## Solutions to $\underline{\dot{x}} = A\underline{x}$

Let  $\lambda_1, \lambda_2$  be the eigenvalues of A with eigenvectors  $\underline{E}_1, \underline{E}_2$ , then

**Type I** If  $\lambda_1 \neq \lambda_2$  and  $\lambda_1, \lambda_2 \in \mathbb{R}$ :

$$A = PJP^{-1}$$
 with  $J = \begin{pmatrix} \lambda_1 & 0\\ 0 & \lambda_2 \end{pmatrix}$  and  $P = (\underline{E}_1, \underline{E}_2)$ 

The solution to  $\underline{\dot{y}} = J\underline{y}$  is  $\underline{y} = C_1 e^{\lambda_1 t} \begin{pmatrix} 1 \\ 0 \end{pmatrix} + C_2 e^{\lambda_2 t} \begin{pmatrix} 0 \\ 1 \end{pmatrix}$ The solution to  $\underline{\dot{x}} = A\underline{x}$  is  $\underline{x} = C_1 e^{\lambda_1 t} \underline{E}_1 + C_2 e^{\lambda_2 t} \underline{E}_2$ 

**Type II** If  $\lambda_1 = \lambda_2$  and  $\lambda_1 \in \mathbb{R}$ :

$$A = PJP^{-1}$$
 with  $J = \begin{pmatrix} \lambda_1 & 1\\ 0 & \lambda_1 \end{pmatrix}$  and  $P = (\underline{E}_1, \underline{J}_1)$ 

$$(A - \lambda_1 I)\underline{J}_1 = \underline{E}_1$$

The solution to  $\underline{\dot{y}} = J\underline{y}$  is  $\underline{y} = (C_1 + C_2 t)e^{\lambda_1 t} \begin{pmatrix} 1\\0 \end{pmatrix} + C_2 e^{\lambda_1 t} \begin{pmatrix} 0\\1 \end{pmatrix}$ The solution to  $\underline{\dot{x}} = A\underline{x}$  is  $\underline{x} = (C_1 + C_2 t)e^{\lambda_1 t}\underline{E}_1 + C_2 e^{\lambda_1 t}\underline{J}_1$ 

**Type III** If  $\lambda_1 = \alpha + i\beta$ ,  $\lambda_2 = \alpha - i\beta$  and  $\alpha, \beta \in \mathbb{R}$  with,  $\beta > 0$ :

$$A = PJP^{-1}$$
 with  $J = \begin{pmatrix} \alpha & \beta \\ -\beta & \alpha \end{pmatrix}$  and  $P = (\underline{e}_1, \underline{e}_2)$ 

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$$\underline{e}_1 = \operatorname{Re}(\underline{E}_1)$$
 and  $\underline{e}_2 = \operatorname{Im}(\underline{E}_1)$ 

The solution to  $\underline{\dot{y}} = J\underline{y}$  is  $\underline{y} = r_0 e^{\alpha t} \cos(-\beta t + \theta_0) \begin{pmatrix} 1 \\ 0 \end{pmatrix} + r_0 e^{\alpha t} \sin(-\beta t + \theta_0) \begin{pmatrix} 0 \\ 1 \end{pmatrix}$ The solution to  $\underline{\dot{x}} = A\underline{x}$  is  $\underline{x} = r_0 e^{\alpha t} \cos(-\beta t + \theta_0)\underline{e}_1 + r_0 e^{\alpha t} \sin(-\beta t + \theta_0)\underline{e}_2$ 

**Type IV** If  $A = \lambda I$ , proportional to the identity, then

The solution to 
$$\underline{\dot{x}} = A\underline{x}$$
 is  $\underline{x} = C_1 e^{\lambda t} \begin{pmatrix} 1 \\ 0 \end{pmatrix} + C_2 e^{\lambda t} \begin{pmatrix} 0 \\ 1 \end{pmatrix}$