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Noncommutative quantum mechanics in a time-dependent background

Andreas Fring

14th International Workshop on Pseudo-Hermitian Hamiltonians
University of Ferhat Abbas (Setif, Algeria), 5-10/09/2014



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based on: [Sanjib Dey and Andreas Fring; arXiv:1407.4843](#)

Content

- Introduction to noncommutative spaces
- The 2D harmonic oscillator in a time-dependent background
- The Ermakov-Pinney equation
- The generalized uncertainty relations
- Conclusions and outlook

Noncommutative spaces

- Flat (abelian) noncommutative space:

$$[x^\mu, x^\nu] = i\theta^{\mu\nu}$$

In 3D:

$$\begin{aligned} [x_0, y_0] &= i\theta_1, & [x_0, z_0] &= i\theta_2, & [y_0, z_0] &= i\theta_3, & \theta_1, \theta_2, \theta_3 &\in \mathbb{R} \\ [x_0, p_{x_0}] &= i\hbar, & [y_0, p_{y_0}] &= i\hbar, & [z_0, p_{z_0}] &= i\hbar, & & \end{aligned}$$

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- Snyder spaces, from twists:

$$[x_i, x_j] = i\theta(x_i p_j - x_j p_i)$$

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- Snyder spaces, from twists:

$$[x_i, x_j] = i\theta(x_i p_j - x_j p_i)$$

- Minimal length spaces, from q-deformed algebras:

$$[x_i, x_j] \approx i\theta(x_j)^2$$

Minimal lengths, areas and volumes

Uncertainty relation:

$$\Delta A \Delta B \geq \frac{1}{2} \left| \langle [A, B] \rangle_\rho \right|$$

- Standard case:

$[A, B] = \text{const}$; give up knowledge about $B \Rightarrow \Delta A = 0$

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 $[A, B] \approx B^2$; even give up knowledge about $B \Rightarrow \Delta A \neq 0$

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$[A, B] \approx B^2$; even give up knowledge about $B \Rightarrow \Delta A \neq 0$

- For instance:

$$[X, P] = i\hbar (1 + \tau P^2)$$

\Rightarrow minimal length

$$\Delta X_{\min} = \hbar \sqrt{\tau} \sqrt{1 + \tau \langle P^2 \rangle_\rho}$$

from minimizing with $(\Delta A)^2 = \langle A^2 \rangle - \langle A \rangle^2$

\mathcal{PT} -symmetric noncommutative spaces

P. Giri, P. Roy, Eur. Phys. C60 (2009) 157: \nexists \mathcal{PT} -symmetry

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- Useful to reduce number of free parameters.

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- Useful to reduce number of free parameters.
- Models on these spaces will have the usual nice properties.

A particular \mathcal{PT}_{\pm} -symmetric solution

from q-deformed oscillator algebra

[S. Dey, A. Fring, L. Gouba, J. Phys. A45 (2012) 385302]

$$[X, Y] = i\theta_1 + i \frac{q^2 - 1}{q^2 + 1} \frac{\theta_1}{\hbar} \left[\frac{m\omega}{2\kappa_6^2} Y^2 + \frac{2\kappa_6^2}{m\omega} P_y^2 \right]$$

$$[Y, Z] = i\theta_3 + i \frac{q^2 - 1}{q^2 + 1} \frac{\theta_3}{\hbar} \left[\frac{m\omega}{2\kappa_6^2} Y^2 + \frac{2\kappa_6^2}{m\omega} P_y^2 \right]$$

$$[X, P_x] = i\hbar + i \frac{q^2 - 1}{q^2 + 1} 2m\omega \left[\kappa_{11}^2 X^2 + \frac{P_x^2/4}{m^2\omega^2\kappa_{11}^2} + \frac{\theta_1^2\kappa_{11}^2 P_y^2}{\hbar^2} + \frac{\theta_1\kappa_{11}^2 X P_y}{\hbar/2} \right]$$

$$[Y, P_y] = i\hbar + i \frac{q^2 - 1}{q^2 + 1} 2m\omega \left[\frac{1}{4\kappa_6^2} Y^2 + \frac{\kappa_6^2}{m^2\omega^2} P_y^2 \right]$$

$$[Z, P_z] = i\hbar + i \frac{q^2 - 1}{q^2 + 1} 2m\omega \left[\frac{Z^2}{4\kappa_7^2} + \frac{\kappa_7^2}{m^2\omega^2} P_z^2 + \frac{\theta_3^2}{4\hbar^2\kappa_7^2} P_y^2 - \frac{\theta_3 Z P_y}{2\hbar^2\kappa_7^2} \right]$$

- Reduced three dimensional solution for $q \rightarrow 1$

$$[X, Y] = i\theta_1 (1 + \hat{\tau} Y^2), \quad [Y, Z] = i\theta_3 (1 + \hat{\tau} Y^2),$$

$$[X, P_x] = i\hbar (1 + \check{\tau} P_x^2), \quad [Y, P_y] = i\hbar (1 + \hat{\tau} Y^2)$$

$$[Z, P_z] = i\hbar (1 + \check{\tau} P_z^2)$$

where $\hat{\tau} = \tau m\omega/\hbar$, $\check{\tau} = \tau/(m\omega\hbar)$

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 \end{aligned}$$

where $\hat{\tau} = \tau m\omega/\hbar$, $\check{\tau} = \tau/(m\omega\hbar)$

- Representation in flat noncommutative space:

$$\begin{aligned}
 X &= (1 + \check{\tau} p_{x_0}^2) x_0 + \frac{\theta_1}{\hbar} (\check{\tau} p_{x_0}^2 - \hat{\tau} y_0^2) p_{y_0}, & P_x &= p_{x_0}, \\
 Z &= (1 + \check{\tau} p_{z_0}^2) z_0 + \frac{\theta_3}{\hbar} (\hat{\tau} y_0^2 - \check{\tau} p_{z_0}^2) p_{y_0}, & P_z &= p_{z_0}, \\
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 \end{aligned}$$

- Bopp-shift to standard canonical variables:

$$\begin{aligned}
 x_0 &\rightarrow x_s - \frac{\theta_1}{\hbar} p_{y_s}, & y_0 &\rightarrow y_s, & z_0 &\rightarrow z_s + \frac{\theta_3}{\hbar} p_{y_s}, \\
 p_{x_0} &\rightarrow p_{x_s}, & p_{y_0} &\rightarrow p_{y_s}, & p_{z_0} &\rightarrow p_{z_s}
 \end{aligned}$$

• Dyson map: $\eta = \eta_{y_0} \eta_{p_{x_0}} \eta_{p_{z_0}}$

$$\eta_{y_0} = (1 + \hat{\tau} y_0^2)^{-1/2}, \quad \eta_{p_{x_0}} = (1 + \check{\tau} p_{x_0}^2)^{-1/2}, \quad \eta_{p_{z_0}} = (1 + \check{\tau} p_{z_0}^2)^{-1/2}$$

• Hermitian variables:

$$x := \eta X \eta^{-1} = \eta_{p_{x_0}}^{-1} \left(x_0 + \frac{\theta_1}{\hbar} \right) \eta_{p_{x_0}}^{-1} - \frac{\theta_1}{\hbar} \eta_{y_0}^{-1} p_{y_0} \eta_{y_0}^{-1} = x^\dagger$$

$$y := \eta Y \eta^{-1} = y_0 = y^\dagger$$

$$z := \eta Z \eta^{-1} = \eta_{p_{z_0}}^{-1} \left(z_0 - \frac{\theta_3}{\hbar} \right) \eta_{p_{z_0}}^{-1} + \frac{\theta_3}{\hbar} \eta_{y_0}^{-1} p_{y_0} \eta_{y_0}^{-1} = z^\dagger$$

$$p_x := \eta P_x \eta^{-1} = p_{x_0} = p_x^\dagger$$

$$p_y := \eta P_y \eta^{-1} = \eta_{y_0}^{-1} p_{y_0} \eta_{y_0}^{-1} = p_y^\dagger$$

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$$p_z := \eta P_z \eta^{-1} = p_{z_0} = p_z^\dagger$$

- Isospectral Hermitian counterpart:

$$H(X, Y, Z, P_x, P_y, P_z) \neq H^\dagger(X, Y, Z, P_x, P_y, P_z) \Rightarrow h = \eta H \eta^{-1} = h^\dagger$$

- Metric: $\rho = \eta^2$

Different types of representations (1D)

$$[X, P] = i\hbar (1 + \check{\gamma} P^2)$$

non-Hermitian: $X_{(1)} = (1 + \check{\gamma} p^2)x$, $P_{(1)} = p$

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non-Hermitian: $X_{(4)} = ix(1 + \check{\gamma} p^2)^{1/2}$, $P_{(4)} = -ip(1 + \check{\gamma} p^2)^{-1/2}$

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Hermitian: $X_{(2)} = (1 + \check{\gamma}p^2)^{1/2}x(1 + \check{\gamma}p^2)^{1/2}$, $P_{(2)} = p$

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Hermitian: $X_{(3)} = x$, $P_{(3)} = \frac{1}{\sqrt{\check{\gamma}}} \tan(\sqrt{\check{\gamma}} p)$

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Hermitian: $X_{(3)} = x$, $P_{(3)} = \frac{1}{\sqrt{\check{\gamma}}} \tan(\sqrt{\check{\gamma}}p)$

The physics is the same for all representations

$$\begin{aligned} & \langle \psi_{(i)} | F(P_{(i)}, X_{(i)}) \psi_{(i)} \rangle_{\rho_{(i)}} \\ &= \frac{1}{N} \int_{-1}^1 F \left[\frac{z}{\sqrt{\check{\gamma}(1-z^2)}}, i\hbar \sqrt{\check{\gamma}(1-z^2)} \partial_z \right] |P_{m-\mu_-}^{\mu_-}(z)|^2 dz \end{aligned}$$

[S. Dey, A. Fring, B. Khantoul, J. Phys. A46 (2013) 335304]

Time-dependent noncommutativity (2D)

$$[X, Y] = i\theta(t)$$

$$[P_x, P_y] = i\Omega(t),$$

$$[X, P_x] = i\hbar + i\frac{\theta(t)\Omega(t)}{4\hbar}$$

$$[Y, P_y] = i\hbar + i\frac{\theta(t)\Omega(t)}{4\hbar}$$

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⇒ time-dependent Hamiltonians $H(X, Y, P_x, P_y) \rightarrow H(t)$.

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$$[Y, P_y] = i\hbar + i\frac{\theta(t)\Omega(t)}{4\hbar}$$

\Rightarrow time-dependent Hamiltonians $H(X, Y, P_x, P_y) \rightarrow H(t)$.

Representation:

$$X = x - \frac{\theta(t)}{2\hbar} p_y, \quad Y = y + \frac{\theta(t)}{2\hbar} p_x,$$

$$P_x = p_x + \frac{\Omega(t)}{2\hbar} y, \quad P_y = p_y - \frac{\Omega(t)}{2\hbar} x.$$

with nonvanishing commutators $[x, p_x] = [y, p_y] = i\hbar$

Lewis-Riesenfeld theory of invariants

Aim: solve time-dependent Schrödinger equation

$$i\hbar\partial_t |\psi_n\rangle = H(t) |\psi_n\rangle$$

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Aim: solve time-dependent Schrödinger equation

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Step 1: Construct Hermitian time-dependent invariant $I(t)$

$$\frac{dI(t)}{dt} = \partial_t I(t) + \frac{1}{i\hbar} [I(t), H(t)] = 0.$$

Lewis-Riesenfeld theory of invariants

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[H. Lewis, W. Riesenfeld, J. Math. Phys. 10, 1458 (1969)]

Example: The 2D harmonic oscillator

$$H(X, Y, P_x, P_y) = \frac{1}{2m} (P_x^2 + P_y^2) + \frac{m\omega^2}{2} (X^2 + Y^2),$$

Using the above representation

$$\begin{aligned} H(t) &= \frac{1}{2}a(t) (p_x^2 + p_y^2) + \frac{1}{2}b(t) (x^2 + y^2) + c(t) (p_x y - x p_y) \\ &= \frac{1}{2}a(t) \left(p_r^2 + \frac{p_\theta^2}{r^2} - \frac{\hbar^2}{4r^2} \right) + \frac{1}{2}b(t)r^2 - c(t)p_\theta \end{aligned}$$

with coefficients

$$a(t) = \frac{1}{m} + \frac{m\omega^2}{4\hbar^2}\theta^2(t), \quad b(t) = m\omega^2 + \frac{\Omega^2(t)}{4m\hbar^2}, \quad c(t) = \frac{m\omega^2\theta(t)}{2\hbar} + \frac{\Omega(t)}{2\hbar m}$$

Step 1 in LR-theory

The Ansatz:

$$I(t) = \alpha(t)p_r^2 + \beta(t)r^2 + \gamma(t)\{r, p_r\} + \delta(t)\frac{p_\theta^2}{r^2} + \varepsilon(t)\frac{p_\theta}{r^2} + \phi(t)\frac{1}{r^2}$$

leads to the set of coupled differential equations

$$\dot{\alpha} = -2a\gamma, \quad \dot{\beta} = 2b\gamma, \quad \dot{\gamma} = b\alpha - a\beta$$

$$\dot{\delta}p_\theta^2 + \dot{\varepsilon}p_\theta + \dot{\phi} = \hbar^2 a\gamma - 2a\gamma p_\theta^2, \quad (\delta - \alpha)p_\theta^2 + \varepsilon p_\theta + \phi + \frac{\alpha\hbar^2}{4} = 0$$

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which are solved by

$$I(t) = \frac{\tau}{\sigma^2}r^2 + \left(\sigma p_r - \frac{\dot{\sigma}}{a}r\right)^2 + \frac{\sigma^2 p_\theta^2}{r^2} - \frac{\sigma^2 \hbar^2}{4r^2}$$

$\tau = const$, $\sigma(t)$ solves the Ermakov-Pinney equation

$$\ddot{\sigma} - \frac{\dot{\sigma}}{a}\dot{\sigma} + ab\sigma = \tau \frac{a^2}{\sigma^3}$$

Step 2 in LR-theory

Rewrite $I(t)$ in terms of time-dependent creation and annihilation operators

$$\hbar \left(\hat{a}^\dagger \hat{a} + \frac{1}{2} \right) - p_\theta = \frac{1}{4} I(t) - \frac{1}{2} p_\theta =: \hat{I}(t)$$

$$\hat{a}(t) = \frac{1}{2\sqrt{\hbar}} \left[\left(\sigma p_r - \frac{\dot{\sigma}}{a} r \right) - i \left(\frac{r}{\sigma} + \frac{\sigma}{r} \left(p_\theta + \frac{\hbar}{2} \right) \right) \right] e^{-i\theta}$$

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From standard arguments:

$$\psi_{n,m-n} = \lambda_n \frac{(i\hbar^{1/2}\sigma)^m}{\sqrt{m!}} r^{n-m} e^{i\theta(m-n) - \frac{a-i\sigma\dot{\sigma}}{2a\hbar\sigma^2} r^2} U \left(-m, 1 - m + n, \frac{r^2}{\hbar\sigma^2} \right)$$

with normalization constant

$$\lambda_n^2 = \frac{1}{\pi n! (\hbar\sigma^2)^{(1+n)}}$$

Step 3 in LR-theory

We fix the phase by solving:

$$\dot{\alpha}_{n,\ell} = \frac{1}{\hbar} \langle n, \ell | i\hbar\partial_t - H | n, \ell \rangle$$

to

$$\alpha_{n,\ell}(t) = (n + \ell) \int^t \left(c(s) - \frac{a(s)}{\sigma^2(s)} \right) ds$$

The Ermakov-Pinney equation

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$$\sigma = \sqrt{u_1^2 + \tau a^2 \frac{u_2^2}{W^2}},$$

where u_1, u_2 solve $\ddot{u} + ab(t)u = 0$ and $W = u_1\dot{u}_2 - \dot{u}_1u_2$
[E. Pinney, Proc. Amer. Math. Soc. 1, 681(1) (1950)]

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For instance for $a(t) = \alpha$ and $b(t) = \beta e^{\gamma t}$, $\alpha, \beta, \gamma \in \mathbb{R}$

$$\sigma(t) = \sqrt{\frac{\pi^2 \alpha^2 \tau}{\gamma^2 c_1^2} Y_0^2 \left(\frac{2\sqrt{\alpha\beta} e^{\gamma t/2}}{\gamma} \right) + c_1^2 J_0^2 \left(\frac{2\sqrt{\alpha\beta} e^{\gamma t/2}}{\gamma} \right)},$$

with J_0, Y_0 Bessel functions of first and second kind.

- When $\dot{a} \neq 0$ no general solution is known.
Special solution:

$$\frac{1}{\lambda_k} \int^{\sigma} \frac{\dot{a}s^3}{\tau a^3 - a^2 b s^4} ds = t \quad \lambda_{\kappa}^{\pm} = \frac{-1 \pm \sqrt{1 - 4\kappa}}{2\kappa}$$

when Chiellini integrability condition holds

$$\frac{d}{d\sigma} \left(\frac{\dot{a}s^3}{\tau a^3 - a^2 b s^4} \right) = -\kappa \frac{\dot{a}}{a} \quad \kappa \in \mathbb{R}$$

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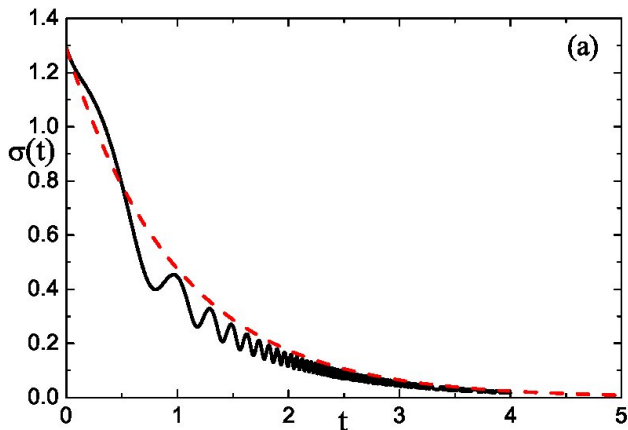
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- \Rightarrow Does not allow to pre-select $\Theta(t)$ and $\Omega(t)$.
- \Rightarrow Resort to numerical solutions.

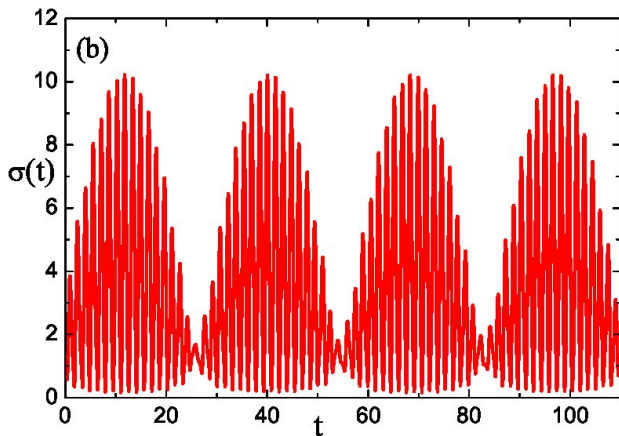
Sample solutions:



(a) Exactly integrable solution (red, dashed) versus a non-Chiellini integrable solution for pre-selected exponential backgrounds $\theta(t) = \alpha e^{-\gamma t}$ and $\Omega(t) = \beta e^{\gamma t}$ (black, solid).

$\alpha = 5$, $\beta = 2$, $\gamma = 2$, $m = \hbar = \tau = \omega = 1$, $\kappa = 1/4$, $\mu = \sqrt{5/3}$

Sample solutions:



(b) Non-Chiellini integrable solution for pre-selected sinusoidal background $\theta(t) = \alpha \sin(\gamma t)$ and $\Omega(t) = \beta \sin(\gamma t/2)$.

$\alpha = 5$, $\beta = 2$, $\gamma = 2$, $m = \hbar = \tau = \omega = 1$, $\kappa = 1/4$, $\mu = \sqrt{5/3}$

Generalized uncertainty relations

In general we have:

$$\Delta A \Delta B|_{\psi} \geq \frac{1}{2} |\langle \psi | [A, B] | \psi \rangle|$$

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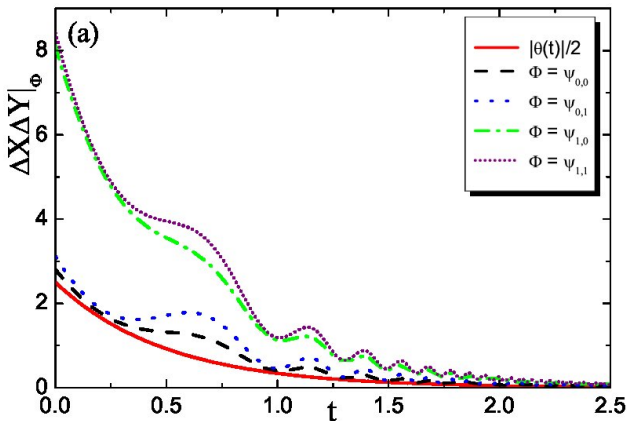
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$$\begin{aligned} \Delta P_x \Delta P_y |_{\psi_{n,m-n}} &= \frac{n-m}{2} \Omega(t) + \frac{\hbar}{2} (n+m+1) \left[\frac{\sigma^2 \Omega^2(t)}{4} + \left(\frac{1}{\sigma^2} + \frac{\dot{\sigma}^2}{a^2} \right) \right] \\ &\geq \frac{\Omega(t)}{2} \end{aligned}$$

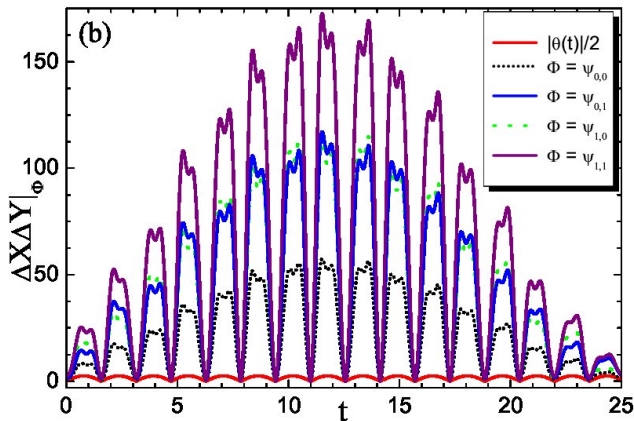
$$\Delta X \Delta P_x |_{\psi_{n,m-n}} = \Delta Y \Delta P_y |_{\psi_{n,m-n}} \geq \frac{\hbar}{2} + \frac{\theta(t)\Omega(t)}{8\hbar}$$

Examples:



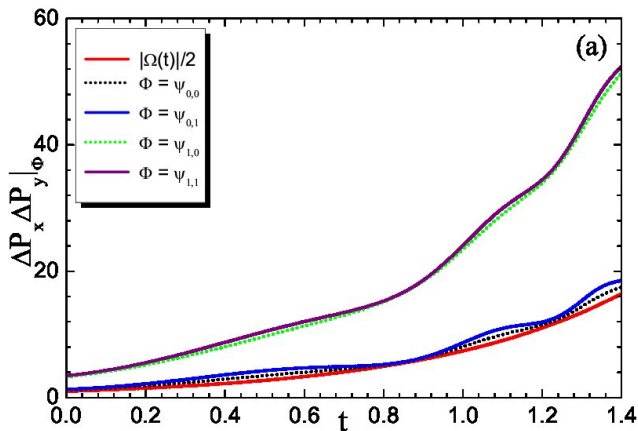
(a) for background fields $\theta(t) = \alpha e^{-\gamma t}$ and $\Omega(t) = \beta e^{\gamma t}$
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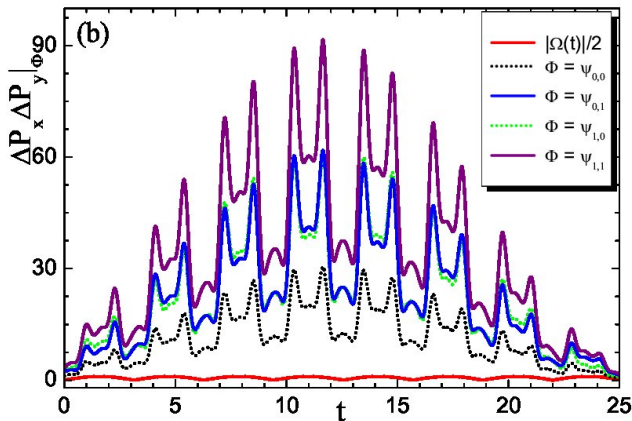
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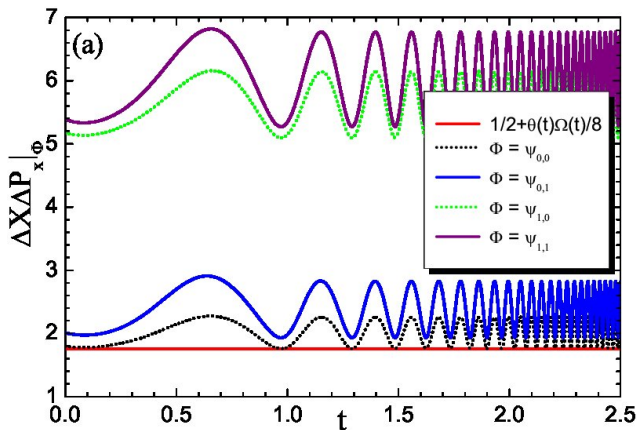
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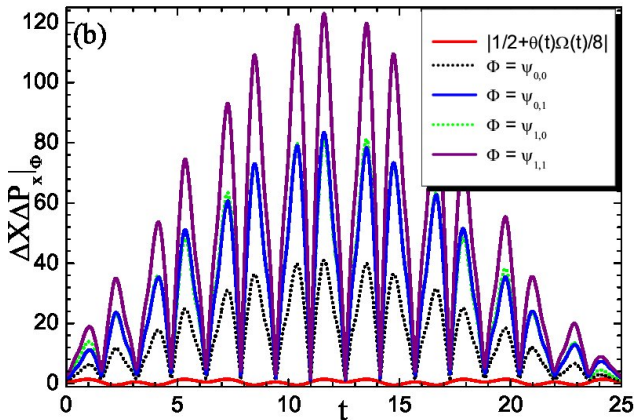
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GUR for coherent states

Glauber coherent states

$$|\alpha, t\rangle := D(\alpha, t) |0, 0\rangle, \quad \text{with } D(\alpha, t) := e^{\alpha \hat{a}^\dagger(t) - \alpha^* \hat{a}(t)}$$

yield

$$\Delta X|_{|\alpha, t\rangle}^2 = \Delta Y|_{|\alpha, t\rangle}^2 = \Delta X|_{|\psi_{0,0}\rangle}^2 \quad \Delta P_x|_{|\alpha, t\rangle}^2 = \Delta P_y|_{|\alpha, t\rangle}^2 = \Delta P_x|_{|\psi_{0,0}\rangle}^2$$

Squeezed coherent states

$$|\alpha, \beta, t\rangle := S(\beta, t) D(\alpha, t) |0, 0\rangle, \quad \text{with } S(\beta, t) := e^{\frac{\beta}{2} [\hat{a}^2(t) - \hat{a}^{\dagger 2}(t)]}$$

yield for instance

$$\Delta X|_{|\alpha, \beta, t\rangle}^2 = \frac{\hbar}{2} \left[\sigma^2 e^\beta + \frac{\theta^2(t)}{4\hbar^2} \left(\frac{1}{\sigma^2} e^\beta + \frac{\dot{\sigma}^2}{a^2} e^{-\beta} \right) \right] \cosh \beta + \frac{\theta(t)}{4} (1 - e^{2\beta})$$

Use β to minimise uncertainties:

- Possible for generic t for $\Delta x \Delta p_x |_{\alpha, \beta, t}$:

$$\beta(t) = \beta_{\min}(t) = 1/2 \ln \left[\left(a \sqrt{a^2 + 8\sigma^2 \dot{\sigma}^2} - a^2 \right) / (4\sigma^2 \dot{\sigma}^2) \right]$$

such that $\Delta x \Delta p_x |_{\alpha, \beta_{\min}, t} < \Delta x \Delta p_x |_{\alpha, t}$

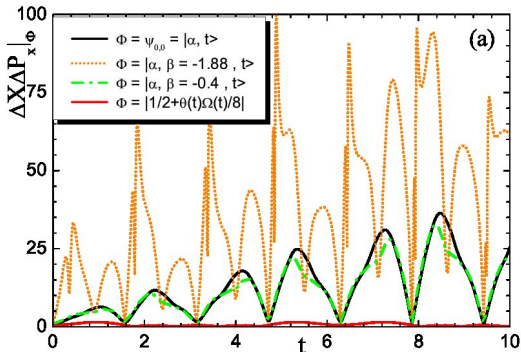
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- Possible for specific t for $\Delta X \Delta P_x |_{|\alpha, \beta, t\rangle}$, e.g. $t = 4$:

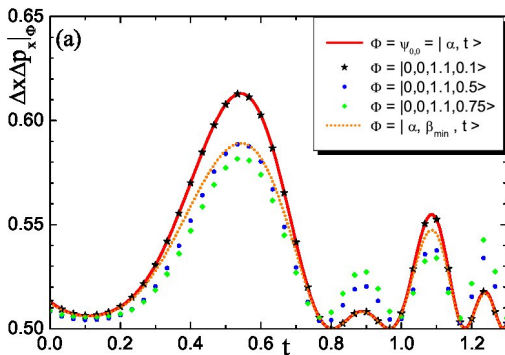


for background fields $\theta(t) = \alpha \sin(\gamma t)$, $\Omega(t) = \beta \sin(\gamma t/2)$

Glauber versus Gaussian Klauder coherent states

$$|n, m_0, \phi_0, s\rangle := \frac{1}{\sqrt{N(m_0)}} \sum_{m=0}^{\infty} \exp\left[-\frac{(m - m_0)^2}{4s^2}\right] e^{im\phi_0} |n, m - n\rangle$$

Quality depends on background fields:

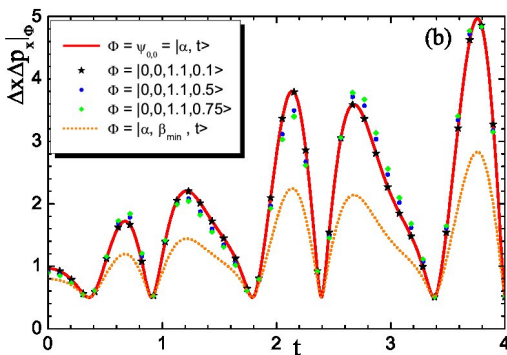


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Thank you for your attention