

Programming in C++

Session 9 – A generic class with dynamic allocation
Declarations and definitions
Program structure

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(slides originally produced by Dr Ross Paterson)



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This session

Two parts:

- 1 Completing memory management: a generic class with dynamic allocation
- 2 Program structure and separate compilation
 - Revision: declarations and definitions
 - Separate compilation in C++

Part I

Generic Class with Dynamic Allocation

Writing our own vector class

- An array to hold the elements
- (efficiency) Array often longer than needed for the elements held
- Implement various vector operations
- The array is dynamically allocated, so must free it in a destructor
- Because we have a non-trivial destructor, we also need a copy constructor and an assignment operator **Gang of Three!!!**
- An iterator
- A **swap** method is also useful

A vector class

```
template <typename Elem>
class my_vector {
    size_t vsize; // # of elements stored - "vector size"
    size_t asize; // size of the array - "array size"
    Elem *array;
// INVARIANT: 0 <= vsize <= asize && array.size() == asize
public:
    my_vector() : vsize(0), asize(1),
                array(new Elem[1]) {}

    size_t size() const { return vsize; }

    Elem & operator[](size_t i) { return array[i]; }
};

• array(new Elem[1]) – why not array(nullptr)?
```

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↳ A vector class

```
A vector class
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class my_vector {
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public:
    my_vector() : vsize(0), asize(1),
                array(new Elem[1]) {}

    size_t size() const { return vsize; }
    Elem & operator[](size_t i) { return array[i]; }
};
↳ array(new Elem[1]) – why not array(nullptr)?
```

array(new Elem[1]) – why not array(nullptr)?

Because of the **invariant**!

For the invariant `vsize <= asize` to hold, `array` must be an actual array, otherwise `asize` is not defined. And `array.size()` must be equal to `asize`.

Why not `asize(0)`, `array(new Elem [0])`? Invariant is satisfied.

⇒ Because of the implementation of `push_back` on the next slide. (and because it'd be silly – avoid 0-length arrays)

Shrinking and growing the vector

```
void pop_back() { vsize--; }

void push_back(const Elem & x) {
    if (vsize == asize) {
        asize *= 2; // Why *= 2 instead of ++? [*]
        Elem *new_array = new Elem[asize];
        for (size_t i = 0; i < vsize; ++i)
            new_array[i] = array[i];
        delete[] array;
        array = new_array;
    }
    array[vsize] = x;
    ++vsize;
}
```

[*] try adding 1000 elements into a vector...

Destructor and Copy constructor

This class allocates dynamic memory, so it should reclaim it:

```
virtual ~my_vector() { delete[] array; }
```

Because we have a non-trivial destructor, we also need a copy constructor and assignment operator. **Gang of Three!!!**

```
my_vector(const my_vector<Elem> & other) :
    vsize(other.vsize), asize(other.asize),
    array(new Elem[other.asize]) {
    for (size_t i = 0; i < vsize; ++i)
        array[i] = other.array[i];
}
```

Assignment operator

```
my_vector<Elem> &
operator=(const my_vector<Elem> & other) {
    if (&other != this) {
        vsize = other.vsize;
        if (asize < vsize) { // Reuse if possible!
            delete[] array;
            asize = other.asize;
            array = new Elem[asize];
        }
        for (size_t i = 0; i < vsize; ++i)
            array[i] = other.array[i];
    }
    return *this;
}
```

REUSE!!! Compare with 8-21 & 8-26 !

An iterator

Recall that in C++, an *iterator* is a type that supports ==, ++, * and --. A simple iterator for this type is pointers to elements:

```
typedef Elem *iterator; // I.e., iterator is a
                        // pointer to an Elem
typedef const Elem *const_iterator;

        iterator begin()           {return array;}
        iterator end()             {return array + vsize;}
const_iterator cbegin() const {return array;}
const_iterator cend()   const {return array + vsize;}
}; // end of my_vector class
```

An alternative is to define a class (*), and overload the ++, ==, * and -- operators.

(*) Can be an internal class !

Swap function

*When designing classes we should think how they'll behave with standard algorithms
(so we should know the standard algorithms...)*

The header <utility> defines a general swap function:

```
template <typename T>
void swap(T & x, T & y) {
    T tmp = x; x = y; y = tmp;
}
```

- Works for vectors too (T is my_vector<Elem>)
- But is ***very*** inefficient

Efficient swap function for vectors

Add a member function to the my_vector class:

```
void fast_swap(my_vector<Elem> & other) {
    std::swap(vsize, other.vsize);
    std::swap(asize, other.asize);
    std::swap(array, other.array);
}
```

Define an overloading of swap for vectors outside the class:

```
template <typename T> // "C++ template specialization"
void swap(my_vector<T> & x, my_vector<T> & y) {
    x.fast_swap(y);
}
```

(constraining the parameter type to my_vector<T> means this applies to our class only)

We're done! :-)

Part II

Program Structure — Declarations vs Definitions

Program structure

- In C++, X (class, function, variable) **must be declared before use**
 - Can *declare* X, and ...
 - *Define* it fully later
 - C++ programs can have *millions* of lines
 - Impossible (too slow) to recompile everything all the time
- ⇒ Programs are partitioned into several files for *separate compilation*
- Common declarations and partial class definitions are placed in *header files* (they serve as interfaces)

Declaration before use

C++ designed for *one-pass* compilers: must declare entities before use

```
class A { ... };
```

```
class B { A *p; ... }; // OK
```

Defining these classes in the opposite order is illegal. Problems:

- limits presentation.
- prohibits recursion.

Forward declarations

Solution: *Declare* first, and fully *define* later:

```
class A; // declare A as a type
```

```
class B { // define B  
    A *p; // OK - pointer size is known  
    ...  
};
```

```
class A { B b1; ... }; // fully define A - OK
```

Limitations

However, this is *NOT* allowed:

```
class A;          // declare A

class B {        // define B
    A a;        // don't know the size of A here
    ...
};

class A { ... }; // define A
```

Because the size of a member must be known when it's used

Recursive class definitions

This is allowed:

```
class A;          // declare A

class B {        // define B
    A *p;        // pointer size is known
    ...
};

class A {        // define A
    B b1;        // size of B is known here
    ...
};
```

Part III

Separate Compilation

Separate compilation

General Idea

- Avoid recompiling a huge program after each change
 - Break it into “*modules*”, each with an interface
- Ideally: only recompile modules when the interfaces they use have changed
- If a module implementation (*but not its interface*) is changed, that module must be recompiled, but its clients need not be
- This should be **automated** (e.g., with *make*)

Separate compilation in C++

- Implementations go into source files, usually ending in “.cc”
- Interfaces go into header files, usually ending in “.h”
 - Header files are included in source files and other header files
- **Never** duplicate declarations (include them instead)
- Recompile decisions are based on inclusion relationships and timestamps on files

(Other suffixes: .cpp, .cxx, .hh, .hpp, .hxx, ...)

Inclusion relationships (as used by **make**) — try:

- `g++ -MM file.cc`
- `g++ -M file.cc`

The compilation process

- Compiling a source file `x.cc` yields an object file `x.o` (like a `.java` file yields a `.class` file)
- `x.cc` must be recompiled if it (or any of the header files it uses) has changed more recently than `x.o` (so don't include header files unnecessarily)
- Object files are linked together to make an executable program (like an executable `.jar` file)
- Re-compiling source files means the program must be re-linked
- In Unix, this is all managed by the **make** command

A Makefile

```
# COMMANDS (e.g., rm) MUST START WITH A TAB CHARACTER!!!
DIR=.
# CXX=g++-13 # or CXX=g++
CXXFLAGS=-I$(DIR) -x c++ -g -std=c++23 -pedantic -Wall -Wpointer-arith \
-Wwrite-strings -Wcast-qual -Wcast-align -Wformat-security \
-Wformat-nonliteral -Wmissing-format-attribute -Winline -funsigned-char
LDLDFLAGS=-L$(DIR) -lc -lstdc++ # Linking flags
CC=$(CXX) # Use the C++ compiler as the C compiler
# (ensures linking is done according to C++)
CFLAGS=$(CXXFLAGS) # C flags are now C++ flags

all:    cwk cwk.t

clean:
    -rm *.o cwk cwk.t *~ 2> /dev/null

cwk:    sample.o Makefile libcity.a
        $(CXX) sample.o -o cwk $(LDLDFLAGS)

cwk.t:  cwk.t.o Makefile libcityt.a
        $(CXX) cwk.t.o -o cwk.t $(LDLDFLAGS)t

...
```

Include directives

- **#include** includes the text of another file at that point.
- To include a file from the **system** directories:

```
#include <vector>
#include <iostream>
```
- To include a file from the **local** directories (`-I dir1 -I dir2`):

```
#include "point.h"
```
- `g++`: You can see what the result is with `-E` (`-E` runs only the C preprocessor on your file, doesn't compile) (and `-c` runs only the C compiler, doesn't link)
- Any file can be included, but the following rules are recommended

Header files

These approximate interfaces, and may contain:

```
comments           // what the class does
include directives  #include "xyz.h"
class definitions   class A { ... };
class declarations class B;
constant definitions  const double pi = 3.14159;
type definitions    typedef double real;
function declarations int sqr(int x);
```

They should not contain code, except inline function definitions.

BE CAREFUL!

NEVER IN HEADER FILES!

```
global variable definition  int counter = 0;
function definition         int foo() { return 3; }
```

INSTEAD YOU SHOULD

```
DECLARE global variables  extern int counter;
INLINE function definitions inline int foo() { return 3; }

Or DECLARE functions    int foo();
```

Otherwise, global variables/functions are defined multiple times from each source file that includes the header file **& linker complains!**

The header file `point.h`, first version

```
class point {
protected:
    int _x, _y;
public:
    point(int x, int y);
    int x() const;
    int y() const;
    void move(int dx, int dy);
};
```

Often, a header file and source file correspond to a single class, but there are many other possibilities.

The implementation `point.cc`

```
#include "point.h"

point::point(int x, int y) : _x(x), _y(y) {}

int point::x() const { return _x; }
int point::y() const { return _y; }

void point::move(int dx, int dy) {
    _x += dx; _y += dy;
}
```

This is why we're so interested in defining methods **outside** a class!

Separate compilation and templates?

NO

isocpp.org/wiki/faq/templates#templates-defn-vs-decl

- C++ DOES NOT support separate compilation of template code
- Generic method definitions must be included in the header file *WITH* the template class definition

Wat Do?

Generic code separation

```
// File: pointt.h
template <typename T>
class pointt {
    pointt(T _x, T _y);
};
#include "pointt.cc" // <---- includes .cc !!!
// *End* of file pointt.h

// File: pointt.cc
// *NOT* including pointt.h! <---- !!!
// Definitions for pointt
template <typename T>
pointt<T>::pointt(T _x, T _y) {
    ...
}
```

Code separation: Normal vs Generic

```
// point.h NORMAL
class point {
    point(int _x, int _y);
};
// *End* of file point.h

// File point.cc
#include "point.h"
// Definitions for pointt
point::point(int _x, int _y){
    ...
}

// pointt.h GENERIC
template <typename T>
class pointt {
    pointt(T _x, T _y);
};
#include "pointt.cc" // !!!
// *End* of file pointt.h

// File pointt.cc
// *NOT* including pointt.h!!!
// Definitions for pointt
template <typename T>
pointt<T>::pointt(T _x, T _y){
    ...
}
```

Repeated inclusion

- Suppose `point.h` is included by both `line.h` and `polygon.h`
Some drawing program might begin:

```
#include "line.h"
#include "polygon.h"
```
- This includes `point.h` twice, causing the compiler to complain about a repeated definition of `point`
- Seems reasonable to expect the language to take care of this, BUT
 - C++ doesn't care about reasonable
 - We must add *include guards* to our header files

The header file `point.h` with an include guard

```
#ifndef POINT_H
#define POINT_H

class point {
protected:
    int _x, _y;
public:
    point(int x, int y);
    int x() const;
    int y() const;
    void move(int dx, int dy);
};

#endif
```

Don't use bloody `#pragma`'s! (non-standard/portable)

Typical structure

- For each class `Foo`, two source files:
 - `Foo.h` containing the class definition, but including only very small methods. This is the place for comments describing the interface of the class.
 - `Foo.cc` containing the method definitions for the class (unless the class is very simple). This should always include `Foo.h`.
- Include header files only if necessary:
 - `Bar.h` should **ONLY** include `Foo.h`, when `Foo` is needed for defining class `Bar`
 - But when class `Foo` is only needed for defining methods of `Bar`, then include `Foo.h` only in `Bar.cc`
- Never **use** namespaces inside header files (**namespace pollution**)
Instead use full names: `std::string`, `std::ostream`, etc.
Exercise: break up `date.cc` in this way.

Summary

- In C++, things must be **declared** before use
- Often, a partial declaration (interface) will suffice (but the compiler needs to know how big things are)
- Large programs are broken up into several source files ⇒ **separate compilation**
- **Common declarations** are placed in **header files**, to be included by several source files
- Shared generic code must also be placed in header files

Learn how to use **make**

<https://www.gnu.org/software/make/manual/>

Next Session

- Exceptions in C++.
- **RAII** — *Resource Acquisition Is Initialization*: a C++ technique ensuring that resources are freed, even in the presence of exceptions, without writing lots of exception-handling code (*Java's try-with-resources on steroids*)
- Reading: Stroustrup 14.4.
- RAII is a special case of the *smart pointer* and *proxy* patterns.

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Next Session

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- RAII – Resource Acquisition & Initialization – a C++ technique ensuring that resources are freed, even in the presence of exceptions, without writing lots of exception handling code (also known as RAII)
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Final Notes – I

- Why not initialize member `array` in `my_vector`'s default constructor with `nullptr`? (slide 5)
Because then we'd be violating the class **invariant**:
`vsize <= asize`
If `array` is not pointing to an array, then `asize` isn't defined.
- `my_vector`'s assignment operator (slide 8) shows that sometimes we can reuse resources instead of always destroying the ones we've got and copying those of the other object.

- Note the parameter type of the copy constructor and the assignment operator (and the operator's return type):

```
template <typename Elem>
class my_vector {
public:
    my_vector( const my_vector<Elem> & o );
    my_vector<Elem> &
    operator=( const my_vector<Elem> & o );
    ...
};
```

The type is a generic one, as the class is generic; type `my_vector` does not exist, only `my_vector<Elem>` exists!!!

- Outside the class:

```
template <typename Elem>
my_vector<Elem>:: my_vector( const my_vector<Elem> & o )
: ... {
    ...
}

template <typename Elem>
my_vector<Elem> &
my_vector<Elem>:: operator=( const my_vector<Elem> & o ) {
    ...
}
```

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Final Notes – II

- Implementation of the iterator type for class `my_vector` (slide 9)
- Slide 11 – the `swap` specialised for objects of type `my_vector`, is another example of partial specialization! The type of its arguments is still generic but now we know that it's a `my_vector` of some `T`.
- Things need to be declared (not necessarily defined) before they're used – slides 13–17.
- Separate compilation – CLASS DEFINITIONS with METHOD DECLARATIONS go into the HEADER file `NAME.h`, while the method IMPLEMENTATIONS into the SOURCE file `NAME.cc`. See slides 26–27.

Which file should include which?

- If there's no generic code, then we include `NAME.h` at the top of `NAME.cc` and compile the latter into `NAME.o`
- If there is generic code, then we include `NAME.cc` at the bottom of `NAME.h` (compiler needs to see the implementation of the generic code to be able to instantiate it where it's used) but do not ask the compiler to produce `NAME.o` (pointless – it'll be empty).

ALL other files that need to know the types defined in `NAME.h` include `NAME.h` (NEVER `NAME.cc`).

- To avoid “multiple definition” compiler errors, we surround the entire contents of `NAME.h` with include guards (*NOT* pragma's!!!):

```
// File: name.h – WITHOUT generic code
#ifndef NAME_H
#define NAME_H
...
#endif
```

This ensures that the compiler will see the contents only the first time `NAME.h` is included (when `NAME_H` hasn't been defined).

```
// File: name.cc – WITHOUT generic code
// Get declarations
#include "name.h"
...
```

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Final Notes – III

- Things change a bit with generic code:

```
// File: name.h – WITH generic code
#ifndef NAME_H
#define NAME_H
...
// Compiler needs to see the implementation
// of the generic code.
#include "name.cc"
#endif
```

and the source file:

```
// File: name.cc – WITH generic code
// No include of "name.h"!
...
```

Afterwards `NAME_H` will get defined, so the contents between the `#ifndef` and the `#endif` will not be considered again.

- Separate compilation is automated with the `make` tool. On the terminal type: `info make`
Or read the GNU documentation of `make` on-line:

<https://www.gnu.org/software/make/manual/>

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Final Notes – IV

- The C preprocessor (`cpp`) can do quite a lot of things (e.g., give you a headache... – advanced, not to be examined):
 - en.wikibooks.org/wiki/C_Programming/Preprocessor
- X-Macros (for meta-programming with macros):
 - en.wikibooks.org/wiki/C_Programming/Preprocessor#X-Macros
 - www.embedded.com/design/programming-languages-and-tools/4403953/C-language-coding-errors-with-X-macros-Part-1#
 - www.embedded.com/design/programming-languages-and-tools/4405283/Reduce-C--language-coding-errors-with-X-macros---Part-2#
 - www.embedded.com/design/programming-languages-and-tools/4408127/Reduce-C-language-coding-errors-with-X-macros--Part-3#
- Hello headache! (No, I don't understand these either... but that doesn't mean that you cannot use them!)
- *Outta This World!!!*
 - <https://github.com/pfultz2/Cloak/wiki/C-Preprocessor-tricks,-tips,-and-idioms>