$

$$1: \varphi_2 = \pm \tilde{\phi}_1^*, \phi_2 = \tilde{\varphi}_1^* \quad 2: \phi_1 = \tilde{\varphi}_1^*, \phi_2 = \pm \tilde{\varphi}_2^*$$

The second choice is not available in the local case.



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Choice 1:

$$\tilde{\Psi}_2(x, t; \lambda) = \begin{pmatrix} \varphi_2(x, t; \lambda) \\ \phi_2(x, t; \lambda) \end{pmatrix} = \begin{pmatrix} \mp e^{\lambda^* x + 2i(\lambda^*)^2(\alpha - 2\delta\lambda)t + \gamma_2^*} \\ e^{-\lambda^* x - 2i(\lambda^*)^2(\alpha - 2\delta\lambda^*)t + \gamma_1^*} \end{pmatrix}$$

with $\lambda, \gamma_1, \gamma_2 \in \mathbb{C}$

$$q_{st}^{(1)}(x, t) = \frac{2(\lambda^* - \lambda)e^{2\lambda^* x + 2i(\lambda^*)^2(\alpha - 2\delta\lambda^*)t - \gamma_1^* + \gamma_2^*}}{1 + e^{2(\lambda^* - \lambda)x + 4i[\alpha(\lambda^*)^2 - \alpha\lambda^2 + 2\delta\lambda^3 - 2\delta(\lambda^*)^3]t - \gamma_1 + \gamma_2 - \gamma_1^* + \gamma_2^*}}.$$

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The second choice is not available in the local case.

Choice 2:

$$\tilde{\Psi}_2(x, t; \nu) = \begin{pmatrix} \varphi_2(x, t; \nu) \\ \phi_2(x, t; \nu) \end{pmatrix} = \begin{pmatrix} e^{\nu x + 2i\nu^2(\alpha - 2\delta\nu)t + \gamma_3} \\ -e^{-\nu x - 2i\nu^2(\alpha - 2\delta\nu)t + \gamma_3^*} \end{pmatrix}$$

$$q_{\text{nonst}}^{(1)}(x, t) = \frac{2(\nu - \mu)e^{\gamma_1 - \gamma_1^* + 2\mu x + 4i\mu^2(\alpha - 2\delta\mu)t}}{1 + e^{2(\mu - \nu)x + 4i(\alpha\mu^2 - \alpha\nu^2 - 2\delta\mu^3 + 2\delta\nu^3)t + \gamma_1 - \gamma_1^* - \gamma_3 + \gamma_3^*}}.$$

Nonlocal n-soliton solutions: $q_n = q + 2 \frac{\det D_n^q}{\det W_n}$, $r_n = r - 2 \frac{\det D_n^r}{\det W_n}$

$$W_n = \begin{pmatrix} \varphi_1^{(n-1)} & \varphi_1^{(n-2)} & \dots & \varphi_1 & \phi_1^{(n-1)} & \dots & \phi'_1 & \phi_1 \\ \varphi_2^{(n-1)} & \varphi_2^{(n-2)} & \dots & \varphi_2 & \phi_2^{(n-1)} & \dots & \phi'_2 & \phi_2 \\ \vdots & \vdots & \ddots & \vdots & \vdots & \ddots & \vdots & \vdots \\ \varphi_{2n}^{(n-1)} & \varphi_{2n}^{(n-2)} & \dots & \varphi_{2n} & \phi_{2n}^{(n-1)} & \dots & \phi'_{2n} & \phi_{2n} \end{pmatrix}$$

$$D_n^q = \begin{pmatrix} \phi_1^{(n-2)} & \phi_1^{(n-3)} & \dots & \phi_1 & \varphi_1^{(n)} & \dots & \varphi'_1 & \varphi_1 \\ \phi_2^{(n-2)} & \phi_2^{(n-3)} & \dots & \phi_2 & \varphi_2^{(n)} & \dots & \varphi'_2 & \varphi_2 \\ \vdots & \vdots & \ddots & \vdots & \vdots & \ddots & \vdots & \vdots \\ \phi_{2n}^{(n-2)} & \phi_{2n}^{(n-3)} & \dots & \phi_{2n} & \varphi_{2n}^{(n)} & \dots & \varphi'_{2n} & \varphi_{2n} \end{pmatrix}$$

$$D_n^r = \begin{pmatrix} \phi_1^{(n)} & \phi_1^{(n-1)} & \dots & \phi_1 & \varphi_1^{(n-2)} & \dots & \varphi'_1 & \varphi_1 \\ \phi_2^{(n)} & \phi_2^{(n-1)} & \dots & \phi_2 & \varphi_2^{(n-2)} & \dots & \varphi'_2 & \varphi_2 \\ \vdots & \vdots & \ddots & \vdots & \vdots & \ddots & \vdots & \vdots \\ \phi_{2n}^{(n)} & \phi_{2n}^{(n-1)} & \dots & \phi_{2n} & \varphi_{2n}^{(n-2)} & \dots & \varphi'_{2n} & \varphi_{2n} \end{pmatrix}$$

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In the nonlocal case use

$$\tilde{S}_{2n}^{\text{st}} = \left\{ \tilde{\Psi}_1(x, t; \lambda_1), \tilde{\Psi}_2(x, t; \lambda_1), \tilde{\Psi}_1(x, t; \lambda_2), \tilde{\Psi}_2(x, t; \lambda_2), \dots \right\}$$

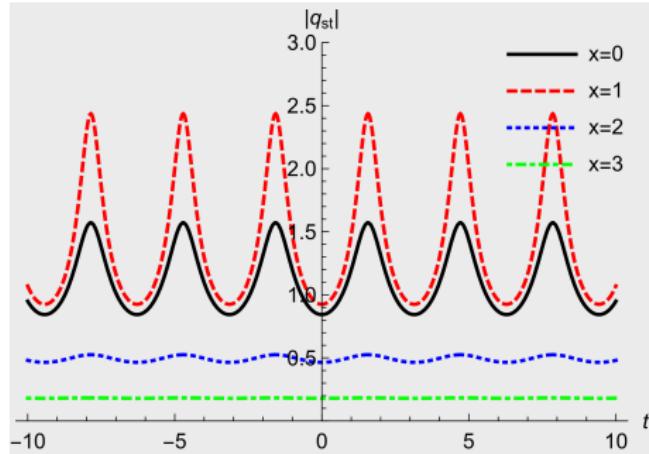
or

$$\tilde{S}_{2n}^{\text{nonst}} = \left\{ \tilde{\Psi}_1(x, t; \mu_1), \tilde{\Psi}_2(x, t; \nu_1), \tilde{\Psi}_1(x, t; \mu_2), \tilde{\Psi}_2(x, t; \nu_2), \dots \right\}$$

Time-crystals: $[r(x, t) = \pm \hat{q}^*(x, -t)]$

$$q_{\text{st}}^{(1)}(x, t) = \frac{\pm 2(\lambda - \lambda^*) e^{\gamma_1 + \gamma_1^* + 2(\lambda + \lambda^*)x}}{e^{\gamma_1 + \gamma_1^* + 4(\lambda^*)^2(2\beta\lambda^* + \delta)t + 2\mu x} \pm e^{\gamma_2 + \gamma_2^* + 4\lambda\mu^2(2\beta\lambda + \delta)t + 2\lambda^*x}}$$

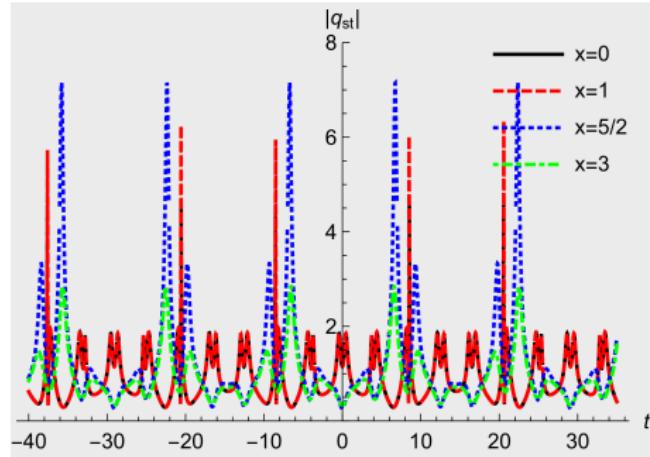
$$q_{\text{nonst}}^{(1)}(x, t) = \frac{2(\nu - \mu) e^{\gamma_1 - \gamma_1^* + 2(\mu + \nu)x}}{e^{4\mu^2(2\beta\mu + \delta)t + 2\nu x} + e^{4\nu^2(2\beta\nu + \delta)t + 2\mu x}}.$$



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Nonlocal gauge equivalence

Two zero curvature conditions are related as

$$\partial_t U_i - \partial_x V_i + [U_i, V_i] = 0 \Leftrightarrow \Psi_{i,t} = V_i \Psi_i, \Psi_{i,x} = U_i \Psi_i \quad i = 1, 2$$

$$U_1 = G U_2 G^{-1} + G_x G^{-1} \quad V_1 = G V_2 G^{-1} + G_t G^{-1}$$

when the auxiliary fields are related by a gauge field $\Psi_1 = G \Psi_2$

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System 1 \equiv (nonlocal) Hirota equation \Rightarrow system 2:

$$U_2 = -i\lambda G^{-1} \sigma_3 G, \quad V_2 = \lambda G^{-1} B_1 G + \lambda^2 G^{-1} B_2 G + \lambda^3 G^{-1} B_3 G$$

Nonlocal gauge equivalence

Two zero curvature conditions are related as

$$\partial_t U_i - \partial_x V_i + [U_i, V_i] = 0 \Leftrightarrow \Psi_{i,t} = V_i \Psi_i, \Psi_{i,x} = U_i \Psi_i \quad i = 1, 2$$

$$U_1 = G U_2 G^{-1} + G_x G^{-1} \quad V_1 = G V_2 G^{-1} + G_t G^{-1}$$

when the auxiliary fields are related by a gauge field $\Psi_1 = G \Psi_2$

System 1 \equiv (nonlocal) Hirota equation \Rightarrow system 2:

$$U_2 = -i\lambda G^{-1} \sigma_3 G, \quad V_2 = \lambda G^{-1} B_1 G + \lambda^2 G^{-1} B_2 G + \lambda^3 G^{-1} B_3 G$$

Extended continuous limit of the Heisenberg spin chain

$$\text{For } S := G^{-1} \sigma_3 G \Rightarrow S_t = i\alpha (S_x^2 + S S_{xx}) - \beta \left[\frac{3}{2} (S S_x^2)_x + S_{xxx} \right]$$

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Extended version of the Landau-Lifschitz equation

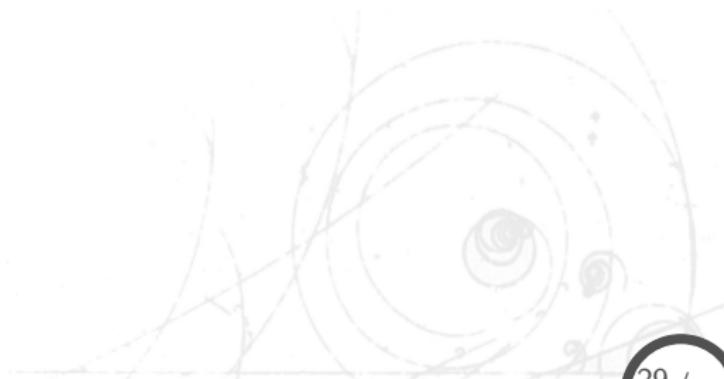
For $S = \mathbf{s} \cdot \boldsymbol{\sigma} \Rightarrow \mathbf{s}_t = -\alpha \mathbf{s} \times \mathbf{s}_{xx} - \frac{3}{2} \beta (\mathbf{s}_x \cdot \mathbf{s}_x) \mathbf{s}_x + \beta \mathbf{s} \times (\mathbf{s} \times \mathbf{s}_{xxx})$

Parameterise

$$S = \begin{pmatrix} -\omega & u \\ v & \omega \end{pmatrix} \quad \omega^2 + uv = 1$$

components of the matrix equation give

$$\begin{aligned} u_t &= i\alpha(u\omega_x - \omega u_x)_x - \beta [u_{xx} + 3/2u(u_x v_x + \omega_x^2)]_x \\ v_t &= -i\alpha(v\omega_x - \omega v_x)_x - \beta [v_{xx} + 3/2v(v_x u_x + \omega_x^2)]_x \end{aligned}$$



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Solutions from auto-gauge transformation \equiv DC transformation

$$\begin{aligned} u_1 &= \frac{2\varphi_1\varphi_2(\lambda_2\varphi_1\phi_2 - \lambda_1\varphi_2\phi_1)(\lambda_1 - \lambda_2)}{\lambda_1\lambda_2(\varphi_2\phi_1 - \varphi_1\phi_2)^2} \\ v_1 &= \frac{2\phi_1\phi_2(\lambda_1\varphi_1\phi_2 - \lambda_2\varphi_2\phi_1)(\lambda_1 - \lambda_2)}{\lambda_1\lambda_2(\varphi_2\phi_1 - \varphi_1\phi_2)^2} \\ \omega_1 &= 1 - \frac{2\varphi_1\varphi_2\phi_1\phi_2(\lambda_1 - \lambda_2)^2}{\lambda_1\lambda_2(\varphi_2\phi_1 - \varphi_1\phi_2)^2} \end{aligned}$$

Back to Hirota equation:

solve $S = G^{-1}\sigma_3 G$ for G and use $G_x = A_0 G$, $G_t = B_0 G$

$$A_0 = \begin{pmatrix} 0 & q(x, t) \\ r(x, t) & 0 \end{pmatrix}$$

$$B_0 = i\alpha [\sigma_3 (A_0)_x - \sigma_3 A_0^2] + \beta [2A_0^3 + (A_0)_x A_0 - A_0 (A_0)_x - (A_0)_{xx}]$$

$$q(x, t) = \frac{\mu(t)}{2} \left(\frac{v_x}{v} + \frac{\omega v_x - \omega_x v}{v} \right) \exp \int^x \frac{\omega(s, t)v_s(s, t) - \omega_s(s, t)v(s, t)}{v(s, t)} ds$$

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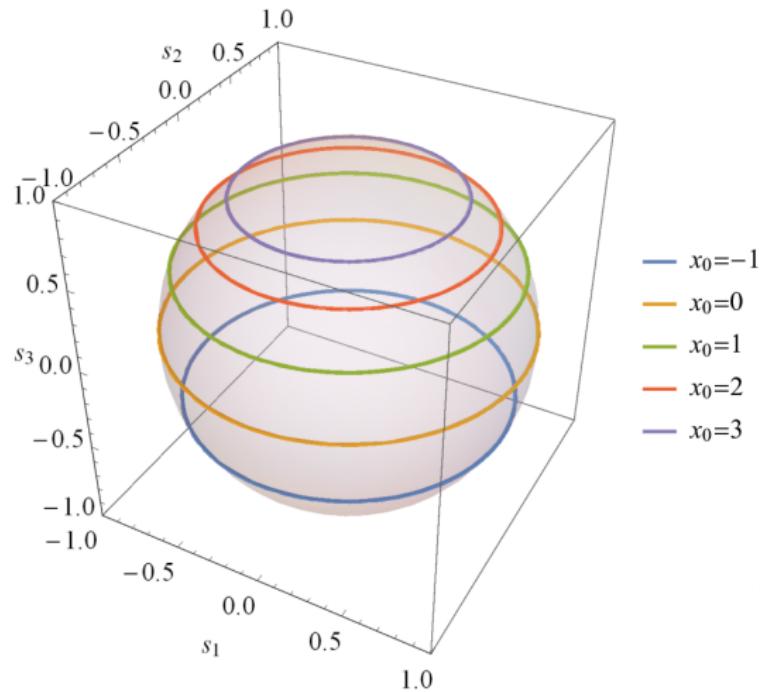
$$q_n(x, t) = \frac{\mu_n}{\prod_{k=1}^{2n} \lambda_k} \left(\frac{(\det \mathcal{V}_n)_x}{\det \mathcal{Y}_n} - \frac{(\det \mathcal{W}_n)_x \det \mathcal{V}_n}{\det \mathcal{W}_n \det \mathcal{Y}_n} \right)$$

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$$\text{Nonlocality: } r_n(x, t) = \kappa \prod_{i=1}^n |\lambda_{2i-1}|^4 / \mu_n^2 q_n^*(-x, t)$$

Trajectories of local extended version of the LL equation

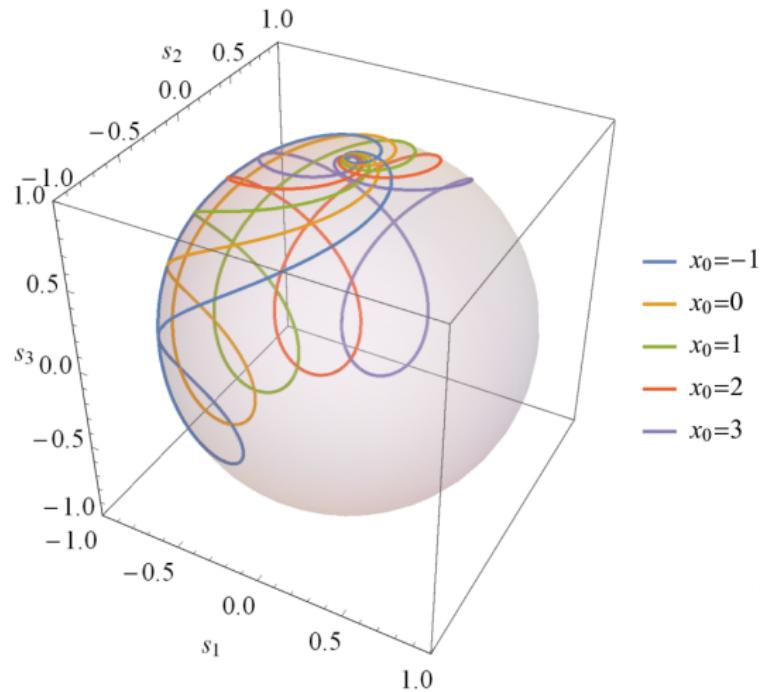
Gauge equivalent version of nonlinear Schrödinger equation $\beta = 0$



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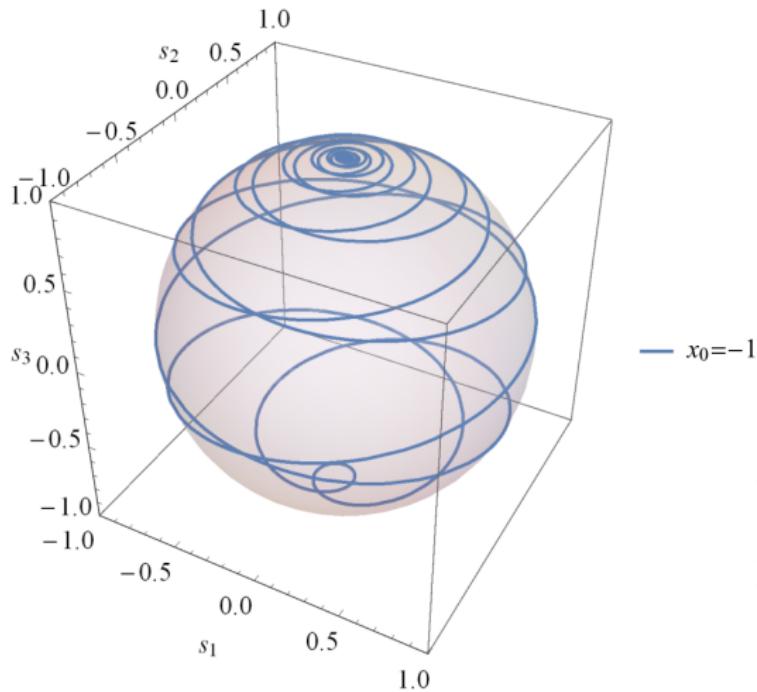
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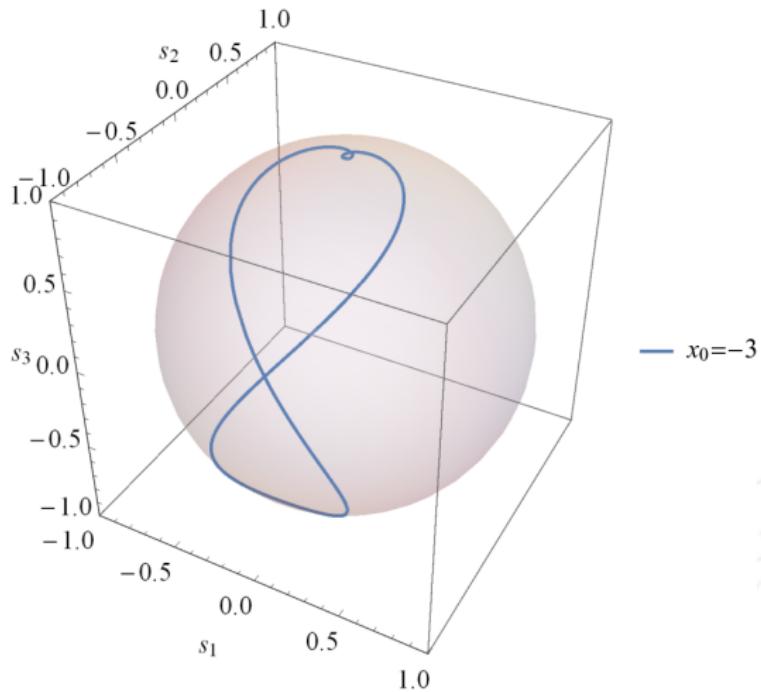
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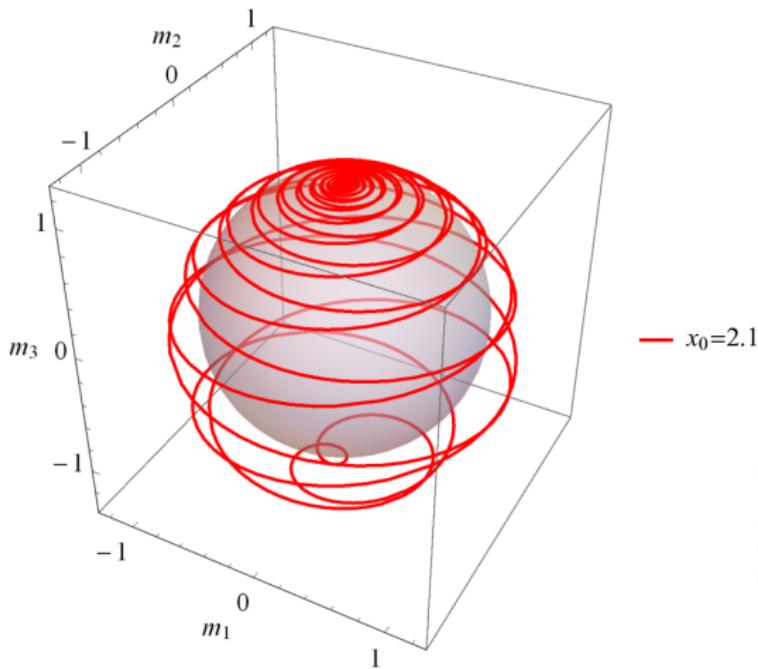
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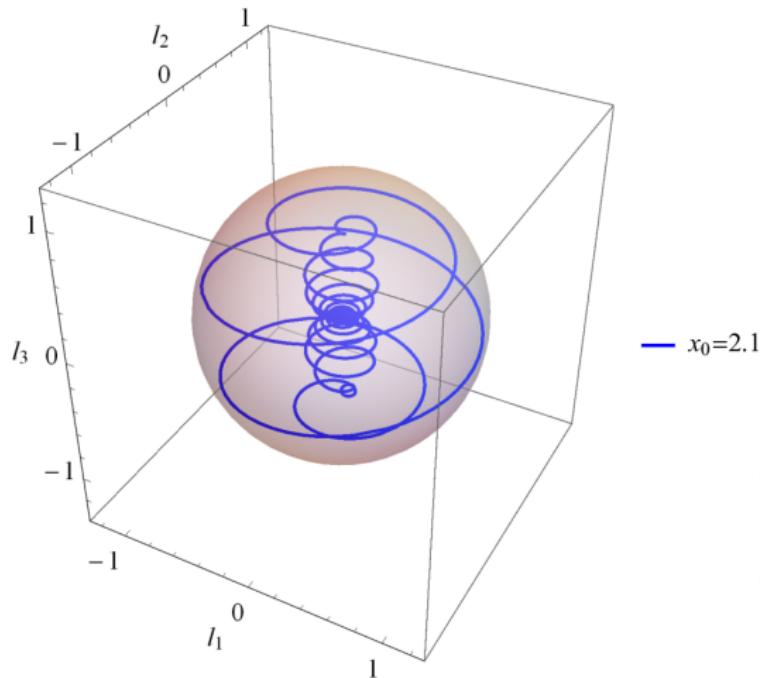
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Trajectories of nonlocal extended version of the LL equation

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Thank you for your attention