

# Non-Hermitian multi-particle systems from complex root spaces

## Andreas Fring

PTQM Symposium, Heidelberg University 25-th-28-th of September 2011

Talk is mainly based on: A.Fring and M.Smith, arXiv:1108.1719, Int. J. Theor. Phys. 50 (2011) 974, J. Phys. A43 (2010) 32520



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## Three possibilities to obtain PT-invariant Calogero models

- Extended Calogero-Moser-Sutherland models
- From constraint field equations
- Open Deformed Calogero-Moser-Sutherland models

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#### **Calogero-Moser-Sutherland models (extended)**

$$\mathcal{H}_{BK} = \frac{p^2}{2} + \frac{\omega^2}{2} \sum_{i} q_i^2 + \frac{g^2}{2} \sum_{i \neq k} \frac{1}{(q_i - q_k)^2} + i\tilde{g} \sum_{i \neq k} \frac{1}{(q_i - q_k)} p_i$$

with  $g, ilde{g} \in \mathbb{R}, q, p \in \mathbb{R}^{\ell+1}$ 

[B. Basu-Mallick, A. Kundu, Phys. Rev. B62 (2000) 9927]

- Representation independent formulation
- Other potentials apart from the rational one?
- 3 Other algebras apart from  $A_n$ ,  $B_n$  or Coxeter groups?
- Is it possible to include more coupling constants?
- Are the extensions still integrable?

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- Generalize Hamiltonian to:

$$\mathcal{H}_{\mu} = \frac{1}{2}p^2 + \frac{1}{2}\sum_{lpha \in \Delta} g_{lpha}^2 V(lpha \cdot q) + i\mu \cdot p$$

· Now  $\triangle$  is any root system

$$\mu = 1/2 \sum_{\alpha \in \Delta} \tilde{g}_{\alpha} f(\alpha \cdot q) \alpha$$
,  $f(x) = 1/x \ V(x) = f^2(x)$   
[A. F., Mod. Phys. Lett. A21 (2006) 691, Acta P. 47 (2007) 44]

Not so obvious that one can re-write

$$\mathcal{H}_{\mu} = \frac{1}{2}(p+i\mu)^2 + \frac{1}{2}\sum_{\alpha \in \Delta} \hat{g}_{\alpha}^2 V(\alpha \cdot q), \quad \hat{g}_{\alpha}^2 = \begin{cases} g_s^2 + \alpha_s^2 \tilde{g}_s^2 & \alpha \in \Delta_s \\ g_l^2 + \alpha_l^2 \tilde{g}_l^2 & \alpha \in \Delta_l \end{cases}$$

$$\Rightarrow \mathcal{H}_{\prime\prime} = \eta^{-1} h_{\mathrm{Cal}} \eta$$
 with  $\eta = e^{-q \cdot \mu}$ 

- integrability follows trivially  $\dot{L} = [L, M]: L(p) \rightarrow L(p + i\mu)$
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 $\textbf{Constrained field equations} \rightarrow \textbf{complex Calogero models}$ 

#### From real fields to complex particle systems

#### i) No restrictions

e.g. Benjamin-Ono equation

$$u_t + uu_x + \lambda Hu_{xx} = 0 \tag{*}$$

 $H \equiv$  Hilbert transform, i.e.  $Hu(x) = \frac{P}{\pi} \int_{-\infty}^{\infty} \frac{u(x)}{z-x} dz$ Then

$$u(x,t) = \frac{\lambda}{2} \sum_{k=1}^{\ell} \left( \frac{i}{x - z_k} - \frac{i}{x - z_k^*} \right) \in \mathbb{R}$$

satisfies (\*) iff  $z_k$  obeys the  $A_n$ -Calogero equ. of motion

$$\ddot{z}_k = \frac{\lambda^2}{2} \sum_{k \neq j} (z_j - z_k)^{-3}$$

[H. Chen, N. Pereira, Phys. Fluids 22 (1979) 187] [talk by J. Feinberg, PHHQP workshop VI, 2007, London]

 $\textbf{Constrained field equations} \rightarrow \textbf{complex Calogero models}$ 

# ii) restrict to submanifold

Theorem: [Airault, McKean, Moser, CPAM, (1977) 95 ] Given a Hamiltonian  $H(x_1, ..., x_n, \dot{x}_1, ..., \dot{x}_n)$  with flow

$$x_i = \partial H/\partial \dot{x}_i$$
 and  $\ddot{x}_i = -\partial H/\partial x_i$   $i = 1, \dots, n$ 

and conserved charges  $I_j$  in involution with H,i.e.  $\{I_j, H\} = 0$ . Then the locus of grad I = 0 is invariant.

$$v_{tt} = a(v^2)_{xx} + bv_{xxxx} + v_{xx}$$
 (\*\*)

Then

$$v(x,t) = c \sum_{k=1}^{\ell} (x - z_k)^{-2}$$

satisfies (\*\*) iff b=1/12, c=-a/2 and  $z_k$  obeys

$$\ddot{z}_k = 2\sum_{j \neq k} (z_j - z_k)^{-3} \qquad \Leftrightarrow \qquad \ddot{z}_k = -\frac{\partial H}{\partial z_j}$$

$$\dot{z}_k = 1 - \sum_{j \neq k} (z_j - z_k)^{-2} \qquad \Leftrightarrow \qquad \operatorname{grad}(I_3 - I_1) = 0$$

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Example: Boussinesq equation

$$v_{tt} = a(v^2)_{xx} + bv_{xxxx} + v_{xx}$$
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Then

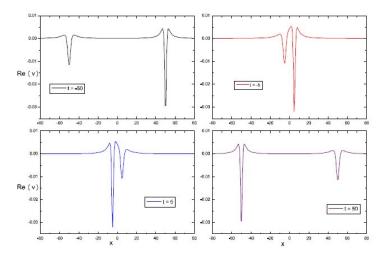
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[P. Assis and A.F., J. Phys. A42 (2009) 425206]

#### Consider

# **Antilinearly invariant deformed Calogero model**

$$\mathcal{H}_{\mathcal{PTCMS}} = \frac{p^2}{2} + \frac{m^2}{16} \sum_{\alpha \in \Delta_s} (\alpha \cdot \tilde{q})^2 + \frac{1}{2} \sum_{\alpha \in \Delta} g_\alpha V(\alpha \cdot \tilde{q}), \ m, g_\alpha \in \mathbb{R}$$

# Define deformed coordinates $(A_2)$

$$egin{array}{ll} q_1 &
ightarrow & ilde{q}_1 = q_1 \cosh arepsilon + i \sqrt{3} (q_2 - q_3) \sinh arepsilon \ q_2 &
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With standard 3D representation for the simple  $A_2$ -roots  $\alpha_1 = \{1, -1, 0\}, \ \alpha_2 = \{0, 1, -1\}, \ q_{ij} := q_i - q_j \text{ compute}$   $\alpha_1 \cdot \tilde{q} = q_{12} \cosh \varepsilon - \frac{\imath}{\sqrt{3}} (q_{13} + q_{23}) \sinh \varepsilon,$   $\alpha_2 \cdot \tilde{q} = q_{23} \cosh \varepsilon - \frac{\imath}{\sqrt{3}} (q_{21} + q_{31}) \sinh \varepsilon,$   $(\alpha_1 + \alpha_2) \cdot \tilde{q} = q_{12} \cosh \varepsilon + \frac{\imath}{2} (q_{12} + q_{22}) \sinh \varepsilon,$ 

#### Symmetries

$$S_1$$
:  $q_1 \leftrightarrow q_2, q_3 \leftrightarrow q_3, i \rightarrow -i$   
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# Unbroken $\mathcal{P}\mathcal{T}$ -symmetry guarantees real eigenvalues

- $\mathcal{P}\mathcal{T}$ -symmetry:  $\mathcal{P}\mathcal{T}: x \to -x \quad p \to p \quad i \to -i$  $(\mathcal{P}: x \to -x, p \to -p; \mathcal{T}: x \to x, p \to -p, i \to -i)$
- PT is an anti-linear operator:

$$\mathcal{P}\mathcal{T}(\lambda \Phi + \mu \Psi) = \lambda^* \mathcal{P}\mathcal{T}\Phi + \mu^* \mathcal{P}\mathcal{T}\Psi \qquad \lambda, \mu \in \mathbb{C}$$

• Real eigenvalues from unbroken  $\mathcal{P}\mathcal{T}$ -symmetry:

$$[\mathcal{H}, \mathcal{P}T] = 0 \quad \land \quad \mathcal{P}T\Phi = \Phi \quad \Rightarrow \varepsilon = \varepsilon^* \text{ for } \mathcal{H}\Phi = \varepsilon\Phi$$

Proof

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## Unbroken PT-symmetry guarantees real eigenvalues

- $\mathcal{P}\mathcal{T}$ -symmetry:  $\mathcal{P}\mathcal{T}: x \to -x \quad p \to p \quad i \to -i$  $(\mathcal{P}: x \to -x, p \to -p; \mathcal{T}: x \to x, p \to -p, i \to -i)$
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# Note, this Hamiltonian also results from deforming the roots:

$$\begin{array}{lll} \alpha_1 & \to & \tilde{\alpha}_1 = \alpha_1 \cosh \varepsilon \ + i \sqrt{3} \sinh \varepsilon \lambda_2 \\ \alpha_2 & \to & \tilde{\alpha}_2 = \alpha_2 \cosh \varepsilon \ - i \sqrt{3} \sinh \varepsilon \lambda_1 \end{array}$$

Thus

$$\mathcal{H}_{\mathcal{P}TCMS} = \frac{p^2}{2} + \frac{m^2}{16} \sum_{\tilde{\alpha} \in \tilde{\Delta}_s} (\tilde{\alpha} \cdot q)^2 + \frac{1}{2} \sum_{\tilde{\alpha} \in \tilde{\Delta}} g_{\tilde{\alpha}} V(\tilde{\alpha} \cdot q), \ m, g_{\tilde{\alpha}} \in \mathbb{R}$$
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#### Symmetries

$$\sigma_1^{\varepsilon} : \tilde{\alpha}_1 \leftrightarrow -\tilde{\alpha}_1, \, \tilde{\alpha}_2 \leftrightarrow \tilde{\alpha}_1 + \tilde{\alpha}_2 \quad \Leftrightarrow \quad q_1 \leftrightarrow q_2, \, q_3 \leftrightarrow q_3, \, i \to -i \\
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General strategy, the construction procedure

#### Construction of antilinear deformations

- Involution  $\in \mathcal{W} \equiv \text{Coxeter group} \Rightarrow \text{deform in antilinear way}$
- Find a linear deformation map:

$$\delta: \Delta \to \tilde{\Delta}(\varepsilon) \qquad \alpha \mapsto \tilde{\alpha} = \theta_{\varepsilon} \alpha$$

$$\alpha_i \in \Delta \subset \mathbb{R}^n$$
,  $\tilde{\alpha}_i(\varepsilon) \in \tilde{\Delta}(\varepsilon) \subset \mathbb{R}^n \oplus i \mathbb{R}^n$ ,  $\varepsilon \in \mathbb{R}$ 

• Find a second map that leaves  $\tilde{\Delta}(\varepsilon)$  invariant

$$\varpi: \tilde{\Delta}(\varepsilon) \to \tilde{\Delta}(\varepsilon), \qquad \tilde{\alpha} \mapsto \omega \tilde{\alpha}$$

- (i)  $\varpi: \tilde{\alpha} = \mu_1 \alpha_1 + \mu_2 \alpha_2 \mapsto \mu_1^* \omega \alpha_1 + \mu_2^* \omega \alpha_2$  for  $\mu_1, \mu_2 \in \mathbb{C}$
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- (ii) there are at least two different  $\omega_i$  with i = 1, 2, ...
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## Many solutions were constructed

$$\tilde{\Delta}(\varepsilon)$$
 for  $A_3$ 

$$\theta_{\varepsilon} = r_0 \mathbb{I} + r_2 \sigma^2 + \imath r_1 \left( \sigma - \sigma^3 \right)$$

with explicit representation

$$\sigma_{1} = \begin{pmatrix} -1 & 0 & 0 \\ 1 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix}, \sigma_{2} = \begin{pmatrix} 1 & 1 & 0 \\ 0 & -1 & 0 \\ 0 & 1 & 1 \end{pmatrix},$$

$$\sigma_{3} = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 1 \\ 0 & 0 & -1 \end{pmatrix}, \sigma = \begin{pmatrix} -1 & -1 & 0 \\ 1 & 1 & 1 \\ 0 & -1 & -1 \end{pmatrix},$$

$$\sigma_{-}=\sigma_{1}\sigma_{3},\,\sigma_{+}=\sigma_{2},\,\sigma=\sigma_{-}\sigma_{+}$$

$$\theta_{\varepsilon} = \begin{pmatrix} r_0 - ir_1 & -2ir_1 & -ir_1 - r_2 \\ 2ir_1 & r_0 - r_2 + 2ir_1 & 2ir_1 \\ -ir_1 - r_2 & -2ir_1 & r_0 - ir_1 \end{pmatrix}$$

all constraints require

$$(r_0 + r_2) \left[ (r_0 + r_2)^2 - 4r_1^2 \right] = 1$$

$$r_0 - r_2 + 2r_1 = (r_0 - r_2 + 2r_1) (r_0 + r_2)$$

$$(r_0 + r_2) = (r_0 - r_2)^2 - 4r_1^2$$

these are solved by

$$\Rightarrow \text{ simple deformed roots}$$

$$\tilde{\alpha}_1 = \cosh \varepsilon \alpha_1 + (\cosh \varepsilon - 1)\alpha_3 - i\sqrt{2}\sqrt{\cosh \varepsilon} \sinh \left(\frac{\varepsilon}{2}\right) (\alpha_1 + 2\alpha_2 + \alpha_3)$$

 $r_0(\varepsilon) = \cosh \varepsilon$ ,  $r_1(\varepsilon) = \pm \sqrt{\cosh^2 \varepsilon - \cosh \varepsilon}$ ,  $r_2(\varepsilon) = 1 - \cosh \varepsilon$ 

$$\tilde{\alpha}_2 = (2\cosh\varepsilon - 1)\alpha_2 + 2\imath\sqrt{2}\sqrt{\cosh\varepsilon}\sinh\left(\frac{\varepsilon}{2}\right)(\alpha_1 + \alpha_2 + \alpha_3),$$

$$\tilde{\alpha}_3 = \cosh \varepsilon \alpha_3 + (\cosh \varepsilon - 1)\alpha_1 - i\sqrt{2}\sqrt{\cosh \varepsilon} \sinh \left(\frac{\varepsilon}{2}\right) \left(\alpha_1 + 2\alpha_2 + \alpha_3\right) + \alpha_3 = \cosh \varepsilon \alpha_3 + (\cosh \varepsilon - 1)\alpha_1 - i\sqrt{2}\sqrt{\cosh \varepsilon} \sinh \left(\frac{\varepsilon}{2}\right) \left(\alpha_1 + 2\alpha_2 + \alpha_3\right) + \alpha_3 = \cosh \varepsilon \alpha_3 + (\cosh \varepsilon - 1)\alpha_1 - i\sqrt{2}\sqrt{\cosh \varepsilon} \sinh \left(\frac{\varepsilon}{2}\right) \left(\alpha_1 + 2\alpha_2 + \alpha_3\right) + \alpha_3 = \cosh \varepsilon \alpha_3 + (\cosh \varepsilon - 1)\alpha_1 - i\sqrt{2}\sqrt{\cosh \varepsilon} \sinh \left(\frac{\varepsilon}{2}\right) \left(\alpha_1 + 2\alpha_2 + \alpha_3\right) + \alpha_3 = \cosh \varepsilon \alpha_3 + (\cosh \varepsilon - 1)\alpha_1 - i\sqrt{2}\sqrt{\cosh \varepsilon} \sinh \left(\frac{\varepsilon}{2}\right) \left(\alpha_1 + 2\alpha_2 + \alpha_3\right) + \alpha_3 = \cosh \varepsilon \alpha_3 + (\cosh \varepsilon - 1)\alpha_1 - i\sqrt{2}\sqrt{\cosh \varepsilon} \sinh \left(\frac{\varepsilon}{2}\right) \left(\alpha_1 + 2\alpha_2 + \alpha_3\right) + \alpha_3 = \cosh \varepsilon \alpha_3 + (\cosh \varepsilon - 1)\alpha_1 - i\sqrt{2}\sqrt{\cosh \varepsilon} \sinh \left(\frac{\varepsilon}{2}\right) \left(\alpha_1 + 2\alpha_2 + \alpha_3\right) + \alpha_3 = \cosh \varepsilon \alpha_3 + (\cosh \varepsilon - 1)\alpha_1 - i\sqrt{2}\sqrt{\cosh \varepsilon} \cosh \varepsilon + (\cosh \varepsilon - 1)\alpha_1 - (\cosh \varepsilon - 1)\alpha_1 - (\cosh \varepsilon - 1)\alpha_2 + (\cosh \varepsilon - 1)\alpha_1 - (\cosh \varepsilon - 1)\alpha_2 + (\cosh \varepsilon -$$

remaining positive roots

$$\tilde{\alpha}_4 := \tilde{\alpha}_1 + \tilde{\alpha}_2, \, \tilde{\alpha}_5 := \tilde{\alpha}_2 + \tilde{\alpha}_3, \, \tilde{\alpha}_6 := \tilde{\alpha}_1 + \tilde{\alpha}_2 + \tilde{\alpha}_3.$$

# $\tilde{\Delta}(\varepsilon)$ for $A_{4n-1}$ -subseries closed solution

$$\theta_{\varepsilon} = r_0 \mathbb{I} + r_{2n} \sigma^{2n} + \imath r_n \left( \sigma^n - \sigma^{-n} \right),$$

- with 
$$r_{2n}=1-r_0,\,r_n=\pm\sqrt{r_0^2-r_0}$$

- useful choice  $r_0 = \cosh \varepsilon$ 

$$\tilde{\Delta}(\varepsilon)$$
 for  $E_6$ 

$$heta_{arepsilon} = \left( egin{array}{cccccc} r_0 & -2\imath r_2 & 0 & -2\imath r_2 & -2\imath r_2 & -\imath r_2 \ 2\imath r_2 & r_0 + \imath r_2 & 2\imath r_2 & 2\imath r_2 & 2\imath r_2 & 2\imath r_2 \ 0 & 2\imath r_2 & r_0 + 2\imath r_2 & 4\imath r_2 & 3\imath r_2 & 2\imath r_2 \ -2\imath r_2 & -2\imath r_2 & -4\imath r_2 & r_0 - 5\imath r_2 & -4\imath r_2 & -2\imath r_2 \ 2\imath r_2 & 2\imath r_2 & 3\imath r_2 & 4\imath r_2 & r_0 + 2\imath r_2 & 0 \ -\imath r_2 & -2\imath r_2 & -2\imath r_2 & -2\imath r_2 & 0 & r_0 \end{array} 
ight)$$

$$r_2 = \pm 1/\sqrt{3}\sqrt{r_0^2 - 1} \;, \; r_0 = \cosh \varepsilon$$

# $\tilde{\Delta}(\varepsilon)$ for $B_{2n+1}$ -subseries

no solution based on factorisation of the Coxeter element

# $\tilde{\Delta}(\varepsilon)$ for $A_{4n-1}$ -subseries closed solution

$$\theta_{\varepsilon} = r_0 \mathbb{I} + r_{2n} \sigma^{2n} + \imath r_n \left( \sigma^n - \sigma^{-n} \right),$$

- with 
$$r_{2n}=1-r_0,\,r_n=\pm\sqrt{r_0^2-r_0}$$

- useful choice  $r_0 = \cosh \varepsilon$ 

# $\tilde{\Delta}(\varepsilon)$ for $E_6$

$$\theta_{\varepsilon} = \begin{pmatrix} r_0 & -2\imath r_2 & 0 & -2\imath r_2 & -2\imath r_2 & -\imath r_2 \\ 2\imath r_2 & r_0 + \imath r_2 & 2\imath r_2 & 2\imath r_2 & 2\imath r_2 & 2\imath r_2 \\ 0 & 2\imath r_2 & r_0 + 2\imath r_2 & 4\imath r_2 & 3\imath r_2 & 2\imath r_2 \\ -2\imath r_2 & -2\imath r_2 & -4\imath r_2 & r_0 - 5\imath r_2 & -4\imath r_2 & -2\imath r_2 \\ 2\imath r_2 & 2\imath r_2 & 3\imath r_2 & 4\imath r_2 & r_0 + 2\imath r_2 & 0 \\ -\imath r_2 & -2\imath r_2 & -2\imath r_2 & -2\imath r_2 & 0 & r_0 \end{pmatrix}$$

$$\emph{r}_{2}=\pm1/\sqrt{3}\sqrt{\emph{r}_{0}^{2}-1}$$
 ,  $\emph{r}_{0}=\cosharepsilon$ 

# $\tilde{\Delta}(\varepsilon)$ for $B_{2n+1}$ -subseries

no solution based on factorisation of the Coxeter element.

# $\tilde{\Delta}(\varepsilon)$ for $A_{4n-1}$ -subseries

closed solution

$$\theta_{\varepsilon} = r_0 \mathbb{I} + r_{2n} \sigma^{2n} + \imath r_n \left( \sigma^n - \sigma^{-n} \right),$$

- with 
$$r_{2n}=1-r_0,\,r_n=\pm\sqrt{r_0^2-r_0}$$

- useful choice  $r_0 = \cosh \varepsilon$ 

$$\tilde{\Delta}(\varepsilon)$$
 for  $E_6$ 

$$\theta_{\varepsilon} = \begin{pmatrix} r_0 & -2\imath r_2 & 0 & -2\imath r_2 & -2\imath r_2 & -\imath r_2 \\ 2\imath r_2 & r_0 + \imath r_2 & 2\imath r_2 & 2\imath r_2 & 2\imath r_2 & 2\imath r_2 \\ 0 & 2\imath r_2 & r_0 + 2\imath r_2 & 4\imath r_2 & 3\imath r_2 & 2\imath r_2 \\ -2\imath r_2 & -2\imath r_2 & -4\imath r_2 & r_0 - 5\imath r_2 & -4\imath r_2 & -2\imath r_2 \\ 2\imath r_2 & 2\imath r_2 & 3\imath r_2 & 4\imath r_2 & r_0 + 2\imath r_2 & 0 \\ -\imath r_2 & -2\imath r_2 & -2\imath r_2 & -2\imath r_2 & 0 & r_0 \end{pmatrix}$$

$$r_2=\pm 1/\sqrt{3}\sqrt{r_0^2-1}$$
 ,  $r_0=\cosh arepsilon$ 

# $\tilde{\Delta}(\varepsilon)$ for $B_{2n+1}$ -subseries

no solution based on factorisation of the Coxeter element

# with different $\omega_i$ we find for instance for $B_{2n+1}$

$$\begin{split} \tilde{\alpha}_{2j-1} &= \cosh \varepsilon \alpha_{2j-1} + i \sinh \varepsilon \left( \alpha_{2j-1} + 2 \sum_{k=2j}^{\ell} \alpha_k \right) \quad \text{for } j = 1, \dots, \\ \tilde{\alpha}_{2j} &= \cosh \varepsilon \alpha_{2j} - i \sinh \varepsilon \left( \sum_{k=2j}^{2j+2} \alpha_k + 2 \sum_{k=2j+3}^{\ell} 2\alpha_k \right) \quad \text{for } j = 1, \dots \\ \tilde{\alpha}_{\ell-1} &= \cosh \varepsilon (\alpha_{\ell-1} + \alpha_{\ell}) - \alpha_{\ell} - i \sinh \varepsilon \left( \alpha_{\ell-2} + \alpha_{\ell-1} + \alpha_{\ell} \right), \\ \tilde{\alpha}_{\ell} &= \alpha_{\ell}. \end{split}$$

in dual space

with 
$$R = \begin{pmatrix} \cosh \varepsilon & i \sinh \varepsilon \\ -i \sinh \varepsilon & \cosh \varepsilon \end{pmatrix}$$

with different  $\omega_i$  we find for instance for  $B_{2n+1}$ 

$$\begin{split} \tilde{\alpha}_{2j-1} &= \cosh \varepsilon \alpha_{2j-1} + i \sinh \varepsilon \left( \alpha_{2j-1} + 2 \sum_{k=2j}^{\ell} \alpha_k \right) \quad \text{for } j = 1, \dots, \\ \tilde{\alpha}_{2j} &= \cosh \varepsilon \alpha_{2j} - i \sinh \varepsilon \left( \sum_{k=2j}^{2j+2} \alpha_k + 2 \sum_{k=2j+3}^{\ell} 2\alpha_k \right) \quad \text{for } j = 1, \dots \end{split}$$

$$\begin{array}{rcl} \left( k=2j & k=2j+3 & J \\ \tilde{\alpha}_{\ell-1} & = & \cosh \varepsilon (\alpha_{\ell-1}+\alpha_{\ell}) - \alpha_{\ell} - i \sinh \varepsilon \left( \alpha_{\ell-2} + \alpha_{\ell-1} + \alpha_{\ell} \right), \\ \tilde{\alpha}_{\ell} & = & \alpha_{\ell}. \end{array}$$

in dual space

$$\theta_{\varepsilon}^{\star} = \begin{pmatrix} R & & & & \\ & R & & 0 & & \\ & & R & & & \\ & 0 & & \ddots & & \\ & & & 1 \end{pmatrix} \quad \text{with } R = \begin{pmatrix} \cosh \varepsilon & i \sinh \varepsilon \\ -i \sinh \varepsilon & \cosh \varepsilon \end{pmatrix}$$

Construction of new models

For **any** model based on roots, these deformed roots can be used to define new invariant models simply by

$$\alpha \to \tilde{\alpha}$$
.

For instance Calogero models:

Three particle system is solved

- Physical properties (A<sub>2</sub>, G<sub>2</sub>)
  - The deformed model can be solved by separation of variables as the undeformed case.
  - Some restrictions cease to exist, as the wavefunctions are now regularized.
  - → modified energy spectrum:

$$E=2\left|\omega\right|\left(2n+\lambda+1\right)$$

becomes

$$E_{n\ell}^{\pm} = 2|\omega|\left[2n + 6(\kappa_s^{\pm} + \kappa_l^{\pm} + \ell) + 1\right]$$
 for  $n, \ell \in \mathbb{N}_0$ ,

with 
$$\kappa_{s/l}^{\pm} = (1 \pm \sqrt{1 + 4g_{s/l}})/4$$

[A. Fring and M. Znojil, J. Phys. A41 (2008) 194010]

# generalized Calogero Hamiltionian (undeformed)

$$\mathcal{H}_{\mathcal{C}}(p,q) = \frac{p^2}{2} + \frac{\omega^2}{4} \sum_{\alpha \in \Delta^+} (\alpha \cdot q)^2 + \sum_{\alpha \in \Delta^+} \frac{g_\alpha}{(\alpha \cdot q)^2},$$

define the variables

$$z:=\prod_{\alpha\in\Delta^+}(\alpha\cdot q)$$
 and  $r^2:=rac{1}{\hat{h}t_\ell}\sum_{\alpha\in\Delta^+}(\alpha\cdot q)^2,$ 

 $\hat{h}\equiv$  dual Coxeter number,  $t_\ell\equiv\ell$ -th symmetrizer of  $\mu$ 

Ansatz:

$$\psi(q) \to \psi(z,r) = z^{\kappa+1/2} \varphi(r)$$

 $\Rightarrow$  solution for  $\kappa = 1/2\sqrt{1+4g}$ .

$$\varphi_n(r) = c_n \exp\left(-\sqrt{\frac{\hat{h}t_\ell}{2}} \frac{\omega}{2} r^2\right) L_n^a \left(\sqrt{\frac{\hat{h}t_\ell}{2}} \omega r^2\right)$$

$$L_n^a(x) \equiv \text{Laguerre polynomial}, \ a = \left(2 + h + h\sqrt{1 + 4g}\right)I/4 - 1$$

Introduction

• generalized Calogero Hamiltionian (undeformed)

$$\mathcal{H}_{\mathcal{C}}(p,q) = \frac{p^2}{2} + \frac{\omega^2}{4} \sum_{\alpha \in \Delta^+} (\alpha \cdot q)^2 + \sum_{\alpha \in \Delta^+} \frac{g_\alpha}{(\alpha \cdot q)^2},$$

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$$L_n^a(x) \equiv \text{Laguerre polynomial}, \ a = \left(2 + h + h\sqrt{1 + 4g}\right)I/4 - 1$$

• eigenenergies

$$E_n = \frac{1}{4} \left[ \left( 2 + h + h\sqrt{1 + 4g} \right) I + 8n \right] \sqrt{\frac{\hat{h}t_{\ell}}{2}} \omega$$

anyonic exchange factors

$$\psi(q_1,\ldots,q_i,q_j,\ldots q_n)=e^{i\pi s}\psi(q_1,\ldots,q_j,q_i,\ldots q_n),\quad \text{for } 1\leq i,j\leq n,$$

with

$$s = \frac{1}{2} + \frac{1}{2}\sqrt{1 + 4g}$$

∴ r is symmetric and z antisymmetric

### The construction is based on the identities:

$$egin{array}{lcl} \sum_{lpha,eta\in\Delta^+}rac{lpha\cdoteta}{(lpha\cdotoldsymbol{q})}&=&\sum_{lpha\in\Delta^+}rac{lpha^2}{(lpha\cdotoldsymbol{q})^2},\ &\sum_{lpha,eta\in\Delta^+}(lpha\cdoteta)rac{(lpha\cdotoldsymbol{q})}{(eta\cdotoldsymbol{q})}&=&rac{\hat{h}h\ell}{2}t_\ell,\ &\sum_{lpha,eta\in\Delta^+}(lpha\cdoteta)\,(lpha\cdotoldsymbol{q})(eta\cdotoldsymbol{q})&=&\hat{h}t_\ell\sum_{lpha\in\Delta^+}(lpha\cdotoldsymbol{q})^2,\ &\sum_{lpha\in\Delta^+}lpha^2&=&\ell\hat{h}t_\ell. \end{array}$$

Strong evidence on a case-by-case level, but no rigorous proof.

# antilinearly deformed Calogero Hamiltionian

$$\mathcal{H}_{adC}(p,q) = \frac{p^2}{2} + \frac{\omega^2}{4} \sum_{\tilde{\alpha} \in \tilde{\Delta}^+} (\tilde{\alpha} \cdot q)^2 + \sum_{\tilde{\alpha} \in \Delta^+} \frac{g_{\tilde{\alpha}}}{(\tilde{\alpha} \cdot q)^2}$$

define the variables

$$ilde{z} := \prod_{ ilde{lpha} \in ilde{\Delta}^+} ( ilde{lpha} \cdot q) \qquad ext{and} \qquad ilde{r}^2 := rac{1}{\hat{h}t_\ell} \sum_{ ilde{lpha} \in ilde{\Delta}^+} ( ilde{lpha} \cdot q)^2$$

Ansatz

$$\psi(q) \to \psi(\tilde{z}, \tilde{r}) = \tilde{z}^s \varphi(\tilde{r})$$

when identies still hold =

$$\psi(\mathbf{q}) = \psi(\tilde{\mathbf{z}}, \mathbf{r}) = \tilde{\mathbf{z}}^{s} \varphi_{n}(\mathbf{r})$$

# antilinearly deformed Calogero Hamiltionian

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define the variables

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antilinearly deformed Calogero Hamiltionian

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antilinearly deformed Calogero Hamiltionian

$$\mathcal{H}_{\textit{adC}}(\textit{p},\textit{q}) = \frac{\textit{p}^2}{2} + \frac{\omega^2}{4} \sum_{\tilde{\alpha} \in \tilde{\Delta}^+} (\tilde{\alpha} \cdot \textit{q})^2 + \sum_{\tilde{\alpha} \in \Delta^+} \frac{g_{\tilde{\alpha}}}{(\tilde{\alpha} \cdot \textit{q})^2}$$

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when identies still hold  $\Rightarrow$ 

$$\psi(\mathbf{q}) = \psi(\tilde{\mathbf{z}}, \mathbf{r}) = \tilde{\mathbf{z}}^{\mathbf{s}} \varphi_{\mathbf{n}}(\mathbf{r})$$

# Deformed $A_3$ -models

 potential from deformed Coxeter group factors  $\alpha_1 = \{1, -1, 0, 0\}, \, \alpha_2 = \{0, 1, -1, 0\}, \, \alpha_3 = \{0, 0, 1, -1\}$  $\tilde{\alpha}_1 \cdot q = q_{43} + \cosh \varepsilon (q_{12} + q_{34}) - i \sqrt{2 \cosh \varepsilon} \sinh \frac{\varepsilon}{2} (q_{13} + q_{24})$  $\tilde{\alpha}_2 \cdot q = q_{23}(2\cosh \varepsilon - 1) + i2\sqrt{2\cosh \varepsilon} \sinh \frac{\varepsilon}{2} q_{14}$  $\tilde{\alpha}_3 \cdot q = q_{21} + \cosh \varepsilon (q_{12} + q_{34}) - i \sqrt{2 \cosh \varepsilon} \sinh \frac{\varepsilon}{2} (q_{13} + q_{24})$  $\tilde{\alpha}_4 \cdot q = q_{42} + \cosh \varepsilon (q_{13} + q_{24}) + i \sqrt{2 \cosh \varepsilon} \sinh \frac{\varepsilon}{2} (q_{12} + q_{34})$  $\tilde{\alpha}_5 \cdot q = q_{31} + \cosh \varepsilon (q_{13} + q_{24}) + i \sqrt{2 \cosh \varepsilon} \sinh \frac{\varepsilon}{2} (q_{12} + q_{34})$  $\tilde{\alpha}_6 \cdot q = q_{14} (2 \cosh \varepsilon - 1) - i \sqrt{2 \cosh \varepsilon} \sinh \frac{\varepsilon}{2} q_{23}$ 

notation  $q_{ij} = q_i - q_i$ , No longer singular for  $q_{ii} = 0$ 

Anyonic exchange factors

# **Deformed** A<sub>3</sub>-models

 potential from deformed Coxeter group factors  $\alpha_1 = \{1, -1, 0, 0\}, \, \alpha_2 = \{0, 1, -1, 0\}, \, \alpha_3 = \{0, 0, 1, -1\}$  $\tilde{\alpha}_1 \cdot q = q_{43} + \cosh \varepsilon (q_{12} + q_{34}) - i \sqrt{2 \cosh \varepsilon} \sinh \frac{\varepsilon}{2} (q_{13} + q_{24})$  $\tilde{\alpha}_2 \cdot q = q_{23}(2\cosh \varepsilon - 1) + i2\sqrt{2\cosh \varepsilon} \sinh \frac{\varepsilon}{2} q_{14}$  $\tilde{\alpha}_3 \cdot q = q_{21} + \cosh \varepsilon (q_{12} + q_{34}) - i \sqrt{2 \cosh \varepsilon} \sinh \frac{\varepsilon}{2} (q_{13} + q_{24})$  $\tilde{\alpha}_4 \cdot q = q_{42} + \cosh \varepsilon (q_{13} + q_{24}) + i \sqrt{2 \cosh \varepsilon} \sinh \frac{\varepsilon}{2} (q_{12} + q_{34})$  $\tilde{\alpha}_5 \cdot q = q_{31} + \cosh \varepsilon (q_{13} + q_{24}) + i \sqrt{2 \cosh \varepsilon} \sinh \frac{\varepsilon}{2} (q_{12} + q_{34})$  $\tilde{\alpha}_6 \cdot q = q_{14}(2\cosh \varepsilon - 1) - i\sqrt{2\cosh \varepsilon} \sinh \frac{\varepsilon}{2} q_{23}$ 

notation  $q_{ij} = q_i - q_j$ , No longer singular for  $q_{ij} = 0$ 

Introduction

# ullet $\mathcal{P}\mathcal{T}$ -symmetry for $\tilde{lpha}$

$$\begin{split} \sigma_{-}^{\varepsilon}: \; \tilde{\alpha}_{1} \rightarrow -\tilde{\alpha}_{1}, \, \tilde{\alpha}_{2} \rightarrow \tilde{\alpha}_{6}, \, \tilde{\alpha}_{3} \rightarrow -\tilde{\alpha}_{3}, \, \tilde{\alpha}_{4} \rightarrow \tilde{\alpha}_{5}, \, \tilde{\alpha}_{5} \rightarrow \tilde{\alpha}_{4}, \, \tilde{\alpha}_{6} \rightarrow \tilde{\alpha}_{6}, \\ \sigma_{+}^{\varepsilon}: \tilde{\alpha}_{1} \rightarrow \tilde{\alpha}_{4}, \, \tilde{\alpha}_{2} \rightarrow -\tilde{\alpha}_{2}, \, \tilde{\alpha}_{3} \rightarrow \tilde{\alpha}_{5}, \, \tilde{\alpha}_{4} \rightarrow \tilde{\alpha}_{1}, \, \tilde{\alpha}_{5} \rightarrow \tilde{\alpha}_{3}, \, \tilde{\alpha}_{6} \rightarrow \tilde{\alpha}_{6} \end{split}$$

PT-symmetry in dual space

$$\sigma_{-}^{\varepsilon}: q_1 \rightarrow q_2, q_2 \rightarrow q_1, q_3 \rightarrow q_4, q_4 \rightarrow q_3, i \rightarrow -i$$
  
$$\sigma_{+}^{\varepsilon}: q_1 \rightarrow q_1, q_2 \rightarrow q_3, q_3 \rightarrow q_2, q_4 \rightarrow q_4, i \rightarrow -i$$

 $\Rightarrow$ 

$$\sigma_{-}^{\varepsilon} \tilde{z}(q_{1}, q_{2}, q_{3}, q_{4}) = \tilde{z}^{*}(q_{2}, q_{1}, q_{4}, q_{3}) = \tilde{z}(q_{1}, q_{2}, q_{3}, q_{4}) 
\sigma_{+}^{\varepsilon} \tilde{z}(q_{1}, q_{2}, q_{3}, q_{4}) = \tilde{z}^{*}(q_{1}, q_{3}, q_{2}, q_{4}) = -\tilde{z}(q_{1}, q_{2}, q_{3}, q_{4}) 
\psi(q_{1}, q_{2}, q_{3}, q_{4}) = e^{i\pi S} \psi(q_{2}, q_{4}, q_{1}, q_{3}).$$

#### Anyonic exchange factors

## • $\mathcal{P}\mathcal{T}$ -symmetry for $\tilde{\alpha}$

$$\begin{split} \sigma_{-}^{\varepsilon}: \ \tilde{\alpha}_{1} \rightarrow -\tilde{\alpha}_{1}, \ \tilde{\alpha}_{2} \rightarrow \tilde{\alpha}_{6}, \ \tilde{\alpha}_{3} \rightarrow -\tilde{\alpha}_{3}, \ \tilde{\alpha}_{4} \rightarrow \tilde{\alpha}_{5}, \ \tilde{\alpha}_{5} \rightarrow \tilde{\alpha}_{4}, \ \tilde{\alpha}_{6} \rightarrow \tilde{\alpha}_{5}, \\ \sigma_{+}^{\varepsilon}: \tilde{\alpha}_{1} \rightarrow \tilde{\alpha}_{4}, \ \tilde{\alpha}_{2} \rightarrow -\tilde{\alpha}_{2}, \ \tilde{\alpha}_{3} \rightarrow \tilde{\alpha}_{5}, \ \tilde{\alpha}_{4} \rightarrow \tilde{\alpha}_{1}, \ \tilde{\alpha}_{5} \rightarrow \tilde{\alpha}_{3}, \ \tilde{\alpha}_{6} \rightarrow \tilde{\alpha}_{6} \end{split}$$

PT-symmetry in dual space

$$egin{aligned} \sigma_-^arepsilon &: q_1 
ightarrow q_2, \ q_2 
ightarrow q_1, \ q_3 
ightarrow q_4, \ q_4 
ightarrow q_3, \ \imath 
ightarrow -\imath \ \sigma_+^arepsilon &: q_1 
ightarrow q_1, \ q_2 
ightarrow q_3, \ q_3 
ightarrow q_2, \ q_4 
ightarrow q_4, \ \imath 
ightarrow -\imath \end{aligned}$$

 $\Rightarrow$ 

$$\sigma_{-}^{\varepsilon} \tilde{Z}(q_{1}, q_{2}, q_{3}, q_{4}) = \tilde{Z}^{*}(q_{2}, q_{1}, q_{4}, q_{3}) = \tilde{Z}(q_{1}, q_{2}, q_{3}, q_{4}) 
\sigma_{+}^{\varepsilon} \tilde{Z}(q_{1}, q_{2}, q_{3}, q_{4}) = \tilde{Z}^{*}(q_{1}, q_{3}, q_{2}, q_{4}) = -\tilde{Z}(q_{1}, q_{2}, q_{3}, q_{4}) 
\psi(q_{1}, q_{2}, q_{3}, q_{4}) = e^{i\pi S} \psi(q_{2}, q_{4}, q_{1}, q_{3}).$$

#### Anyonic exchange factors

## • $\mathcal{P}\mathcal{T}$ -symmetry for $\tilde{\alpha}$

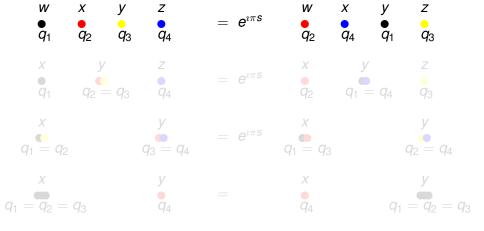
$$\begin{split} \sigma_{-}^{\varepsilon}: \ \tilde{\alpha}_{1} \rightarrow -\tilde{\alpha}_{1}, \ \tilde{\alpha}_{2} \rightarrow \tilde{\alpha}_{6}, \ \tilde{\alpha}_{3} \rightarrow -\tilde{\alpha}_{3}, \ \tilde{\alpha}_{4} \rightarrow \tilde{\alpha}_{5}, \ \tilde{\alpha}_{5} \rightarrow \tilde{\alpha}_{4}, \ \tilde{\alpha}_{6} \rightarrow \tilde{\alpha}_{6}, \\ \sigma_{+}^{\varepsilon}: \tilde{\alpha}_{1} \rightarrow \tilde{\alpha}_{4}, \ \tilde{\alpha}_{2} \rightarrow -\tilde{\alpha}_{2}, \ \tilde{\alpha}_{3} \rightarrow \tilde{\alpha}_{5}, \ \tilde{\alpha}_{4} \rightarrow \tilde{\alpha}_{1}, \ \tilde{\alpha}_{5} \rightarrow \tilde{\alpha}_{3}, \ \tilde{\alpha}_{6} \rightarrow \tilde{\alpha}_{6} \end{split}$$

PT-symmetry in dual space

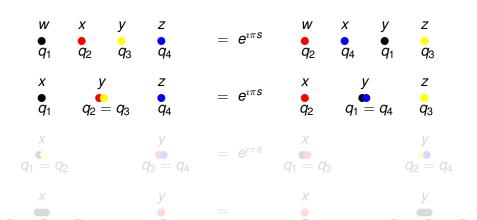
$$\sigma_{-}^{\varepsilon}: q_1 \rightarrow q_2, q_2 \rightarrow q_1, q_3 \rightarrow q_4, q_4 \rightarrow q_3, i \rightarrow -i$$
  
 $\sigma_{+}^{\varepsilon}: q_1 \rightarrow q_1, q_2 \rightarrow q_3, q_3 \rightarrow q_2, q_4 \rightarrow q_4, i \rightarrow -i$ 

 $\Rightarrow$ 

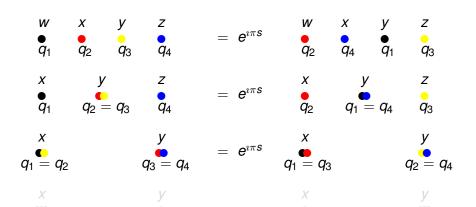
$$\begin{split} \sigma_{-}^{\varepsilon} & \tilde{\mathcal{Z}}(q_1, q_2, q_3, q_4) &= \tilde{\mathcal{Z}}^*(q_2, q_1, q_4, q_3) = \tilde{\mathcal{Z}}(q_1, q_2, q_3, q_4) \\ \sigma_{+}^{\varepsilon} & \tilde{\mathcal{Z}}(q_1, q_2, q_3, q_4) &= \tilde{\mathcal{Z}}^*(q_1, q_3, q_2, q_4) = -\tilde{\mathcal{Z}}(q_1, q_2, q_3, q_4) \\ & \psi(q_1, q_2, q_3, q_4) = e^{\imath \pi s} \psi(q_2, q_4, q_1, q_3). \end{split}$$

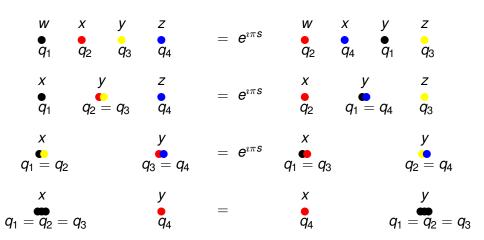


Anyonic exchange factors



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Introduction

# Find Hermitian counterpart h, Dyson map $\eta$ and metric $\rho$ :

$$h = \eta H \eta^{-1} = h^{\dagger} = (\eta^{-1})^{\dagger} H^{\dagger} \eta^{\dagger} \iff H^{\dagger} \rho = \rho H \text{ with } \rho = \eta^{\dagger} \eta$$

Some  $B_{\ell}$ -models correspond to complex rotations

$$\begin{pmatrix} \tilde{z}_i \\ \tilde{z}_j \end{pmatrix} = R_{ij} \begin{pmatrix} z_i \\ z_j \end{pmatrix} = \eta_{ij} \begin{pmatrix} z_i \\ z_j \end{pmatrix} \eta_{ij}^{-1}, \qquad \text{for } z \in \{x, p\}, \, \eta_{ij} = e^{\varepsilon(x_i p_j - x_j p_i)}$$

For instance for

$$heta_{arepsilon}^{\star} = \left(egin{array}{ccc} R & & & & & & \\ & R & & & & & \\ & & R & & & \\ & & 0 & & \ddots & \\ & & & & 1 \end{array}
ight) \qquad ext{with } R = \left(egin{array}{ccc} \cosh arepsilon & i \sinh arepsilon \\ -i \sinh arepsilon & \cosh arepsilon \end{array}
ight)$$

we have

$$\mathcal{H}_0(p, x) = \eta \mathcal{H}_{\varepsilon}(p, x) \eta^{-1}$$

$$\eta = \eta_{12}^{-1} \eta_{34}^{-1} \eta_{56}^{-1} \dots \eta_{(\ell-2)(\ell-1)}^{-1}$$

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Hermitian isospectral counterparts and metric

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For instance for:

$$\theta_{\varepsilon}^{\star} = \begin{pmatrix} R & & & & \\ & R & & 0 & & \\ & & R & & & \\ & 0 & & \ddots & & \\ & & & 1 \end{pmatrix} \quad \text{with } R = \begin{pmatrix} \cosh \varepsilon & i \sinh \varepsilon \\ -i \sinh \varepsilon & \cosh \varepsilon \end{pmatrix}$$

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Hermitian isospectral counterparts and metric

For B<sub>5</sub>

$$heta_{arepsilon}^{\star} = \left( egin{array}{ccccc} r_0 & -i artheta & i artheta & 1 - r_0 & 0 \ i artheta & r_0 & 1 - r_0 & -i artheta & 0 \ -i artheta & 1 - r_0 & r_0 & i artheta & 0 \ 1 - r_0 & i artheta & -i artheta & r_0 & 0 \ 0 & 0 & 0 & 0 & 1 \end{array} 
ight).$$

we find

$$\tilde{\mathbf{x}} = \theta_{\varepsilon}^{\star} \mathbf{x} = R_{24}^{-1} R_{13} R_{34} R_{12}^{-1} \mathbf{x} = \eta \mathbf{x} \eta^{-1}, \qquad \text{with } \eta = \eta_{24}^{-1} \eta_{13} \eta_{34} \eta_{12}^{-1}.$$

In general this is an open problem.

#### Deformed CMS models have interesting new properties

- less singular ⇒ new energy spectral
- configuration space is not separated ⇒ exchange factors

- construction based on different assumptions
- solve generic case
- proof of identities involved
- generic h, Dyson map  $\eta$  and metric  $\rho$
- different types of models, e.g. Toda [A.F.,M. Smith arXiv:1108.1719]

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Thank you for your attention